

Volumetric cloud reconstruction

and cloud radar sensitivity to liquid cumulus clouds

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Outline

1) M36S cloud radar at our institute

- miraMACS – part of the Munich Aerosol Cloud Scanner
- Modifications and lessons learned

2) 3D cloud reconstruction using miraMACS

- Motivation, scan strategies and interpolation methods
- Sensitivity to scan resolution and scan strategies
- Application to real-world cases

3) Radar sensitivity towards liquid cumulus clouds

- Nominal and measured detection limit
- Coherent and incoherent averaging and decoherence

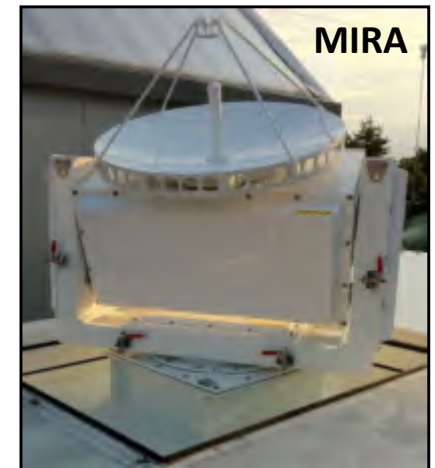
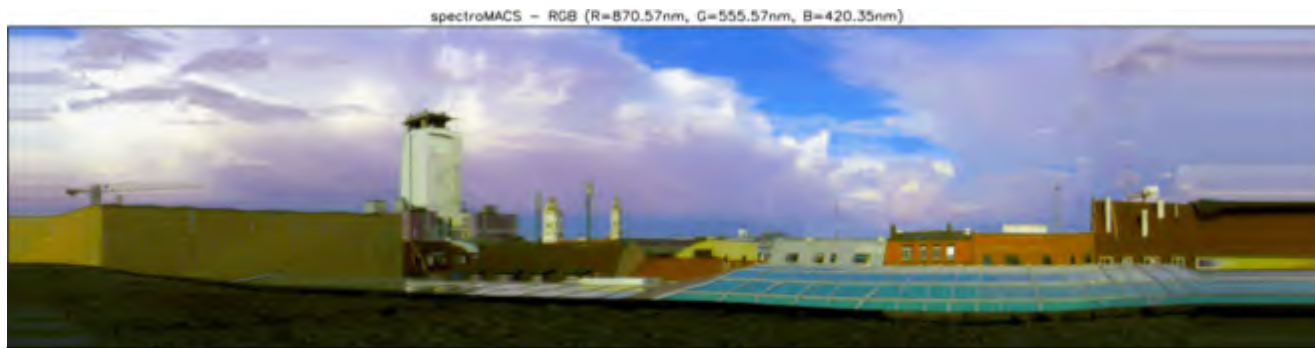
M36S cloud radar at our institute

>> Capturing the 3D structure of single clouds <<

MACS – Munich Aerosol Cloud Scanner

our new measurement platform in a nutshell

- **Task:** Passive and active observations of convective cloud sides
- **Goal:** Retrieval of microphysics in their vertical extent



spectral range	400 - 1000 nm	970 - 2500 nm
spectral resolution	2.8 nm	10 nm
spectral bands	768	256







Beam Webcam

- aligned with beam propagation direction
- weather proof
 - enhanced pointing accuracy
 - continuous documentation





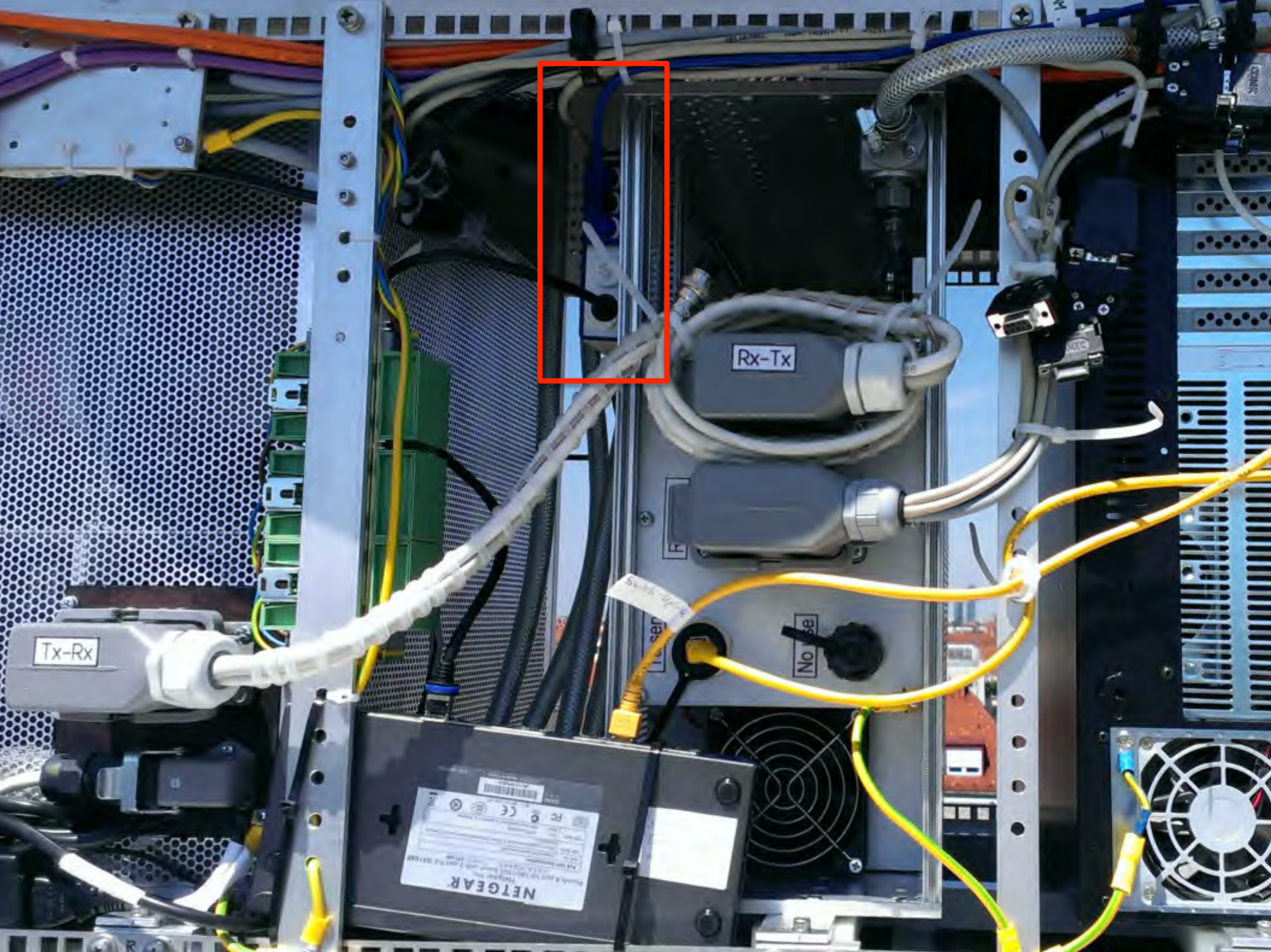
Tx-Rx

Rx-Tx

Pwr. Antenn.

To serv.

No Use



Solid State Disks

acceleration and vibrations during scans
were considerably at the beginning

after several scanning episodes HDDs started
to fail with bad sectors

adjusted the feedback loop and replaced HDDs
with solid state disks

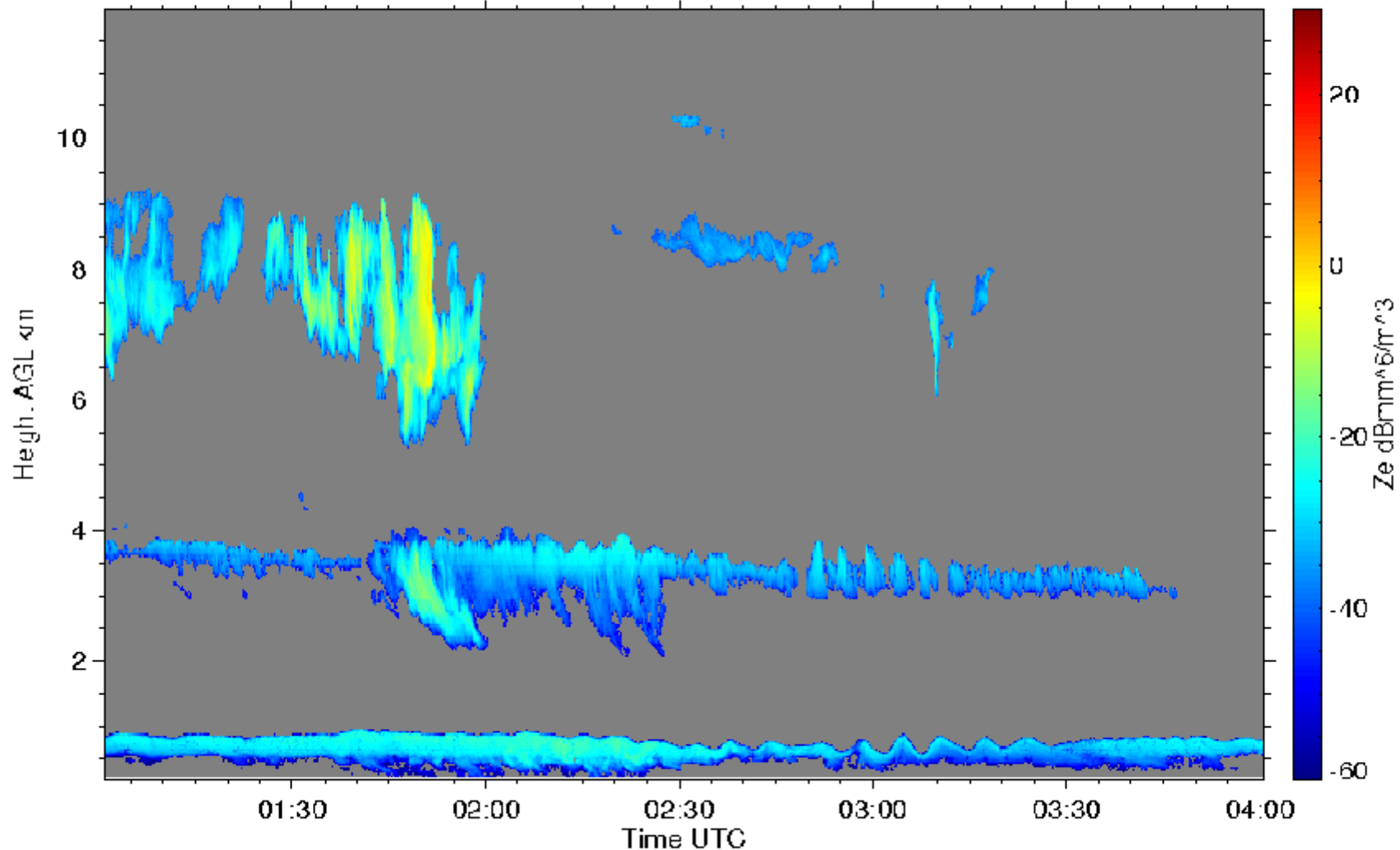


Twisted waveguide pressure feed

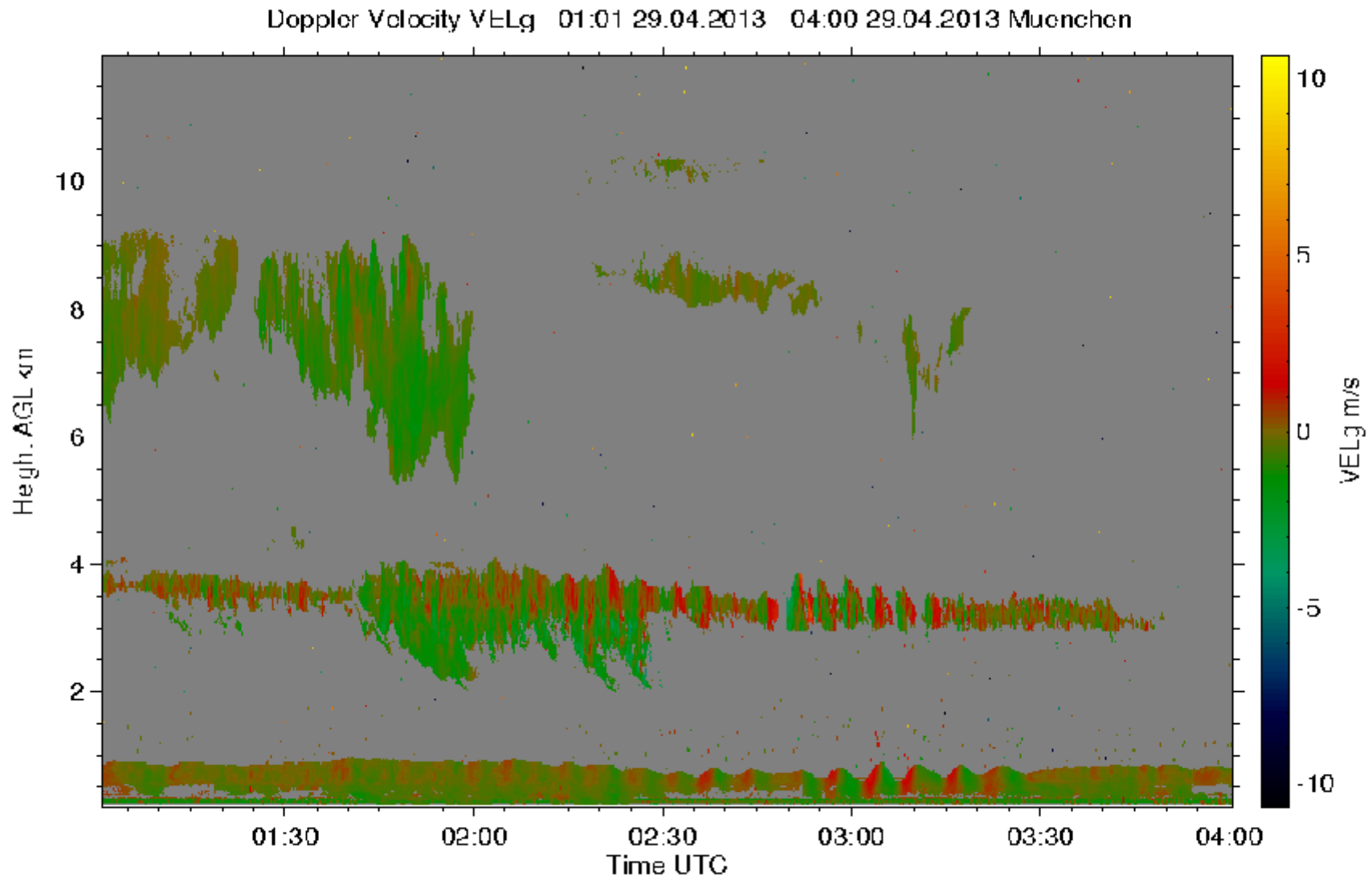


miraMACS – Gravity waves

Equivalent Radar Reflectivity Factor Z_e of Hydrometeors 01:01 29.04.2013 04:00 29.04.2013 Muenchen

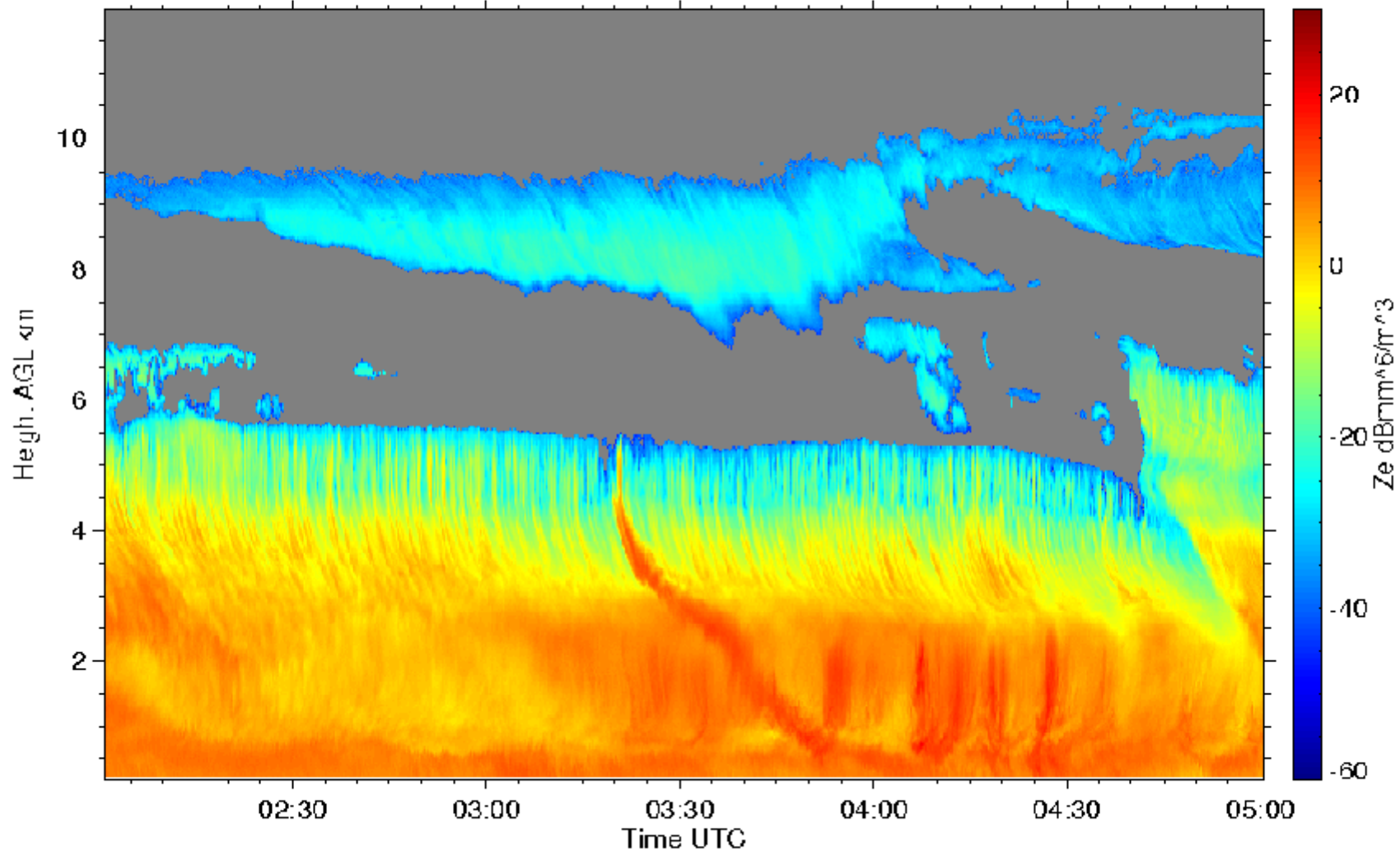


miraMACS – Gravity waves



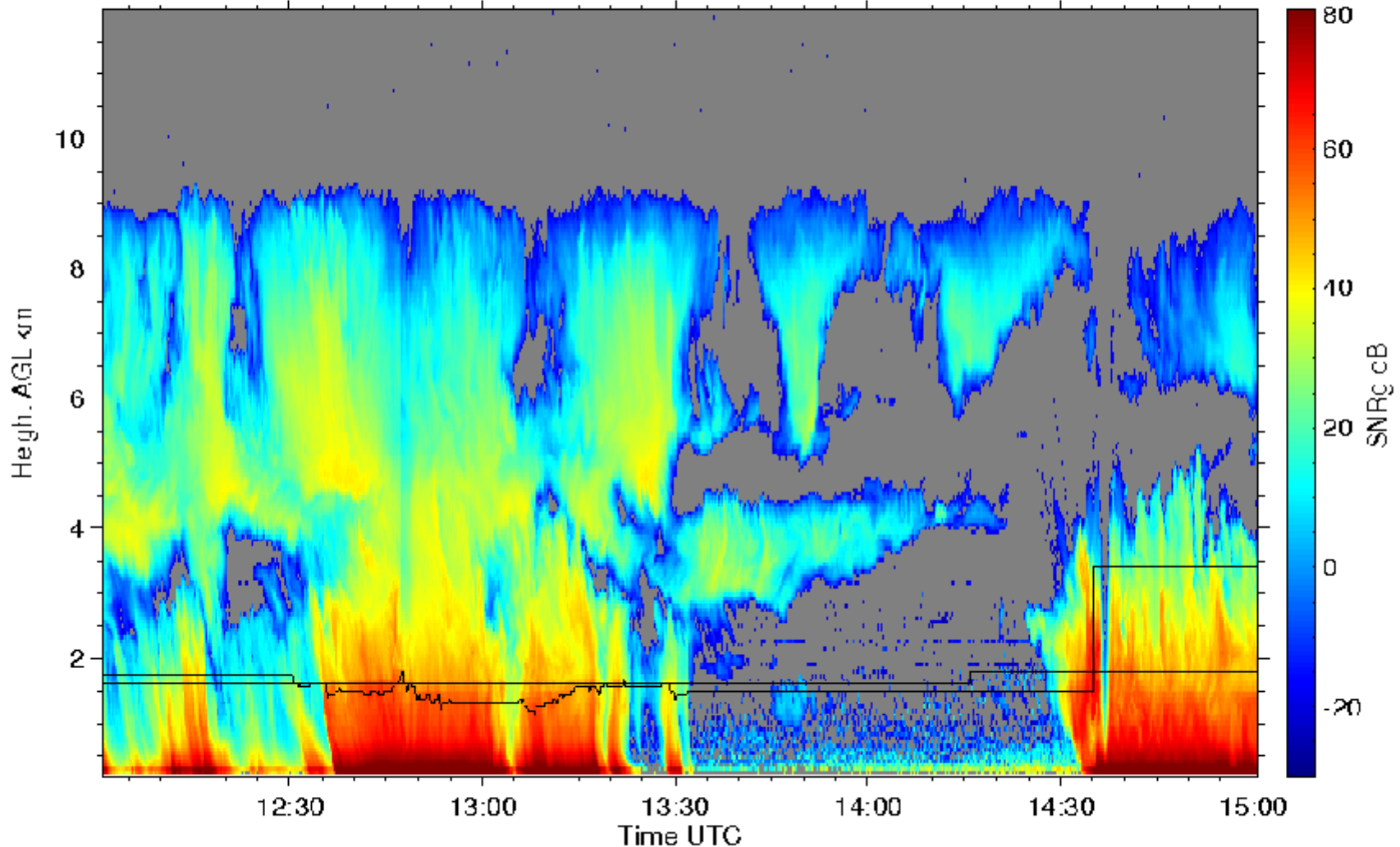
miraMACS – Snow seeding?

Equivalent Radar Reflectivity Factor Z_e of Hydrometeors 02:01 04.02.2013 05:00 04.02.2013 Muenchen



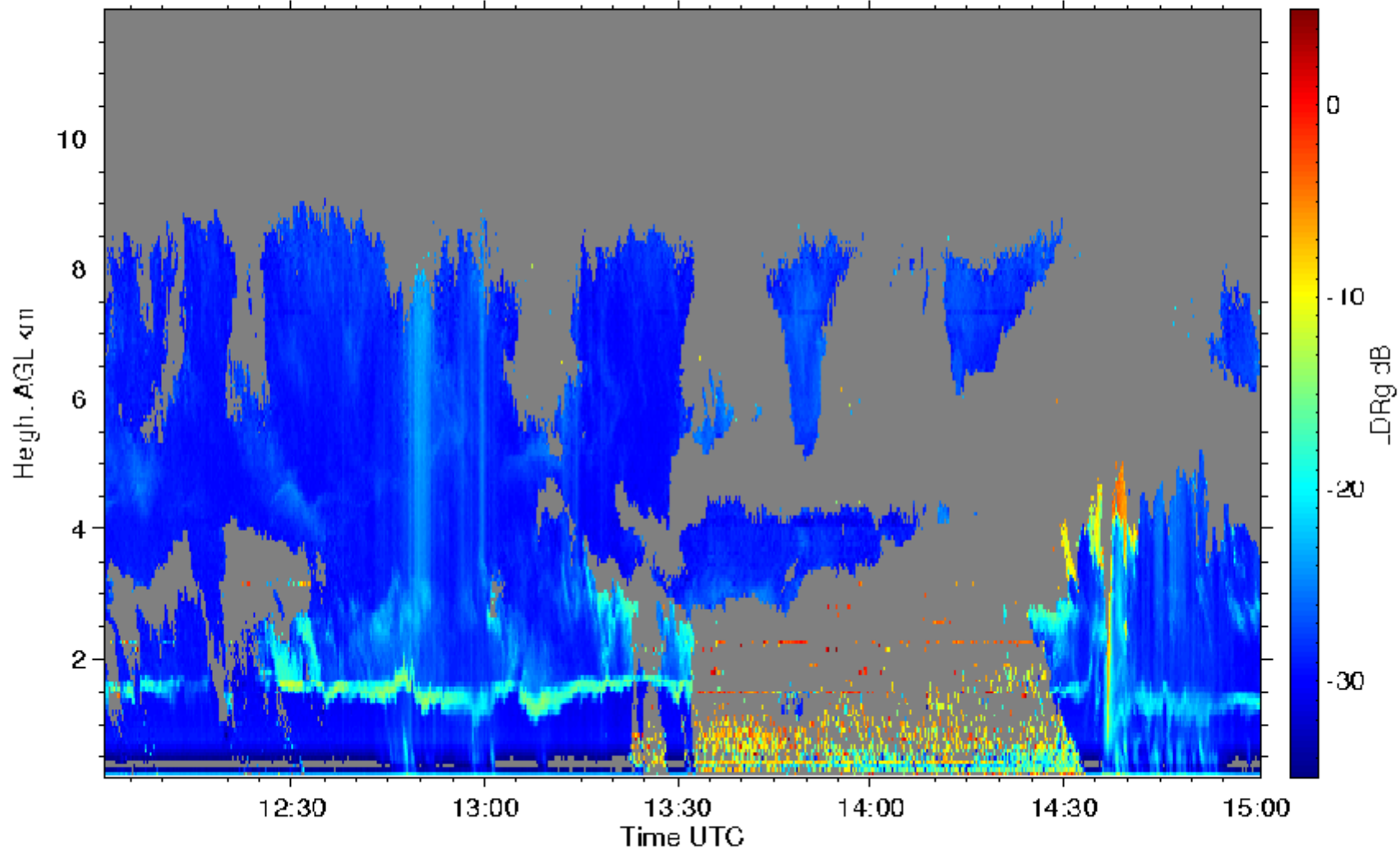
miraMACS – Side lobe effect

20140507_0000.mmc1x Reflectivity SNR_{CB} 12:01 07.05.2014 15:00 07.05.2014 Muenchen

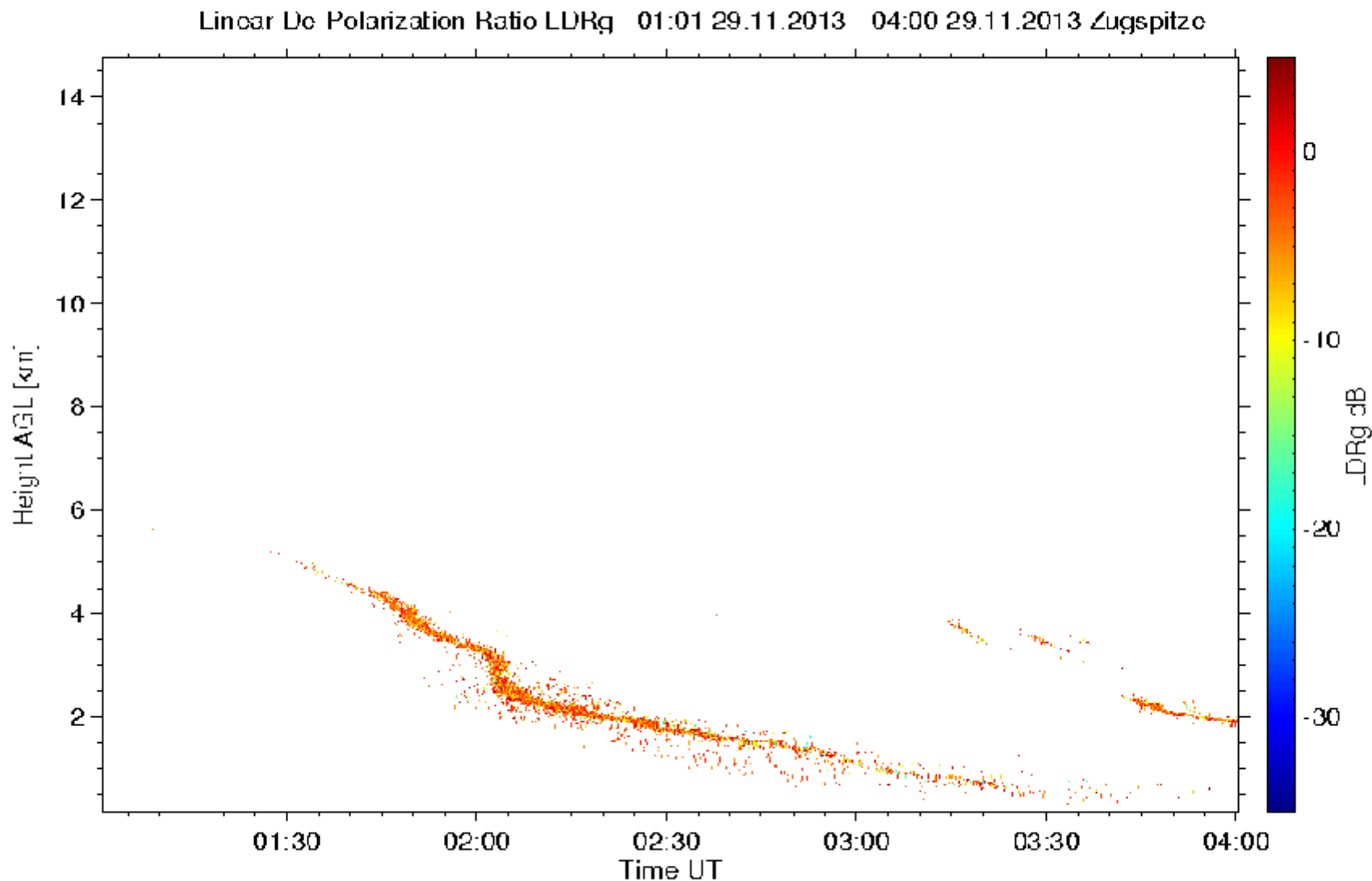


miraMACS – Side lobe effect

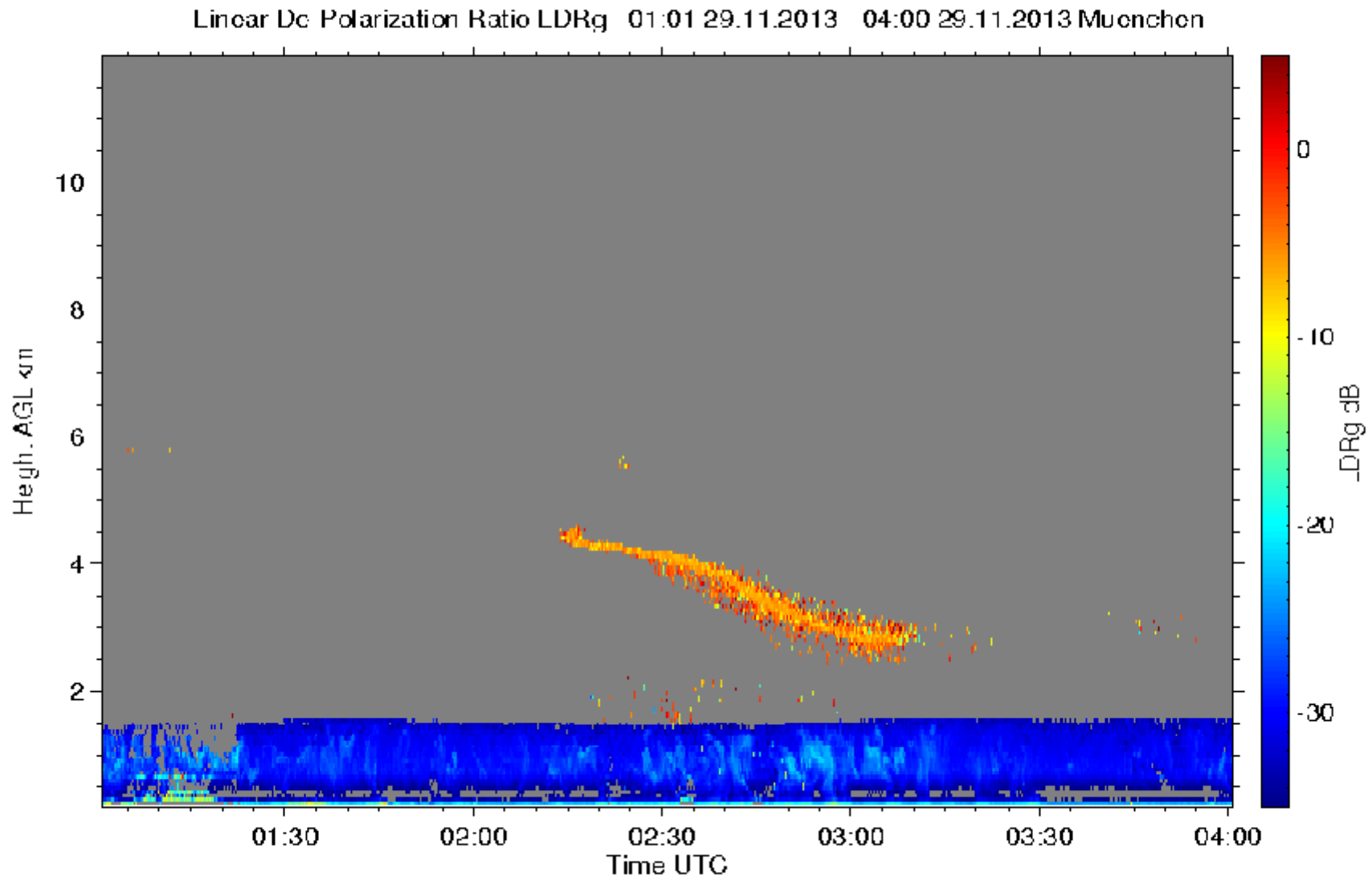
Linear Dc Polarization Ratio LDRg 12:01 07.05.2014 15:00 07.05.2014 Muenchen



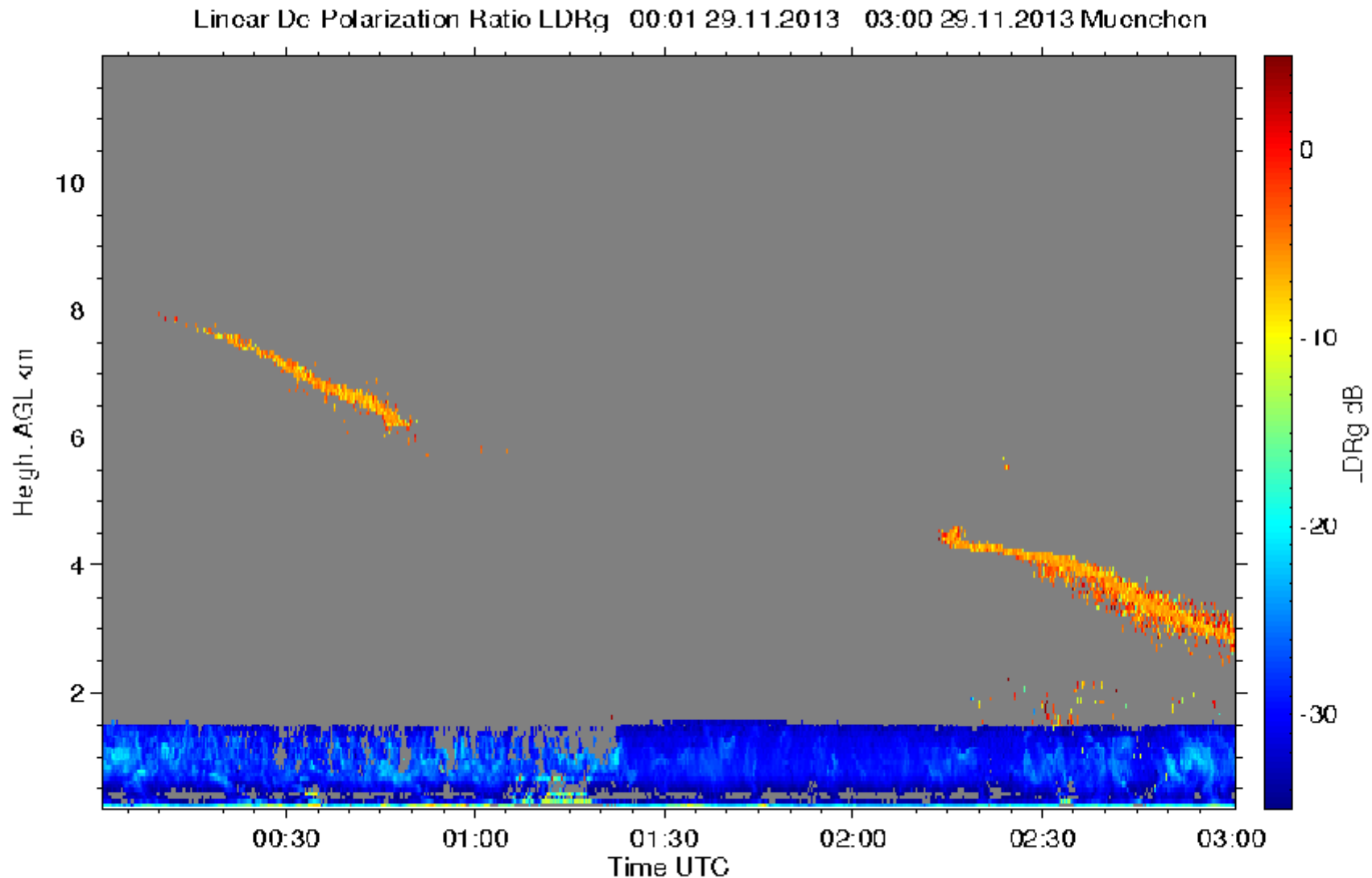
miraMACS – Ultraragiant aerosol?



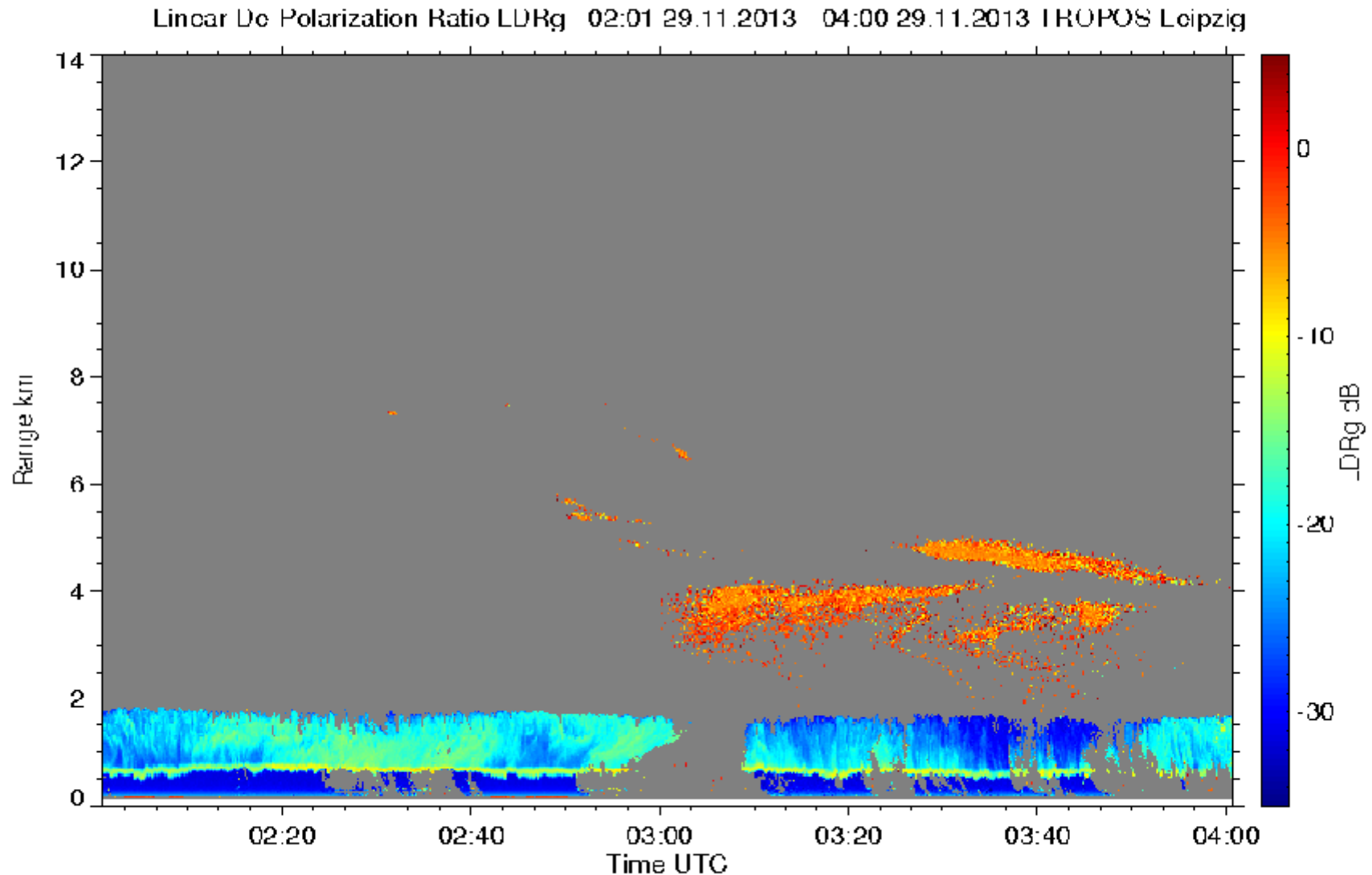
miraMACS – Ultraradiant aerosol?



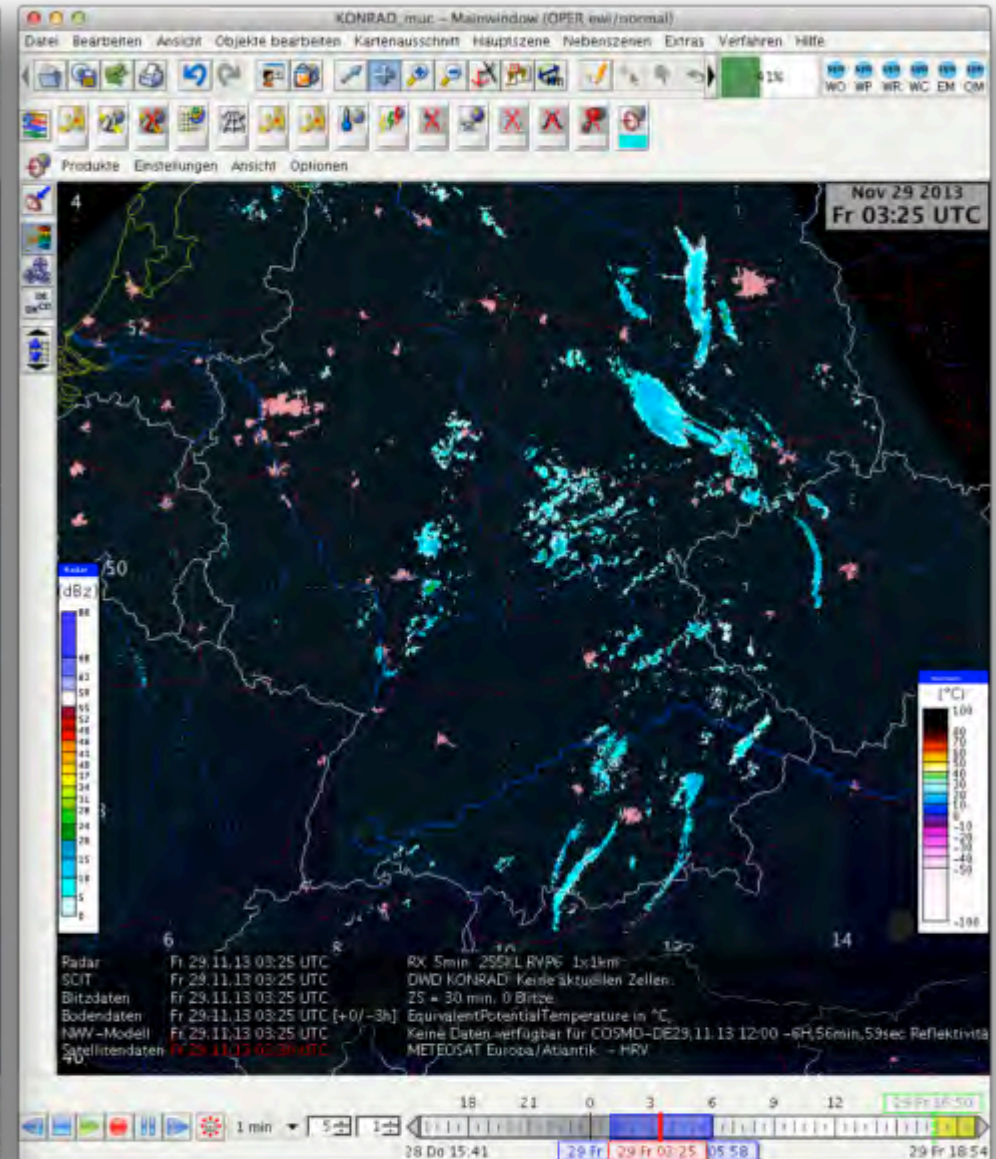
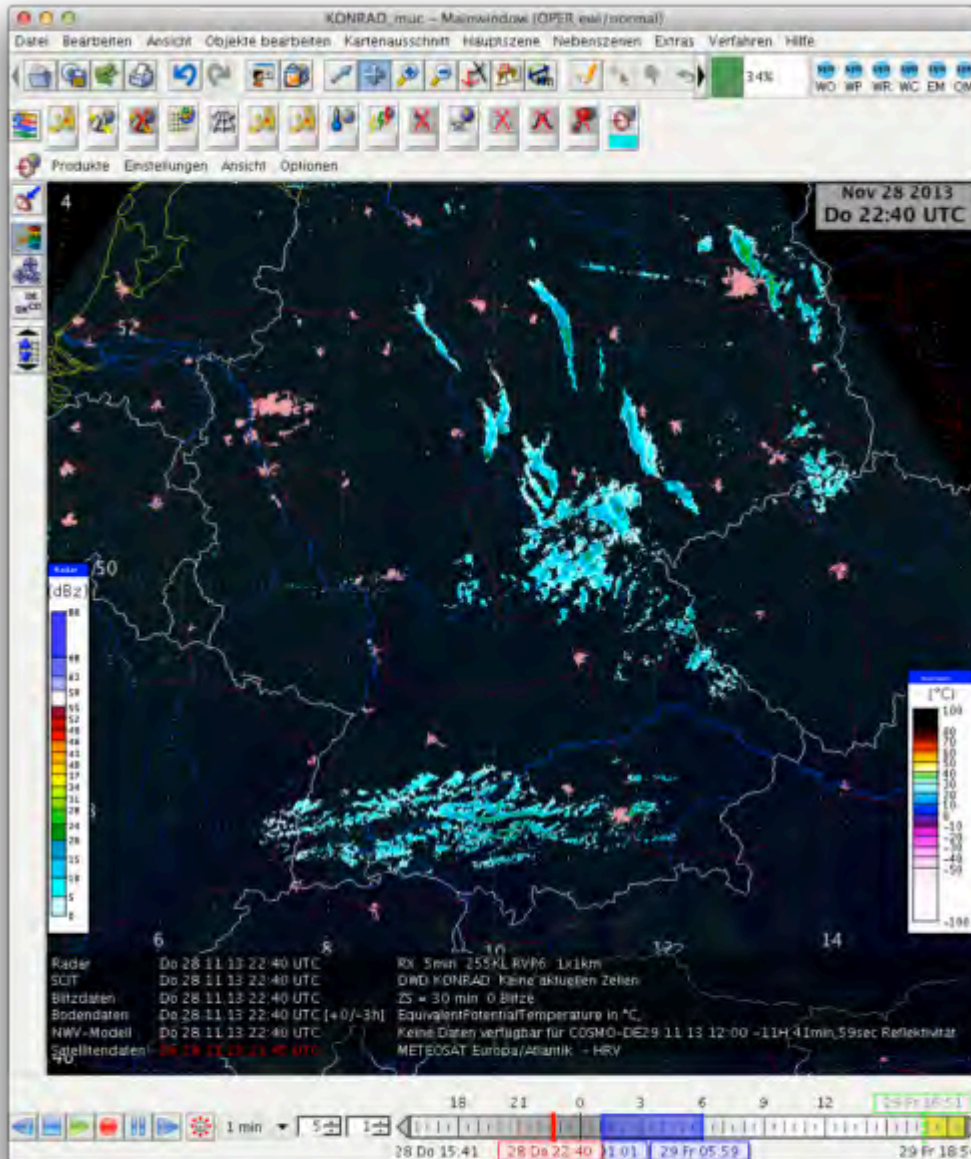
miraMACS – Ultraragiant aerosol?



miraMACS – Ultraradiant aerosol?

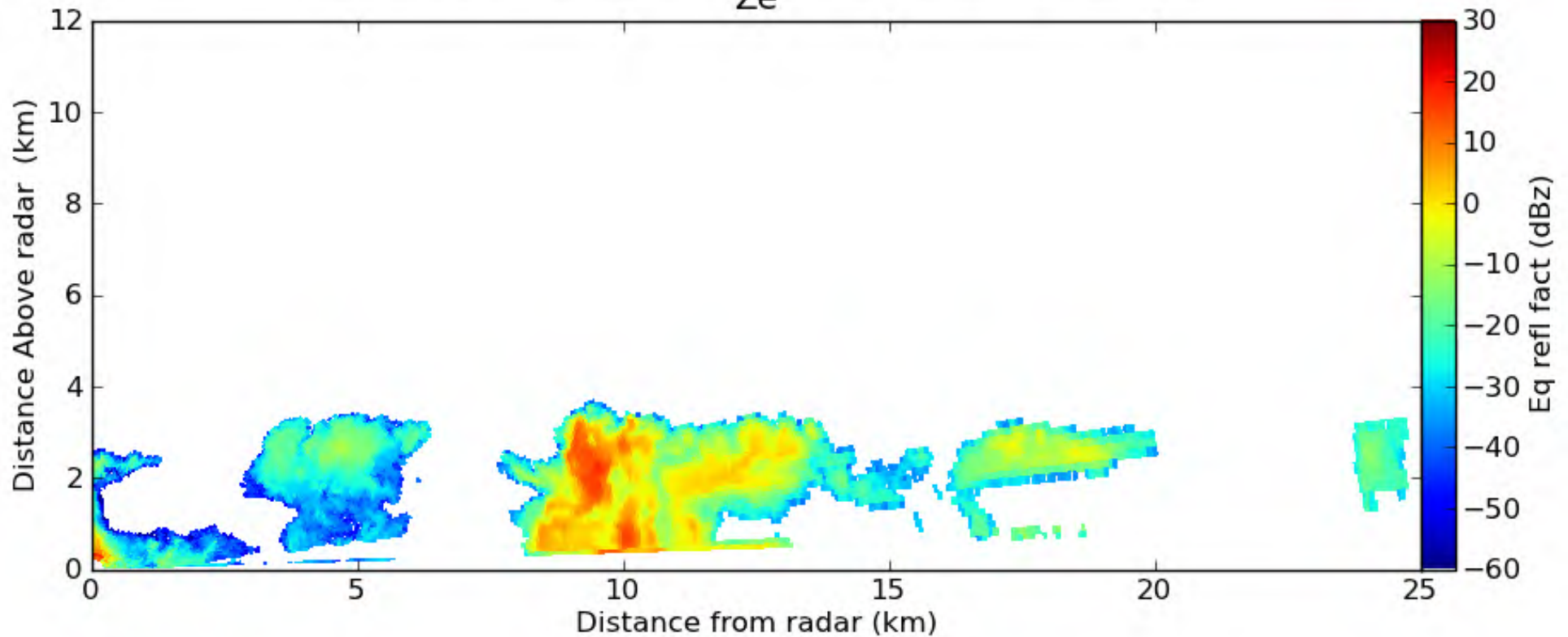


miraMACS – Or Chaff?



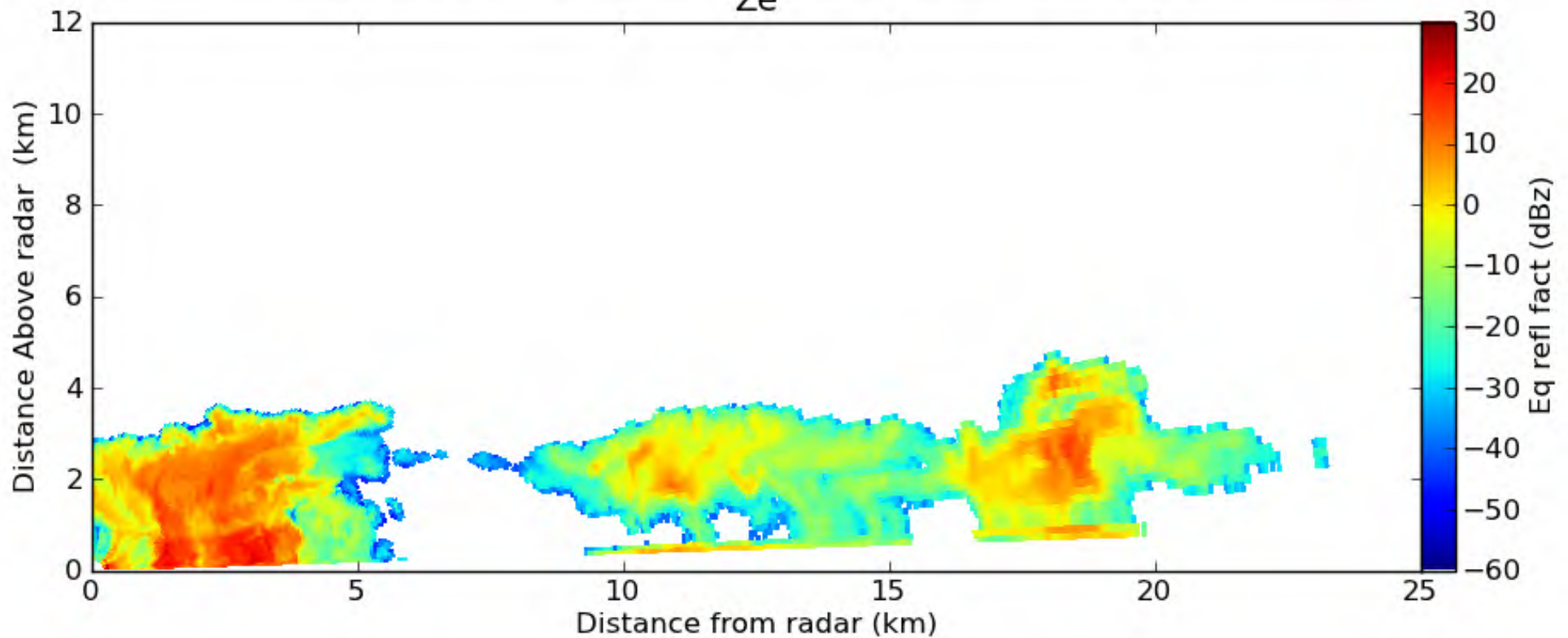
miraMACS – RHIs from today

LMU miraMACS 195.4 Deg. 2014-05-14T13:46:41Z
Ze



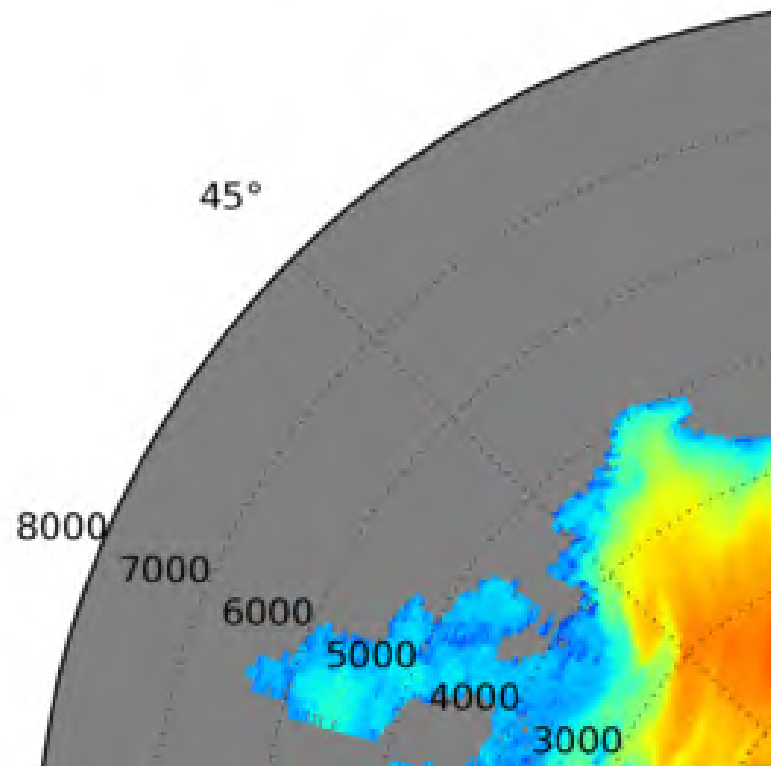
miraMACS – RHIs from today

LMU miraMACS 194.0 Deg. 2014-05-14T13:41:49Z
Ze



miraMACS – cloud evolution

Looking through one specific cloud during its evolution

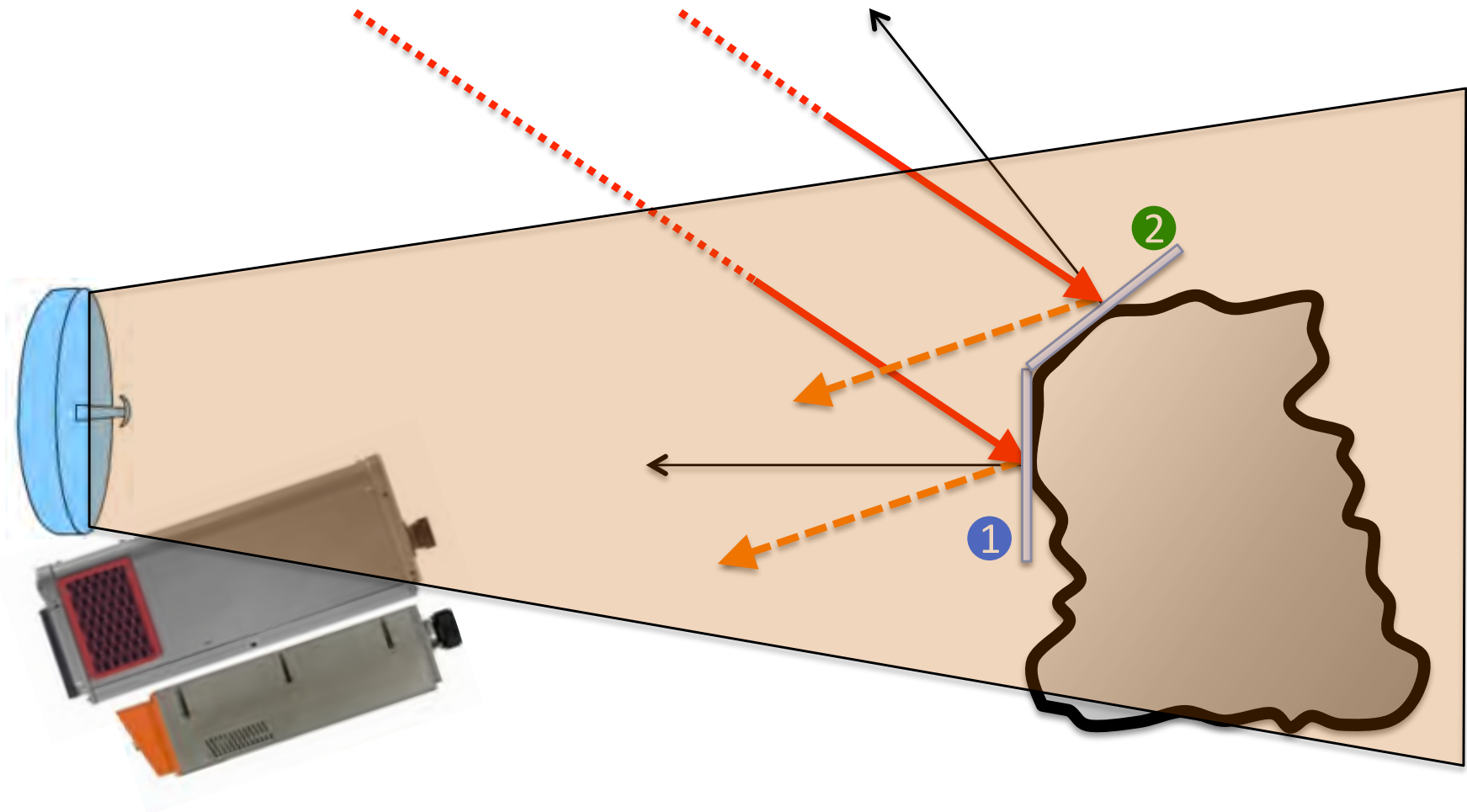


Volumetric reconstruction of clouds

>> Capturing the 3D structure of single clouds <<

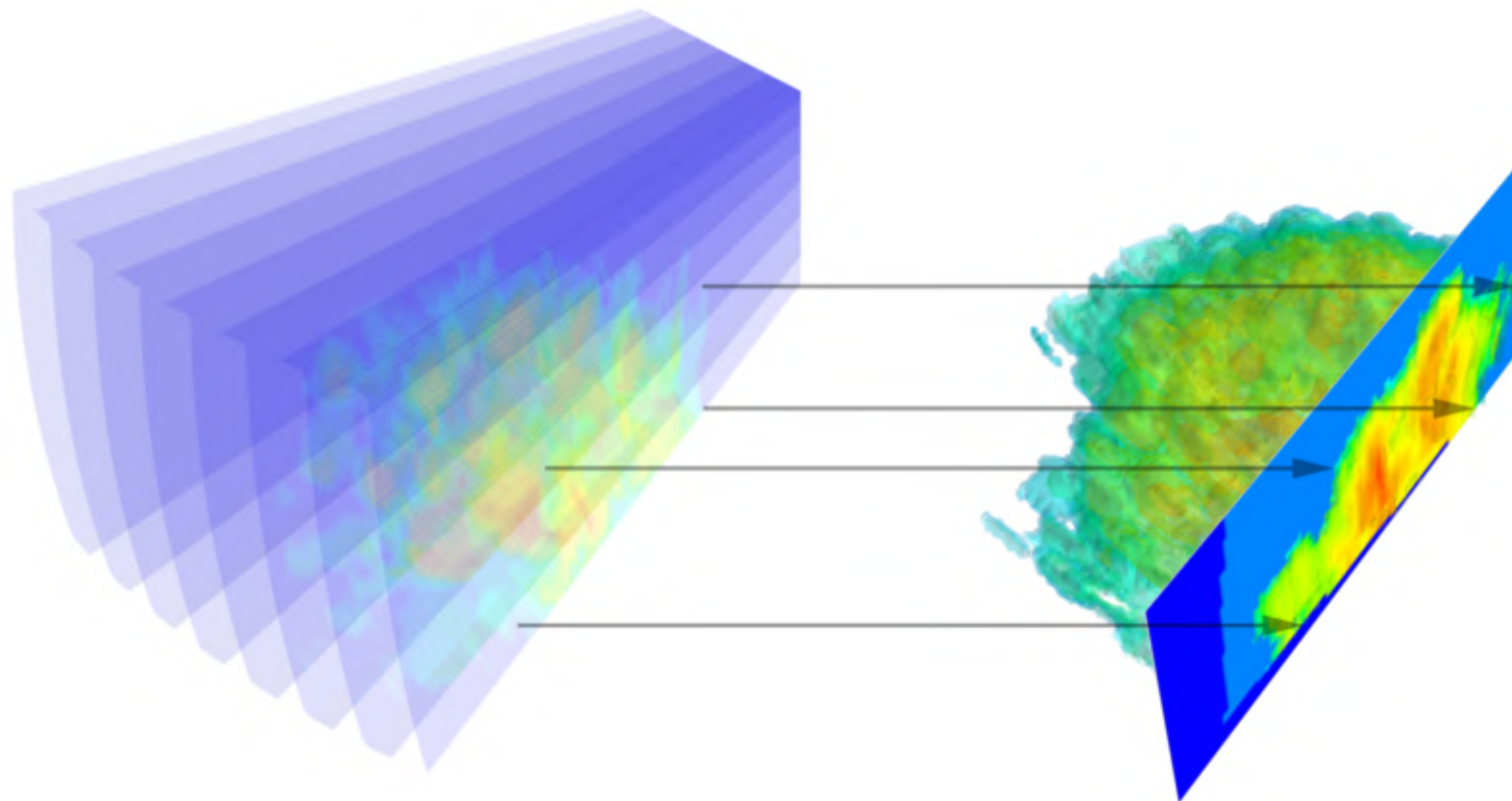
miraMACS – 3D Reconstruction

Reducing the number of degrees of freedom in passive microphysical retrievals



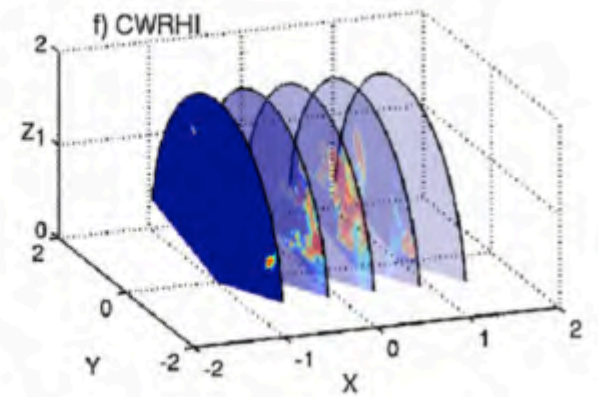
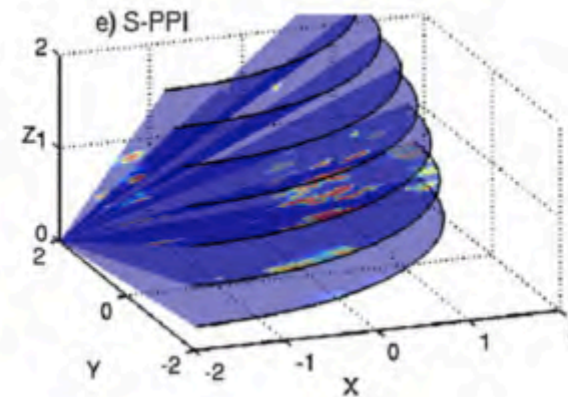
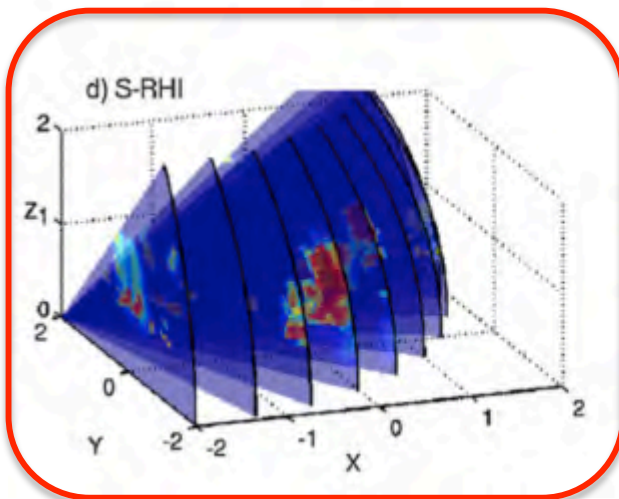
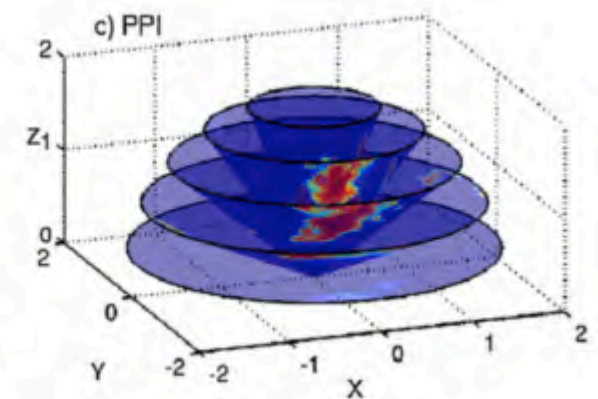
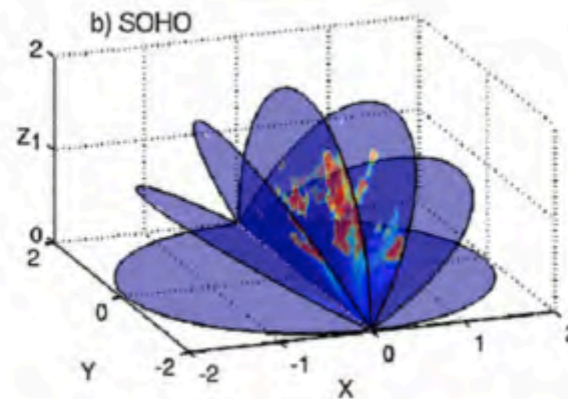
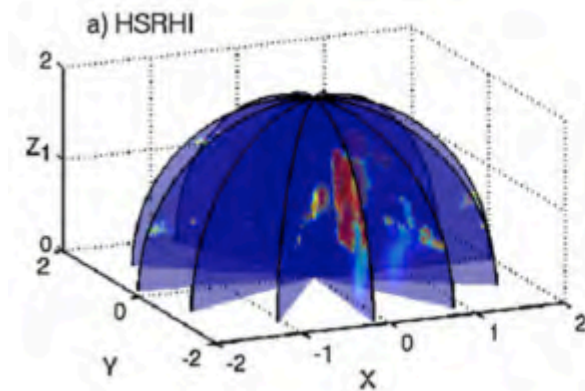
miraMACS – cloud reconstruction

Reconstructing a cloud from a set of radar slices



miraMACS – scan strategies

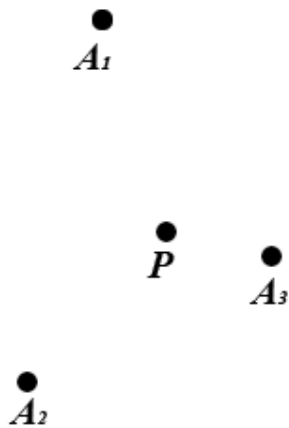
The various methods to sample a cloud



miraMACS – interpolation methods

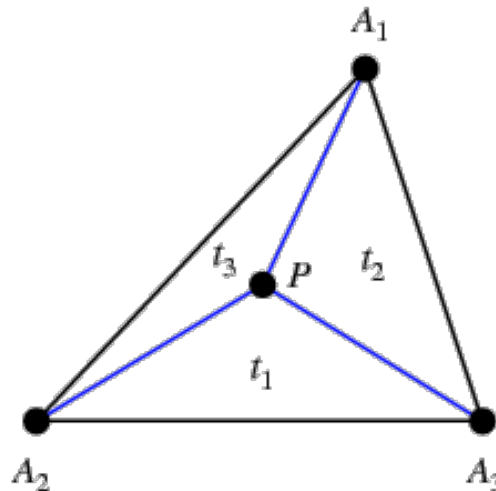
The methods to interpolate in-between profiles

Nearest Neighbor



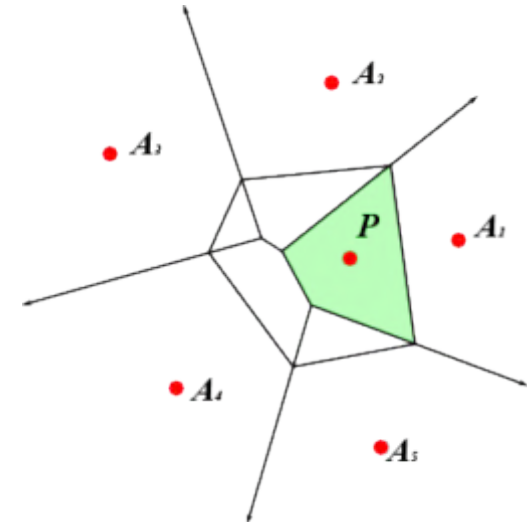
- + very simple and fast
- no smooth field
- unsuitable for coarse sampling

Barycentric Interpolation



- + smooth field
- simplices sometimes visible

Natural Neighbor

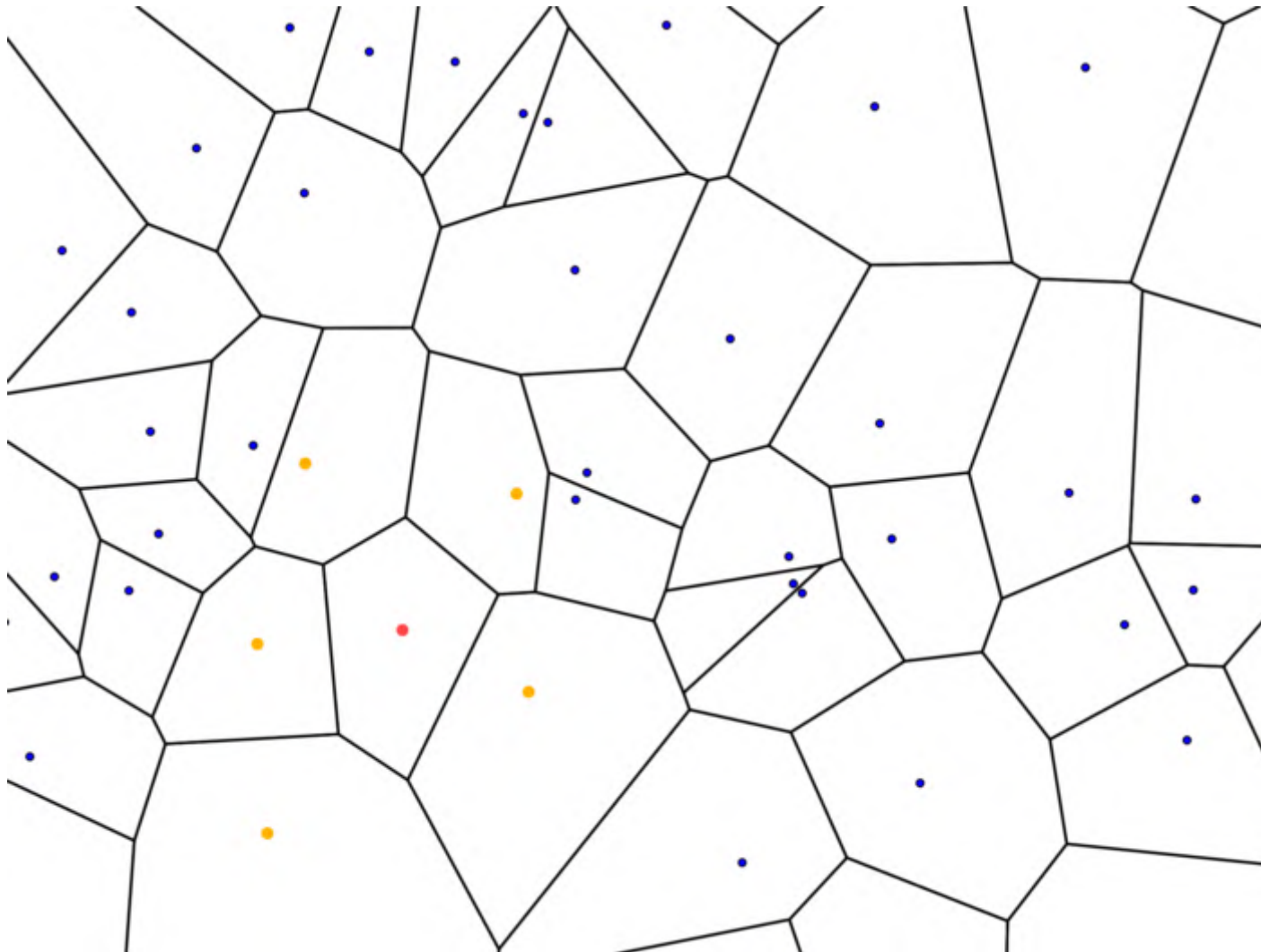


- + adaptive to grid
- numerical unstable

based on Delaunay triangulation / Voronoi diagram

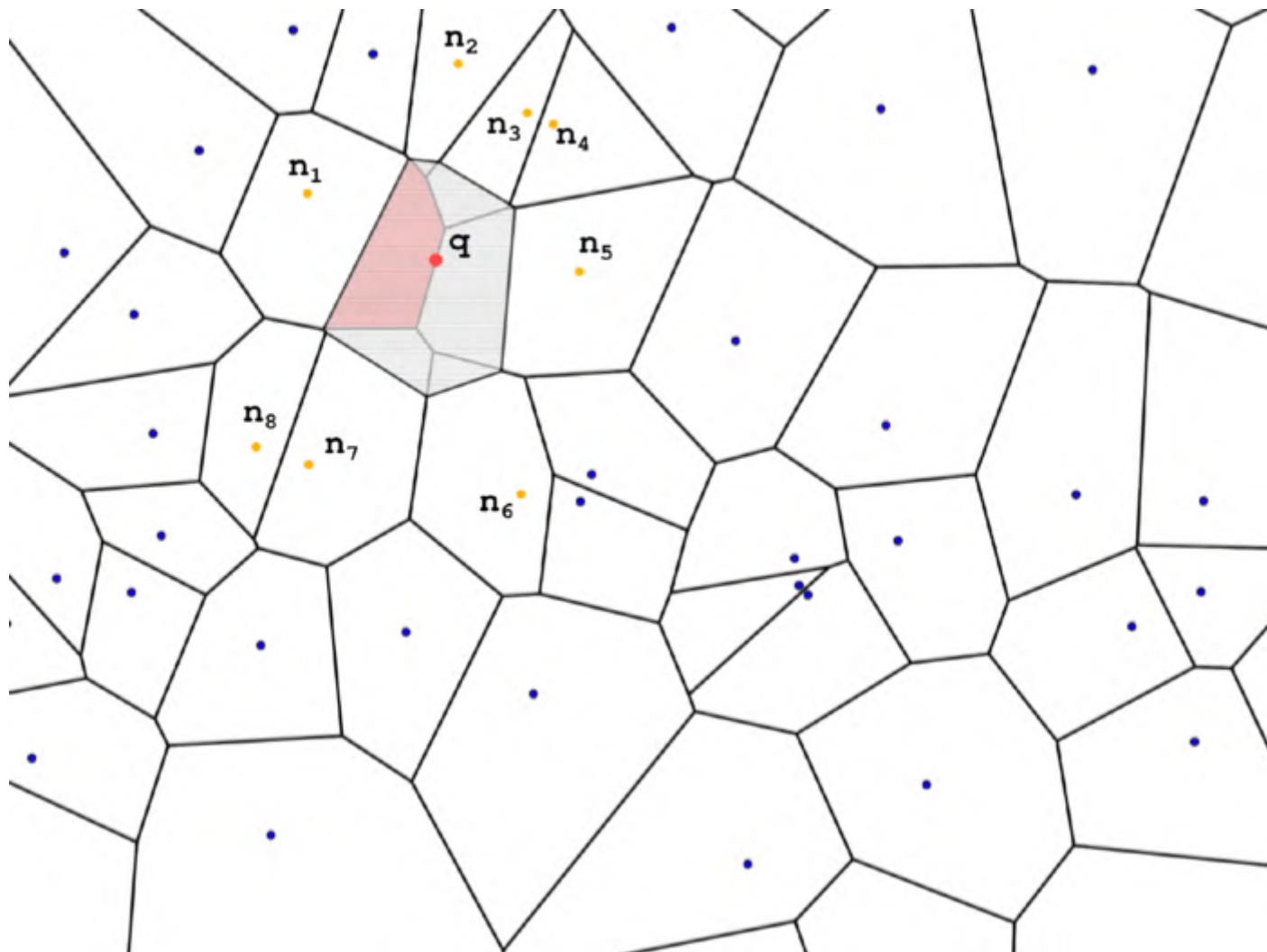
miraMACS – natural neighbor

The methods to interpolate in-between profiles



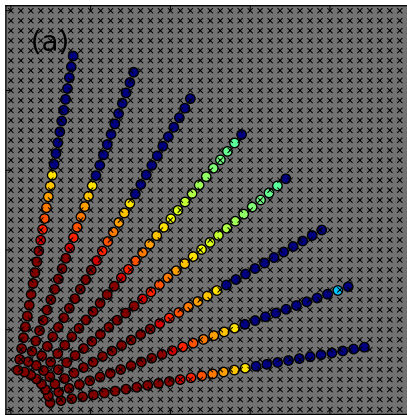
miraMACS – natural neighbor

The methods to interpolate in-between profiles

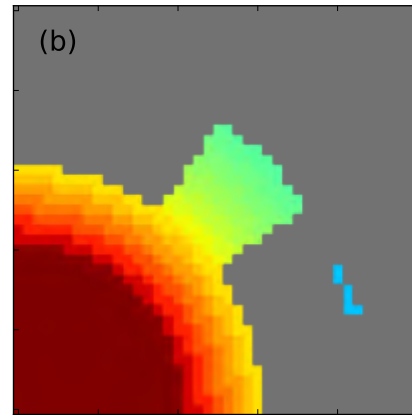


miraMACS – interpolation methods

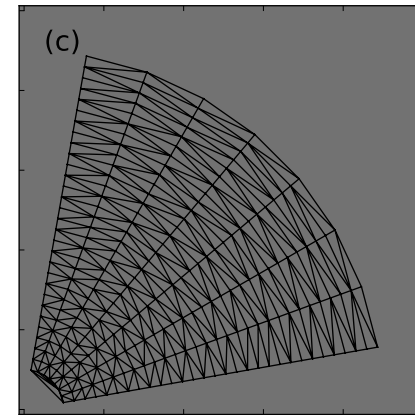
The methods to interpolate in-between profiles



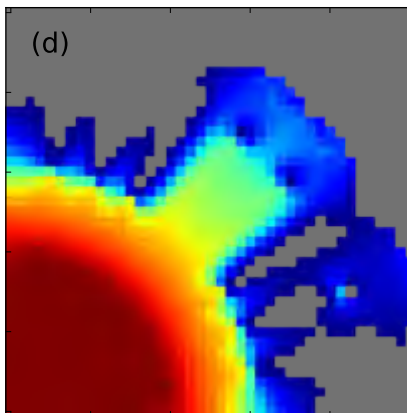
Sim. Radar Beams



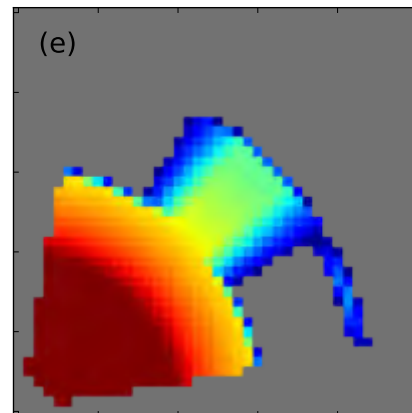
Model Cloud



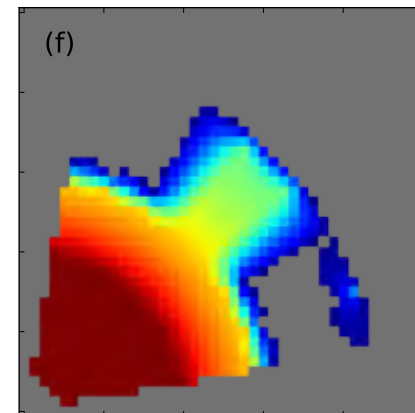
Voronoi Triangulation



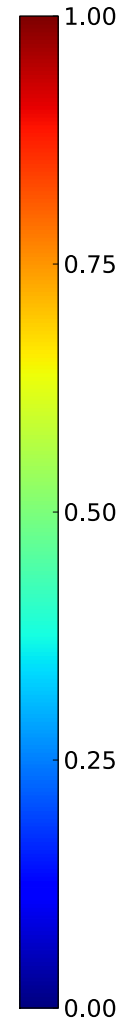
Nearest Interp.



Barycentric Interp.

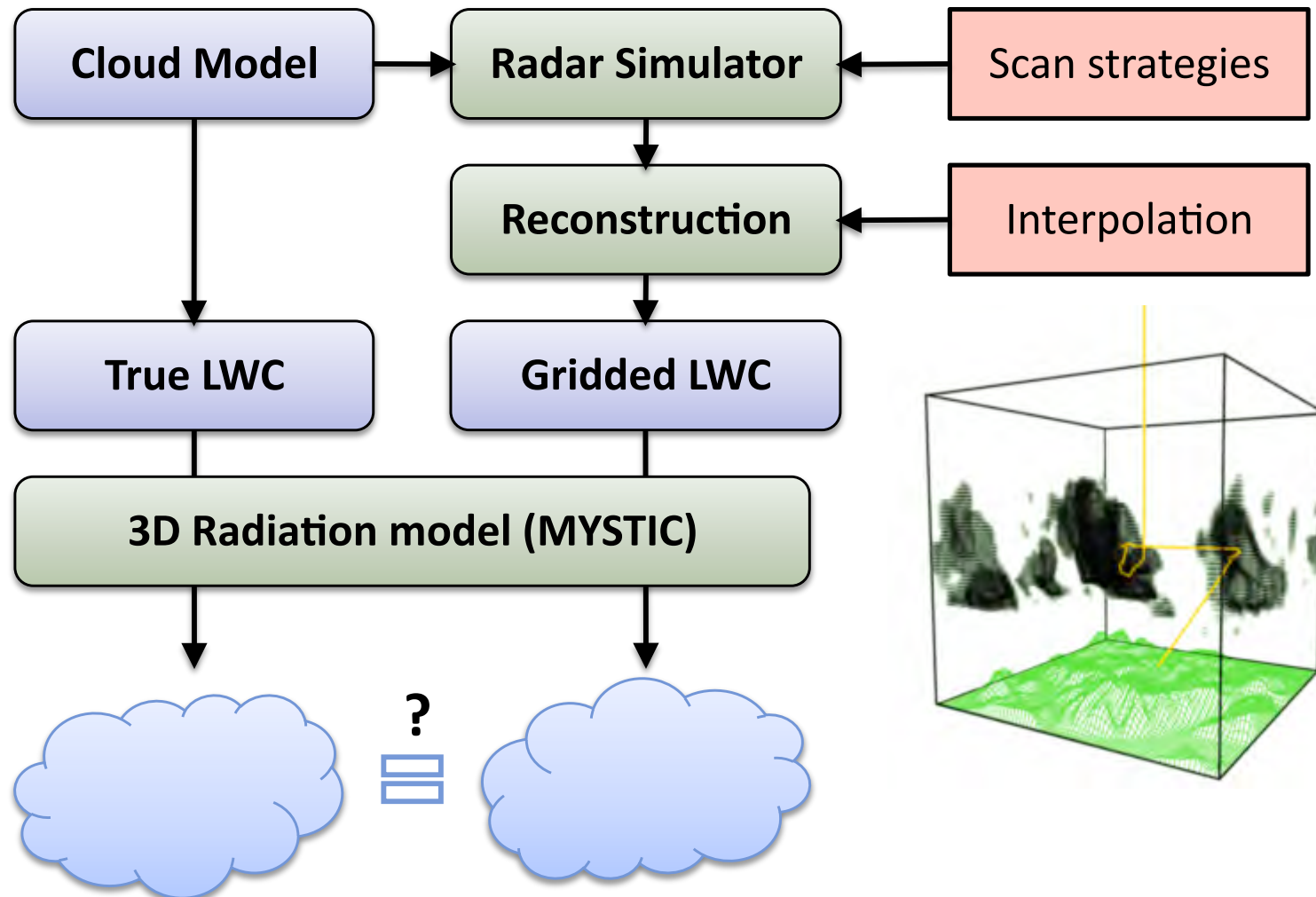


Natural Interp.



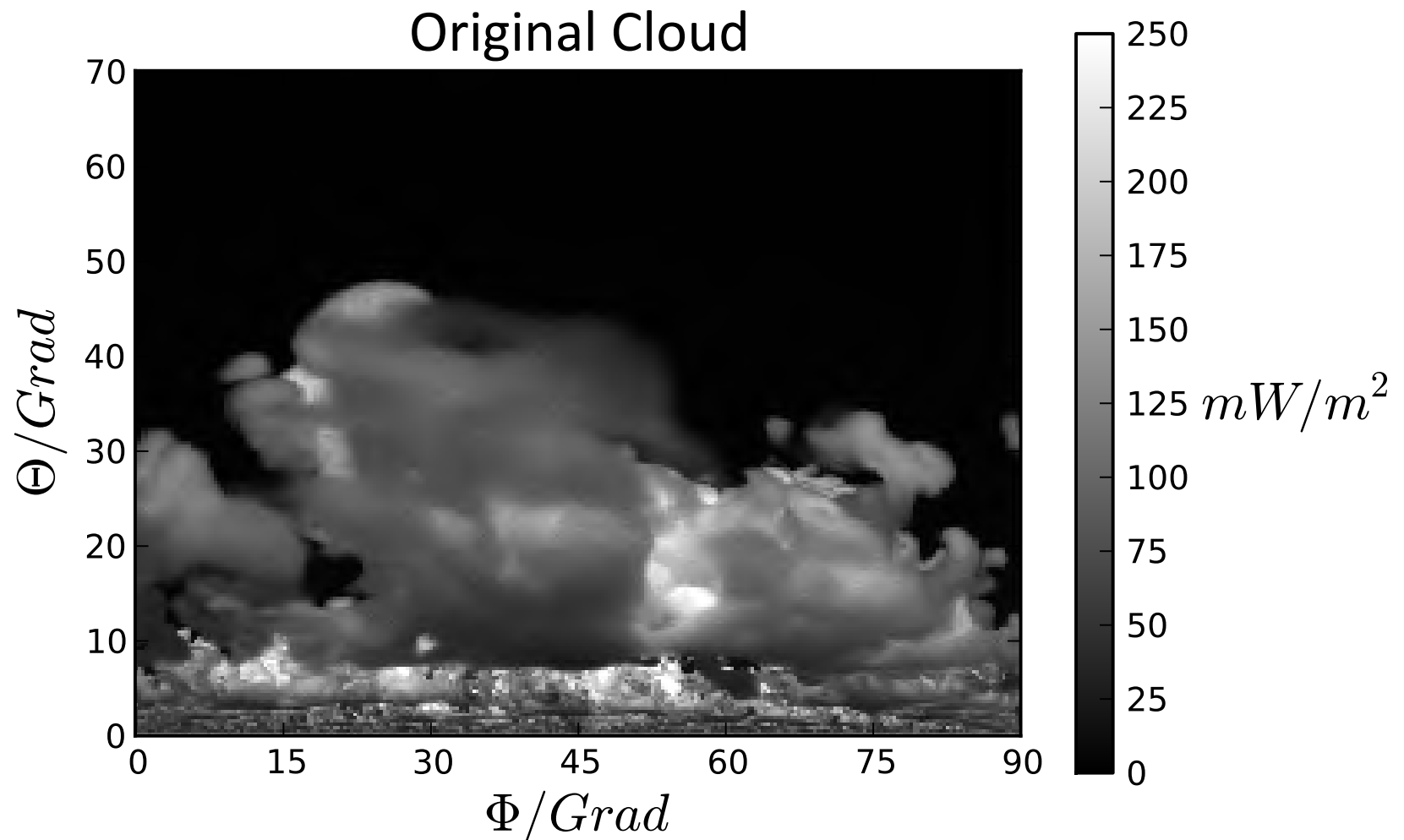
Analysis of the reconstruction

Finding the suitable interpolation method and scanning resolution



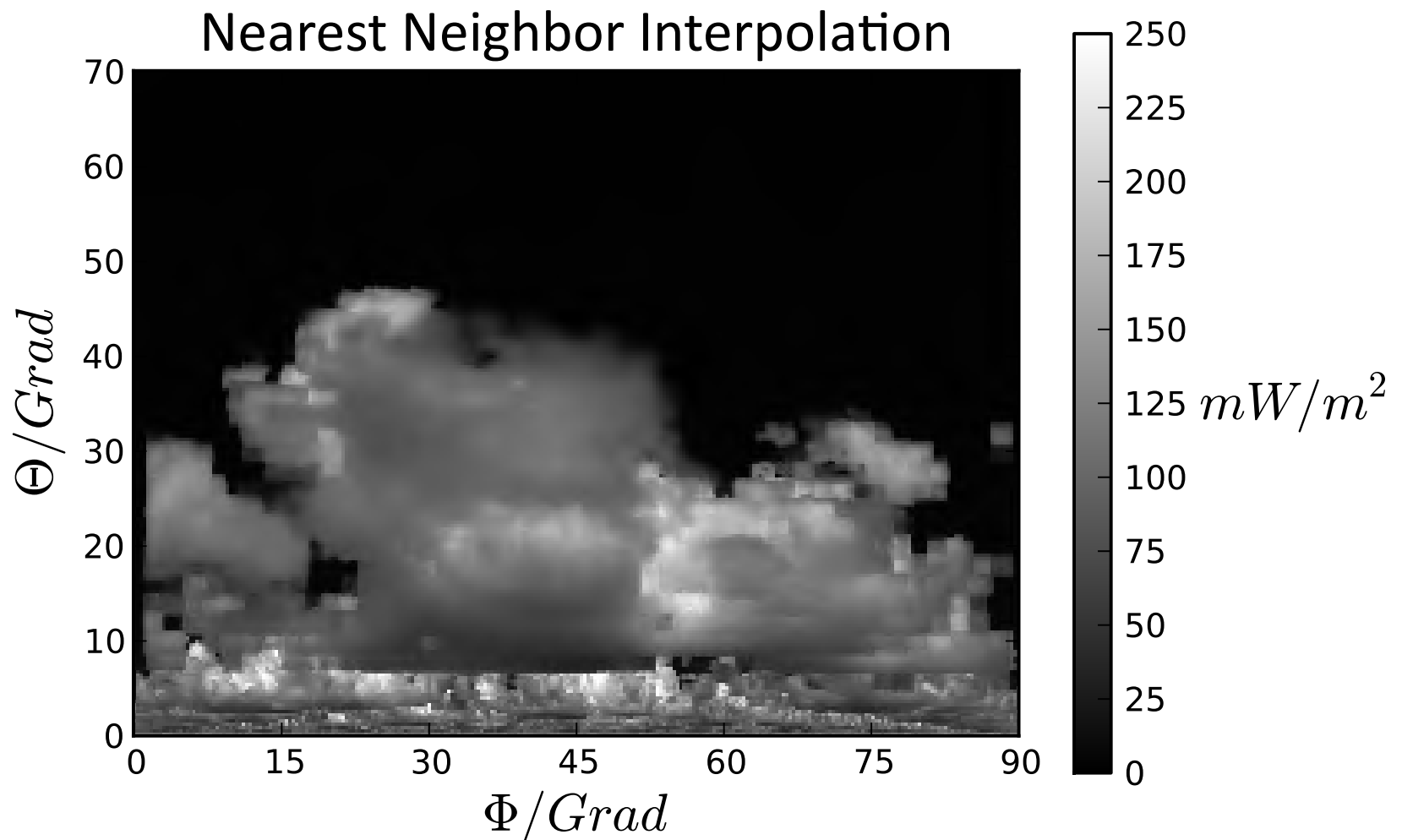
Sensitivity to interpolation method

Which interpolation method reproduces the original cloud best?



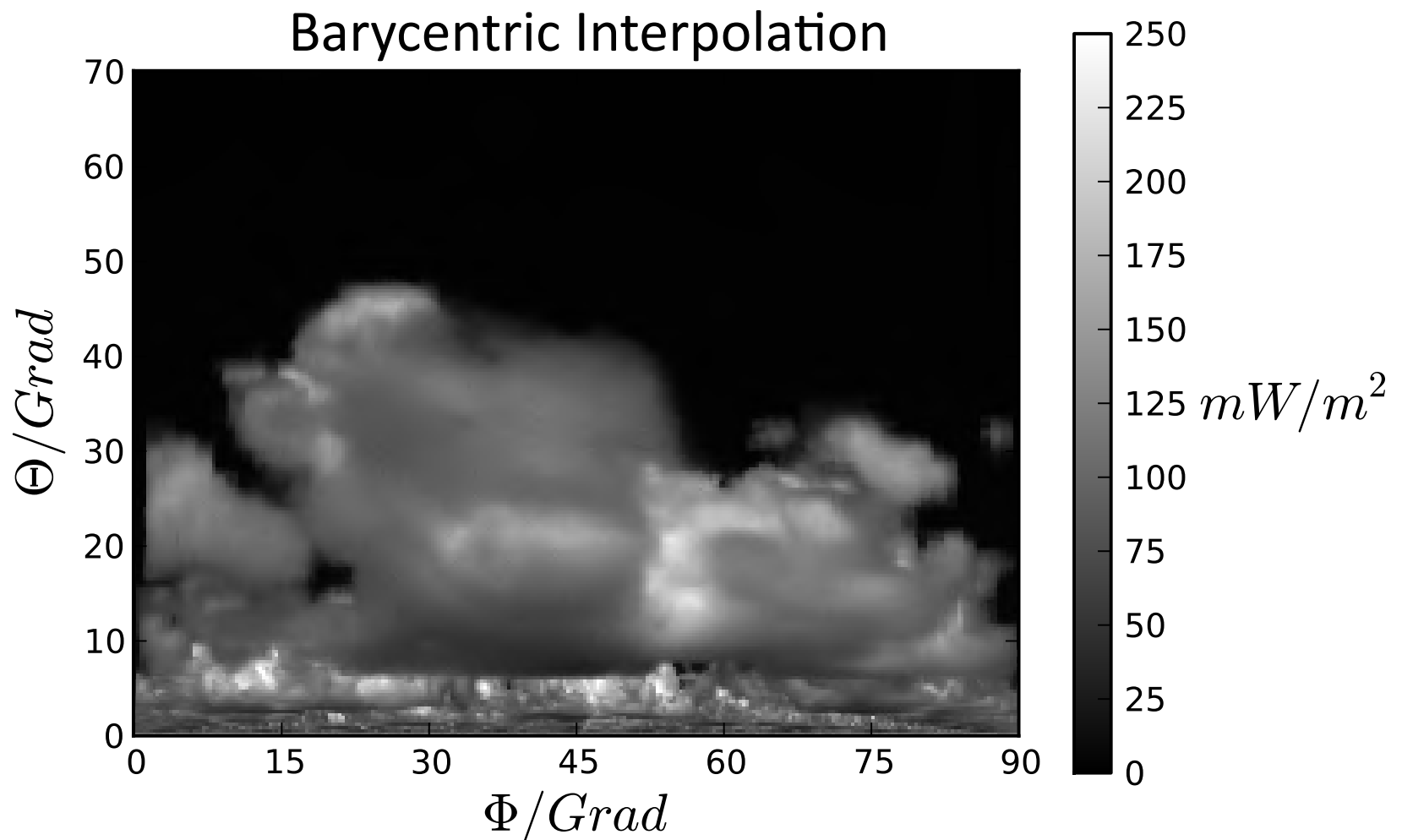
Sensitivity to interpolation method

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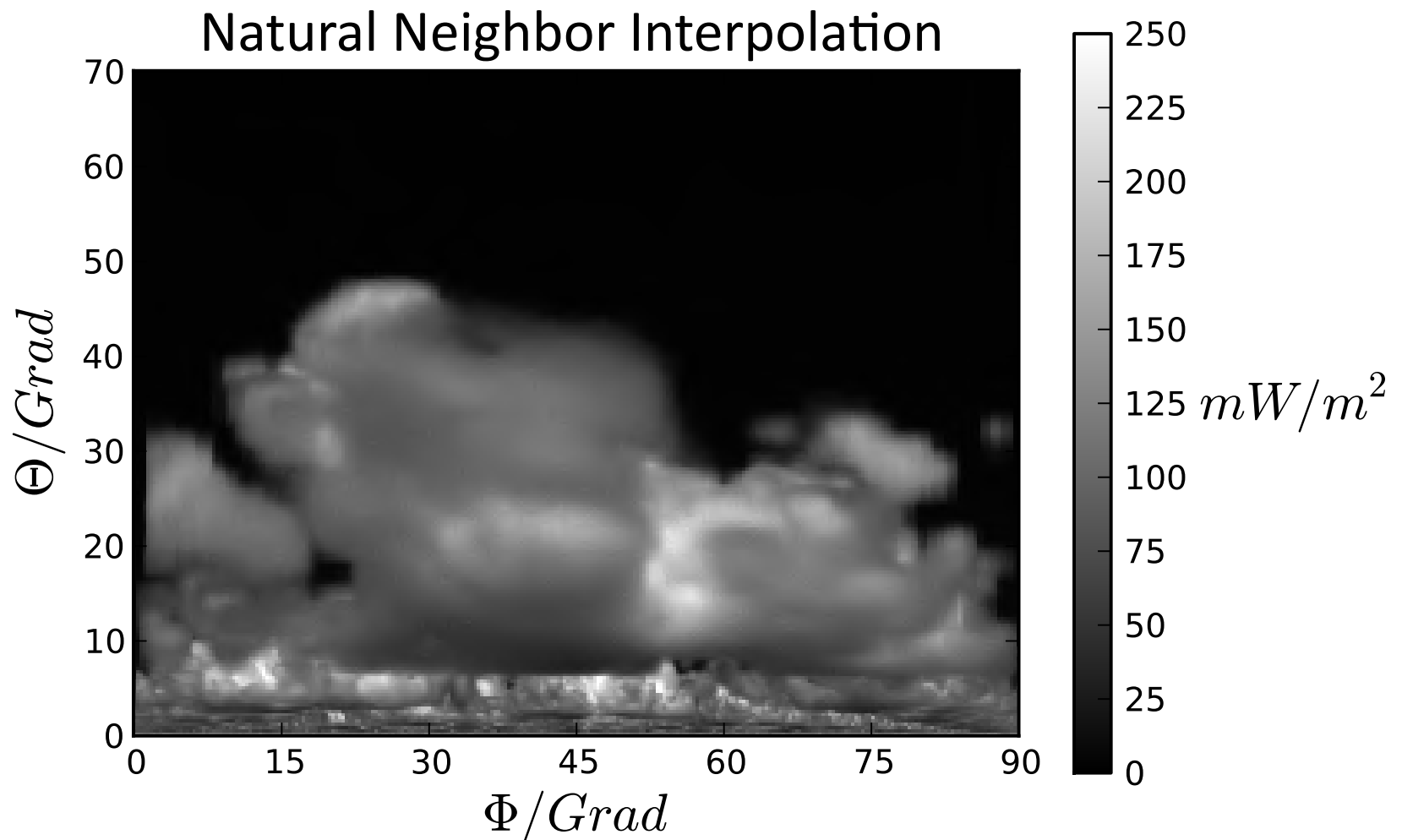
Sensitivity to interpolation method

Which interpolation method reproduces the original cloud best?



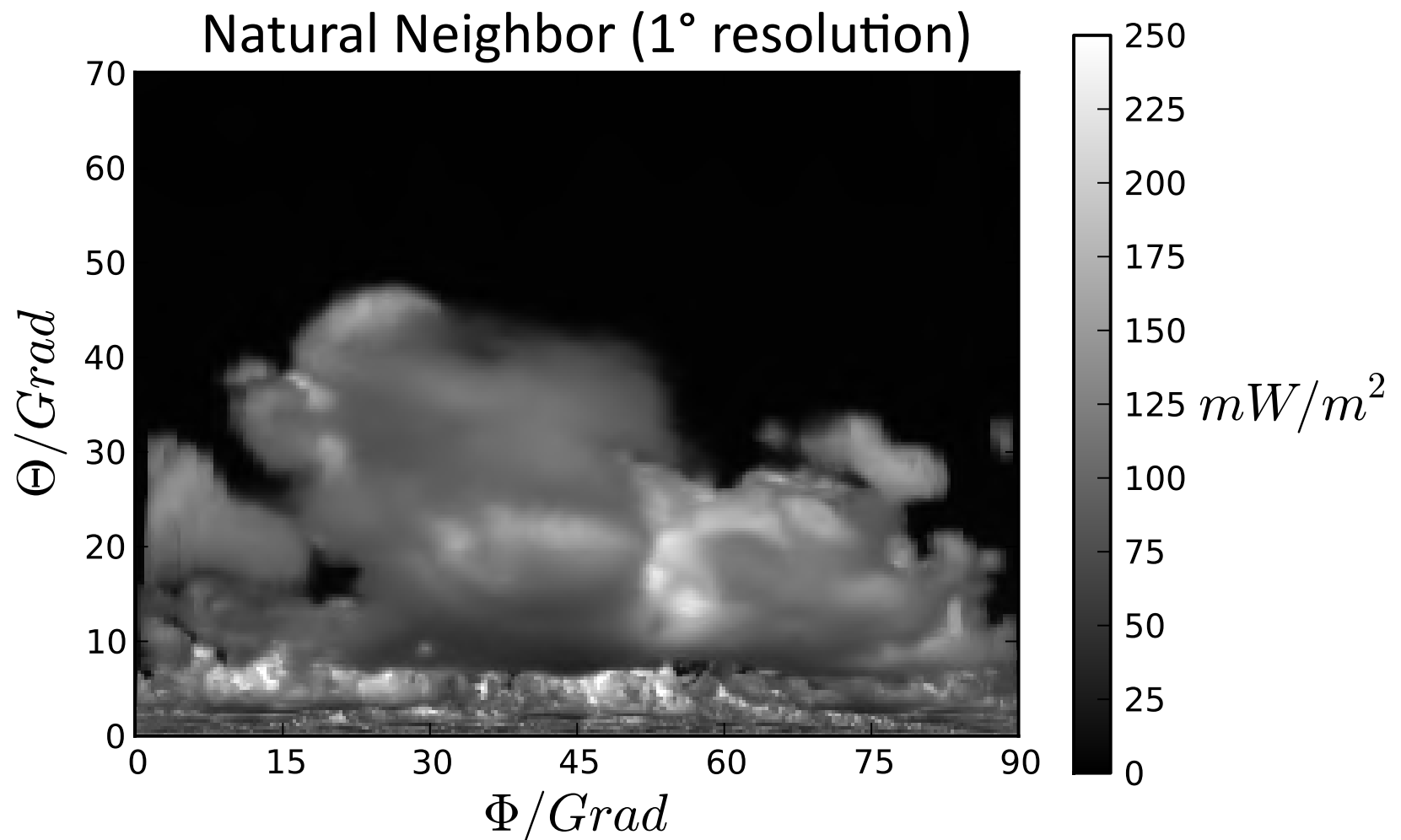
Sensitivity to interpolation method

Which interpolation method reproduces the original cloud best?



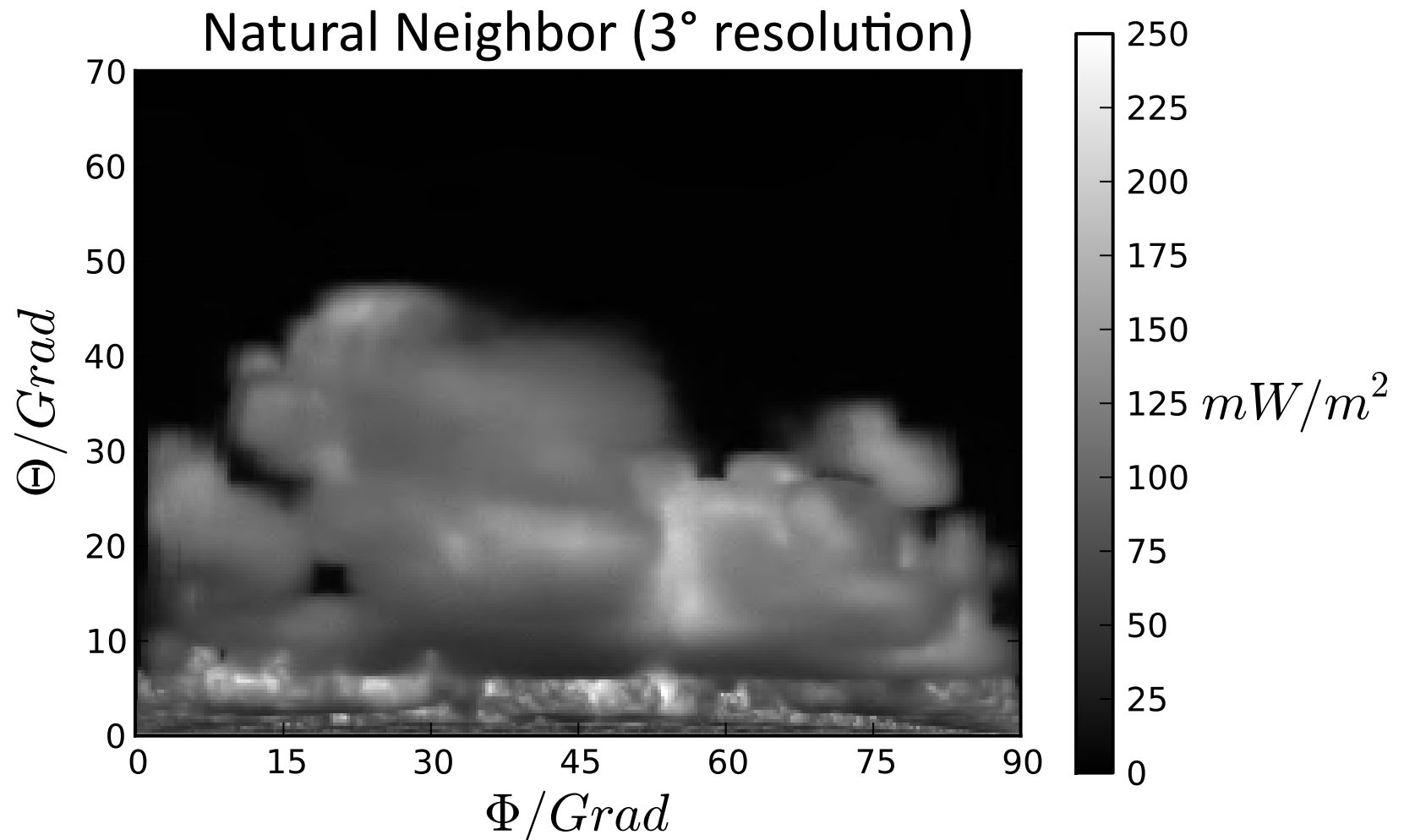
Sensitivity to scan resolution

Finding a compromise between scan resolution and scan duration



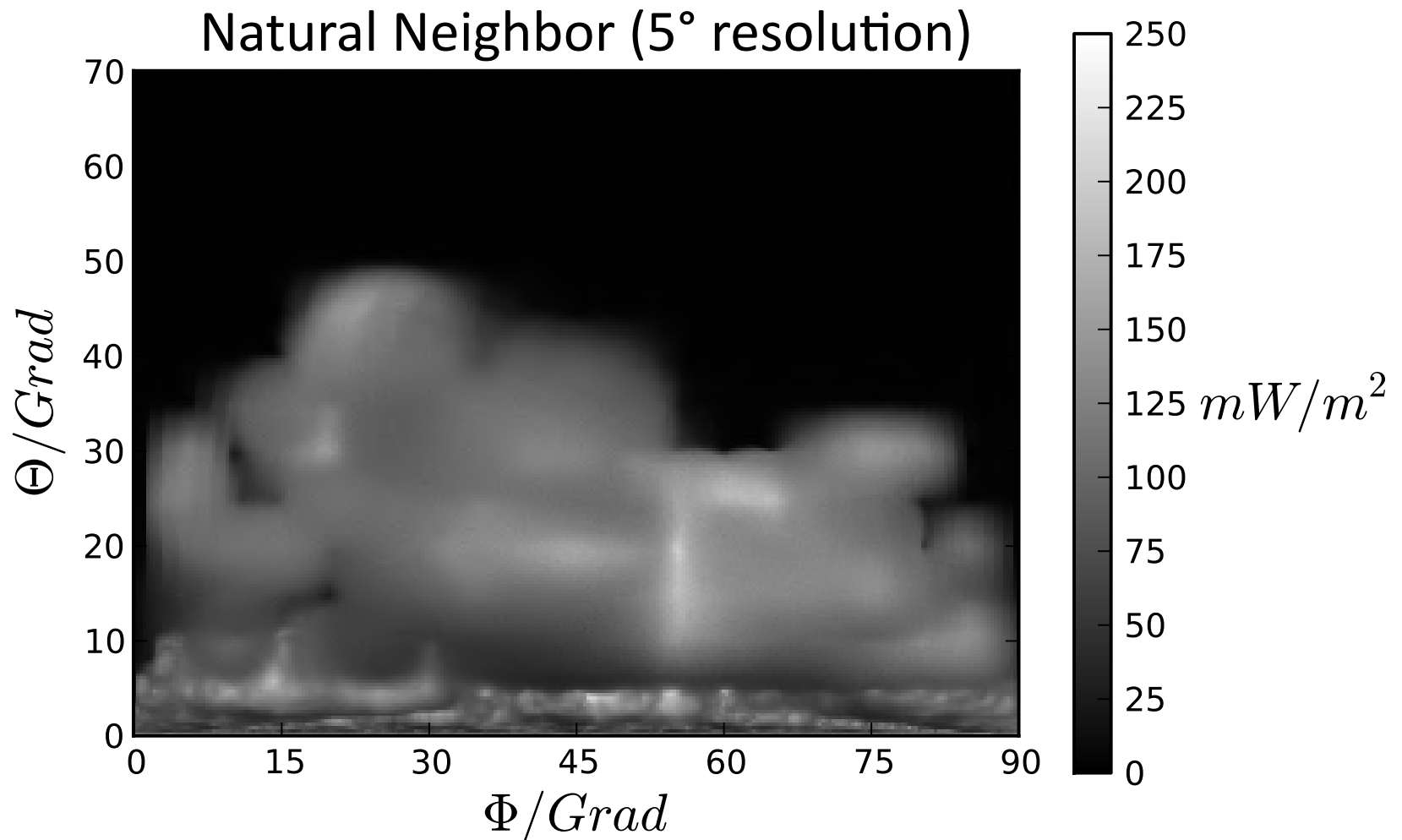
Sensitivity to scan resolution

Finding a compromise between scan resolution and scan duration



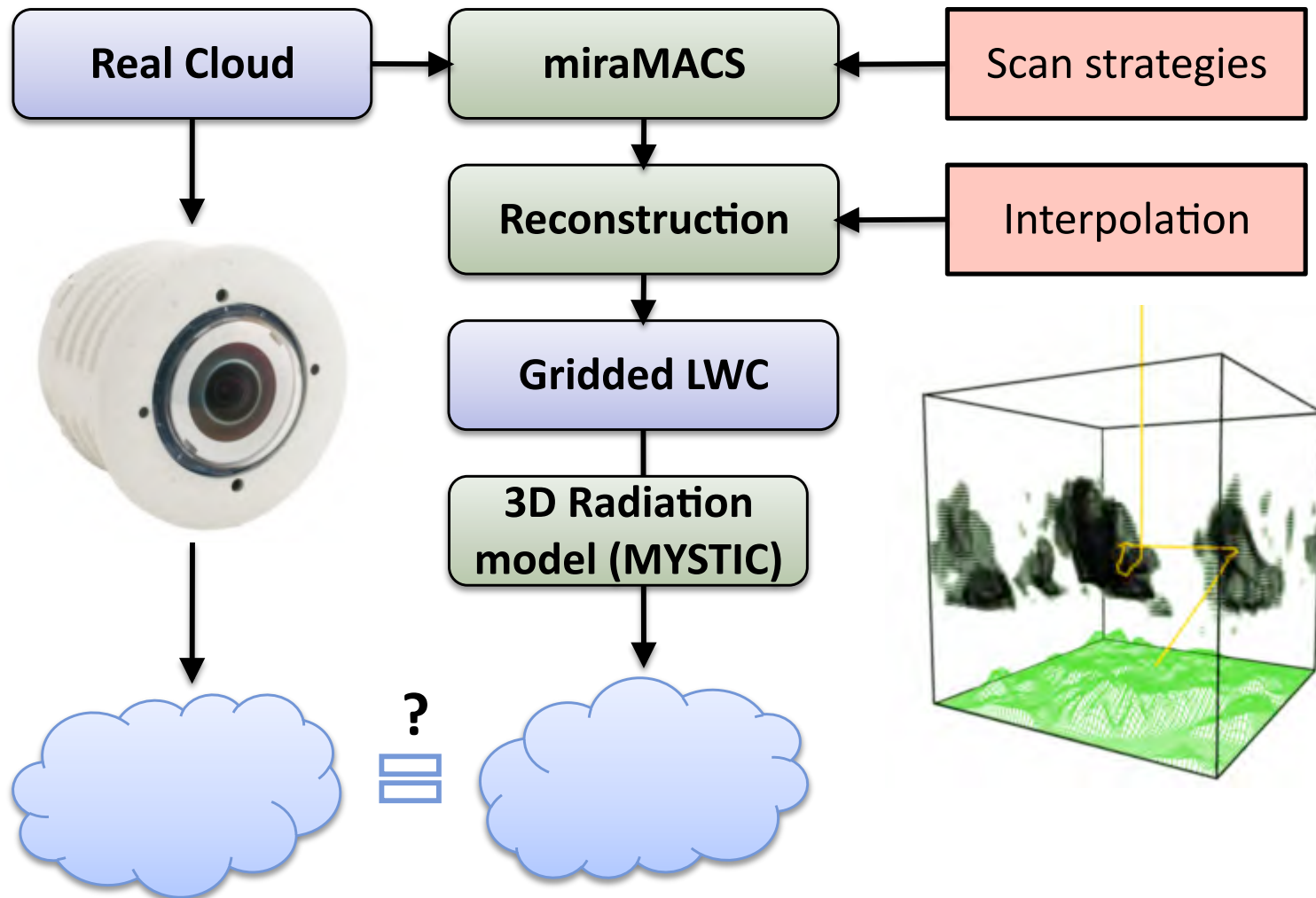
Sensitivity to scan resolution

Finding a compromise between scan resolution and scan duration



Application to real-world cases

Does the cloud reconstruction work in real-world cases?





Application to real-world cases

Does the cloud reconstruction work for real-world cases?

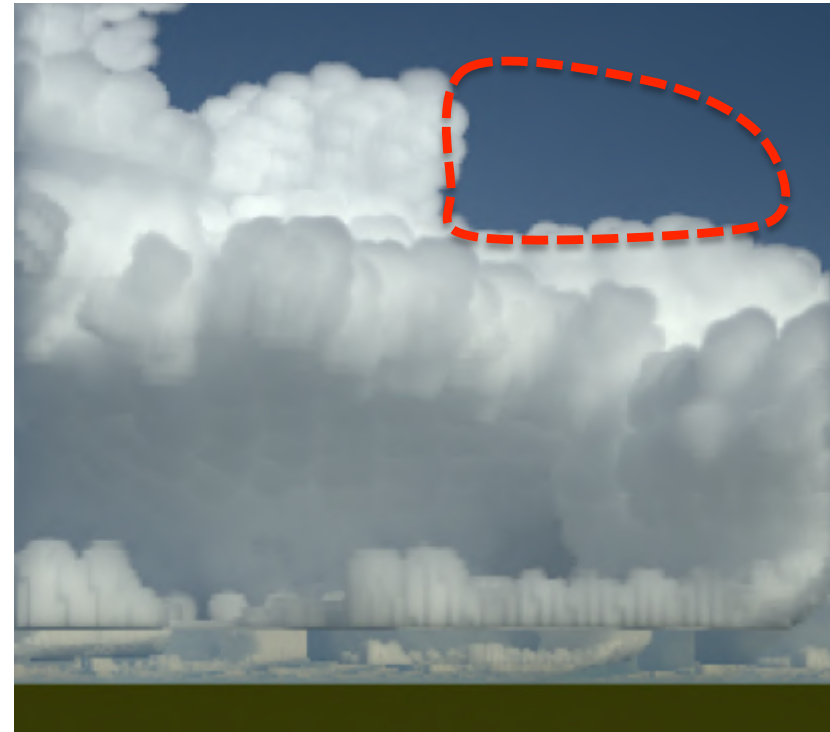


Application to real-world cases

Does the cloud reconstruction work for real-world cases?



miraMACS Reconstruction RGB (2013/07/25 15:28)



Conclusion and further work steps that need to be done:

- Cloud reconstruction from cloud radar measurements is possible!
- Matching cloud reconstructions with spectrometer measurements
- Incorporating both datasets into a synergistic retrieval

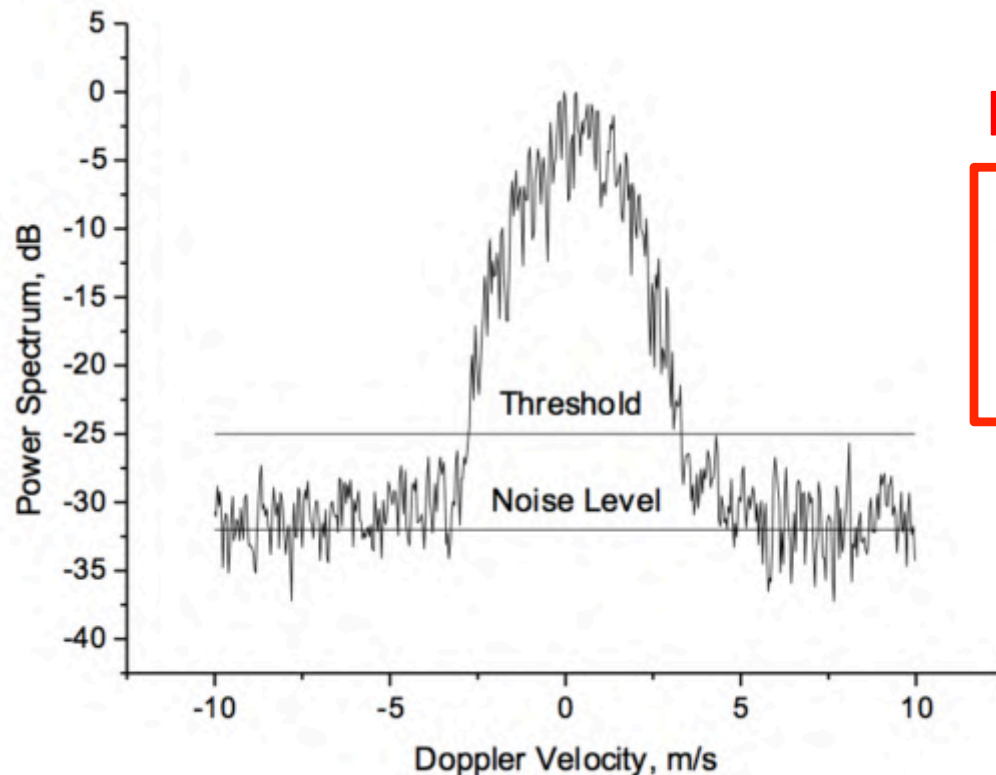
Cloud radar sensitivity

>> You simply have to integrate long enough, stupid! ... Really? <<

miraMACS – Nominal sensitivity

Influence of distance and droplet size

$$Z_{MIN} [dBZ] = C [dB] + 20 \log \left(\frac{H}{H_0} \right) + SNR_{MIN} [dB].$$



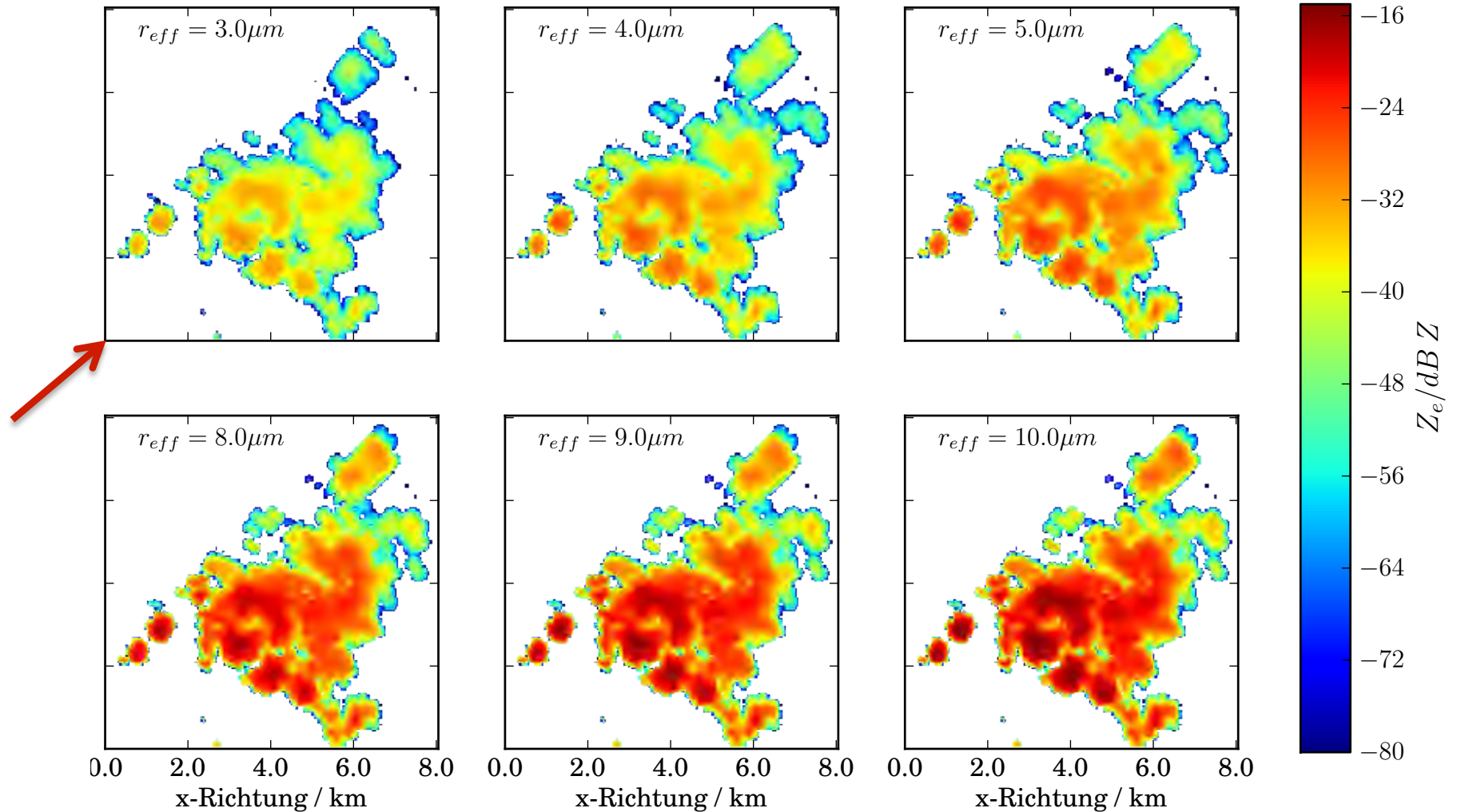
Hildebrand and Sekhorn (1974)

$$SNR_{MIN} = \frac{Q}{N_{FFT} \cdot \sqrt{K_{SUM}}} \ll 1,$$

$$SNR_{MIN} = -18.5 \text{ dB}$$

miraMACS – Nominal Sensitivity

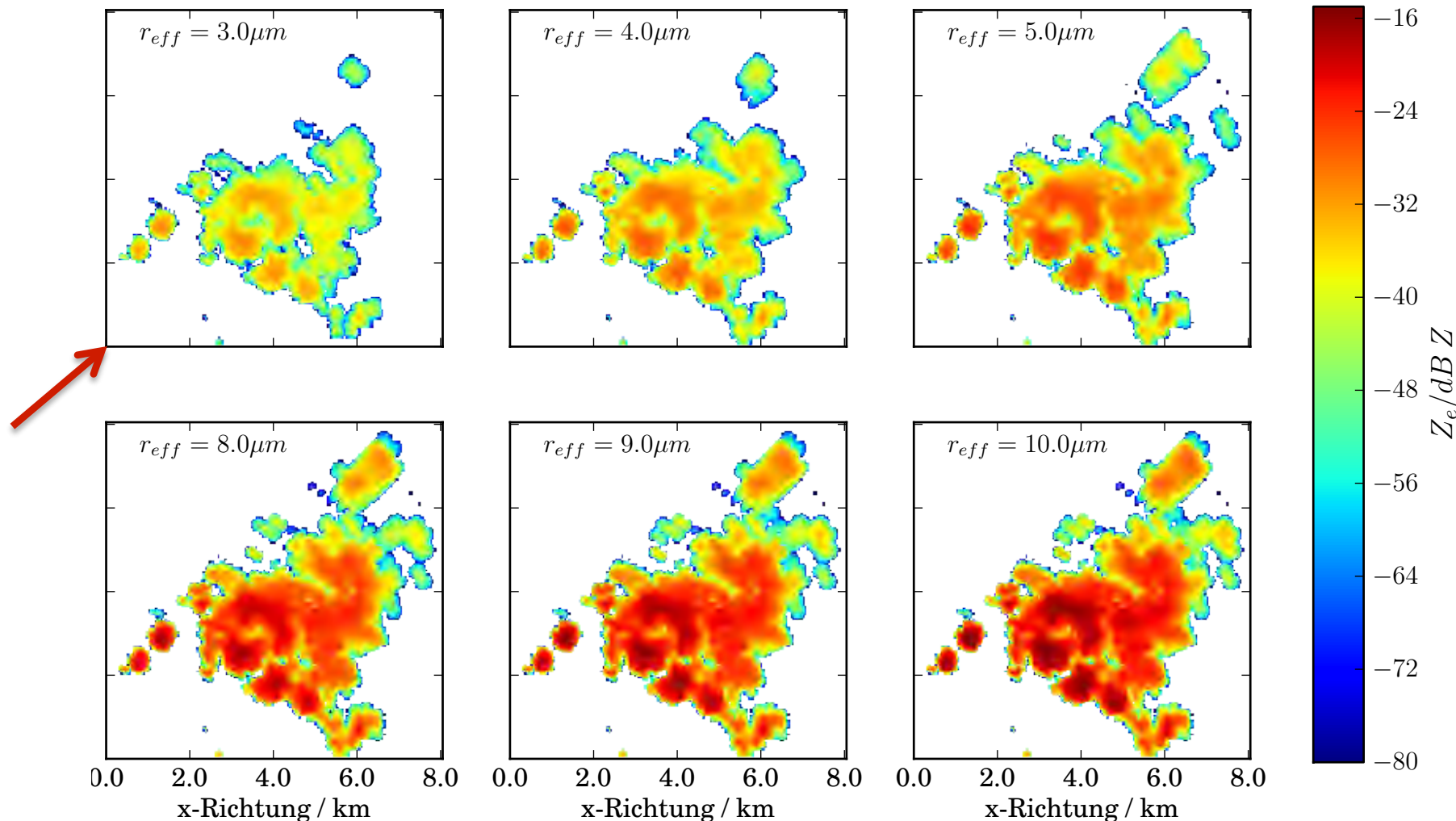
Influence of distance and droplet size



Distance between radar and lower left corner = 0 km

miraMACS – Nominal Sensitivity

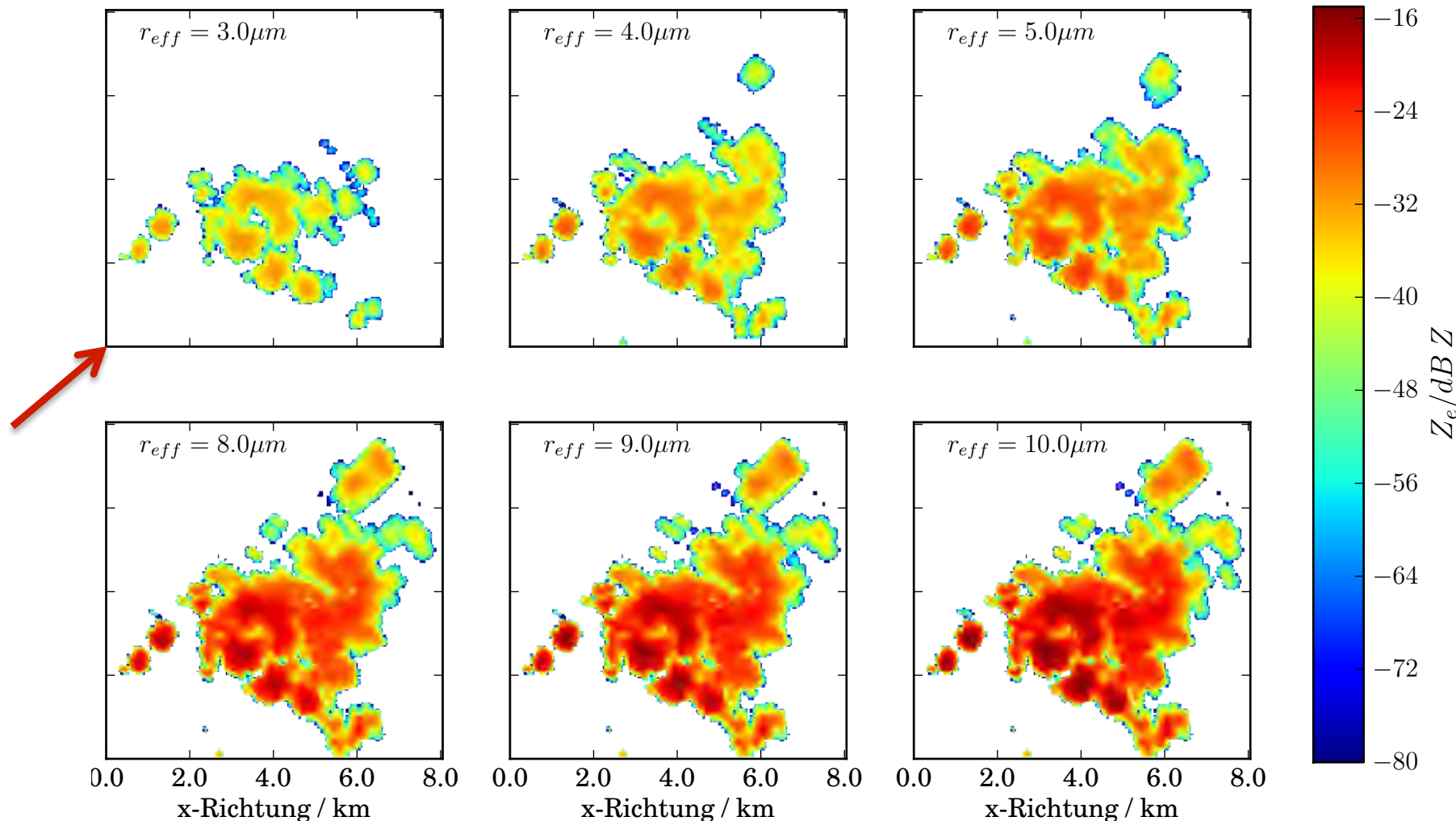
Influence of distance and droplet size



Distance between radar and lower left corner = 7 km

miraMACS – Nominal Sensitivity

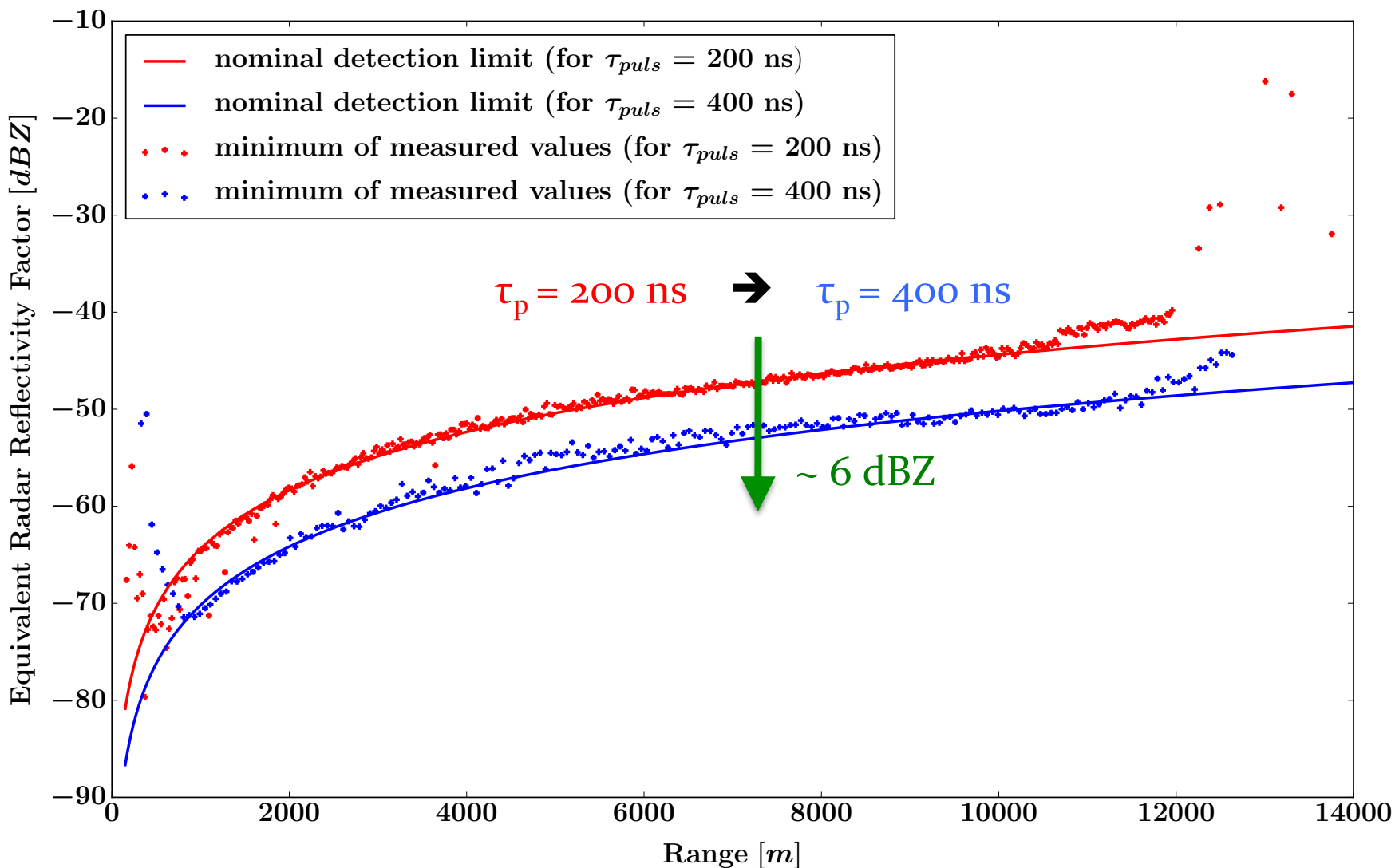
Influence of distance and droplet size



Distance between radar and lower left corner = 14 km

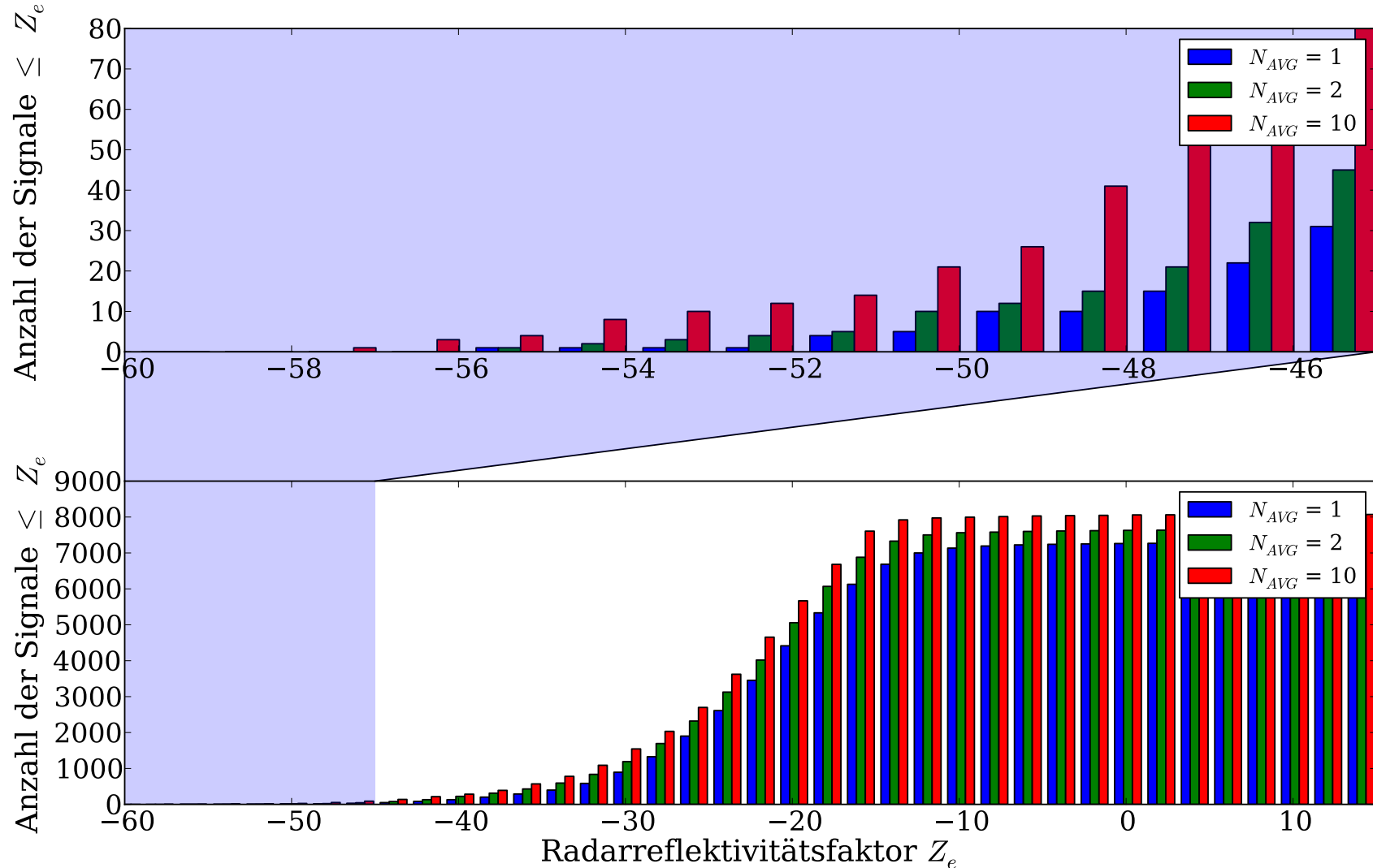
miraMACS – Measured Sensitivity

Influence of pulse width on cloud radar detection limit



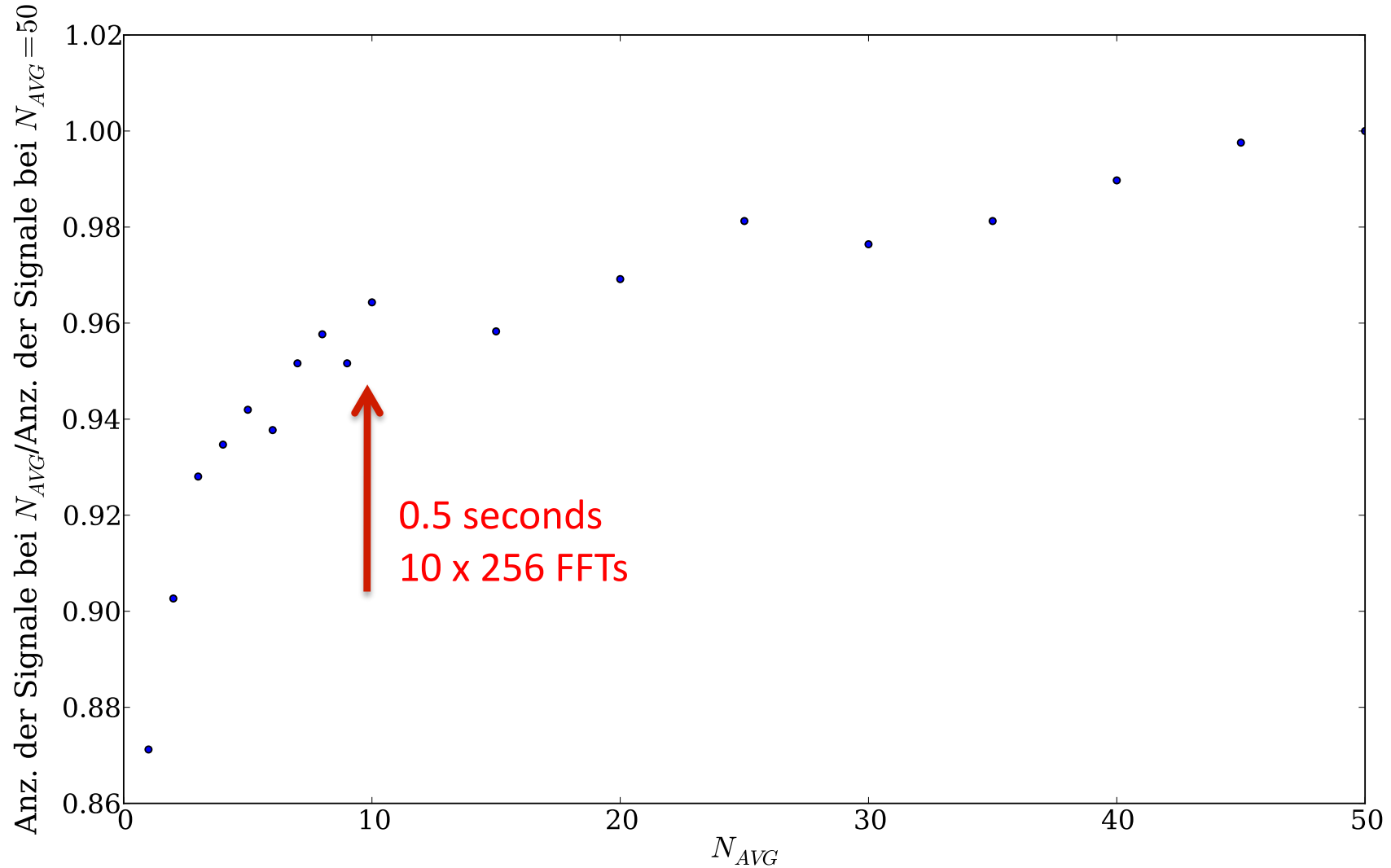
miraMACS – Measured Sensitivity

Influence of incoherent averaging length ($N_{FFT}=256$)



miraMACS – Measured Sensitivity

Influence of incoherent averaging length ($N_{FFT}=256$)

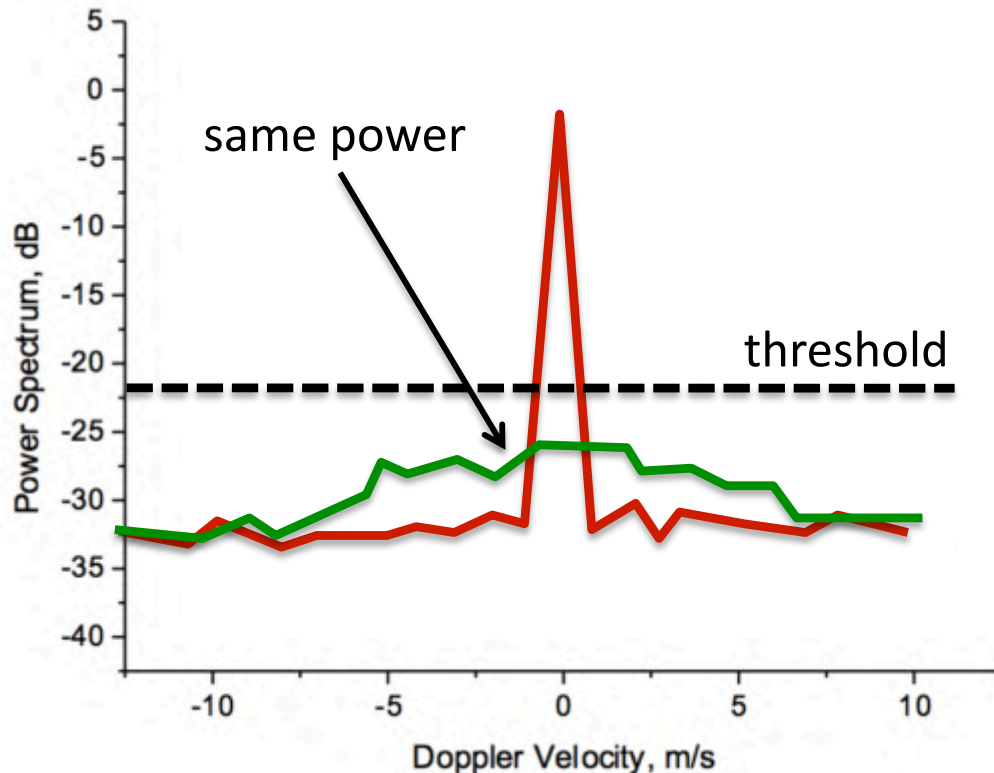


miraMACS – Missing Sensitivity?

Consequence of pulse width doubling and spectrum broadening

$$C_0 = \frac{1024 \ln 2 \lambda^2 K_B T_0}{\pi^3 c |K_w|^2} 10^{18} \frac{L F_N}{G_0^2 \theta_0^2} \frac{F_0 H_0^2}{P_{TAV0} \tau_0}$$

$$Z_e = C_0 \left(\frac{H}{H_0} \right)^2 \frac{F}{F_0} \frac{\tau_0 P_{TAV0}}{\tau P_{TAV}} SNR$$



Narrow Peak

$$P_{SnMin} = \frac{P_N Q}{\sqrt{N_{FFT} f_{PRF} T_{inCo}}}$$

Broad Peak

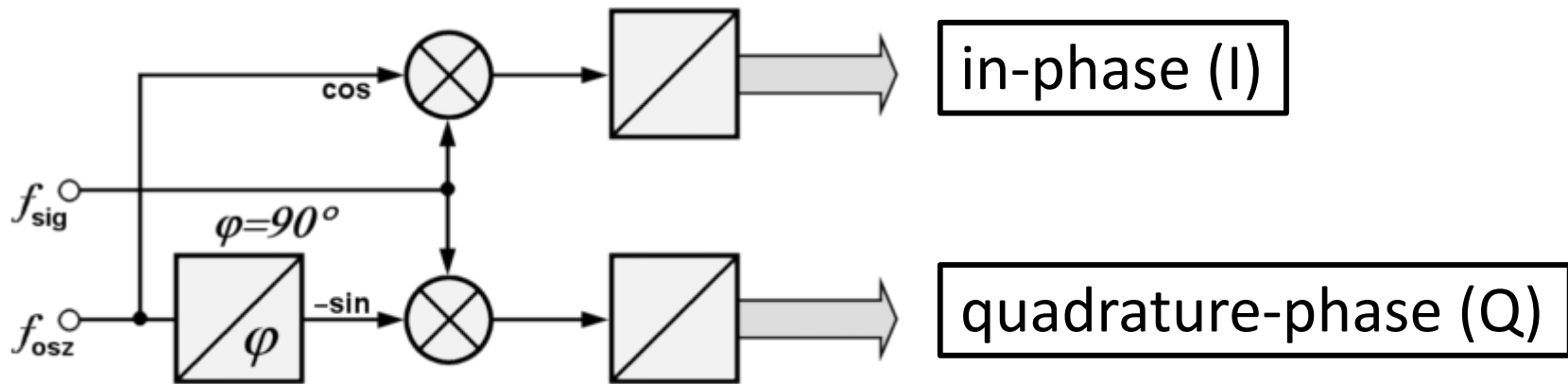
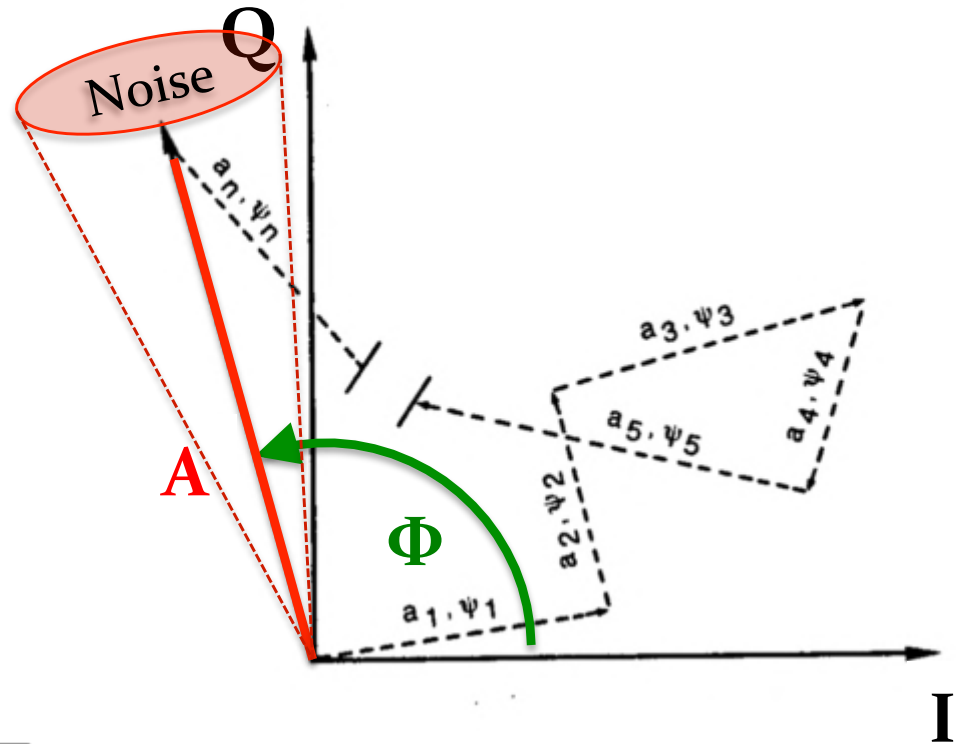
$$P_{SnMin} = \frac{P_N Q D_{Sn} \sqrt{N_{FFT}}}{\sqrt{f_{PRF} T_{inCo}}}$$

IQ data – knowledge refresher

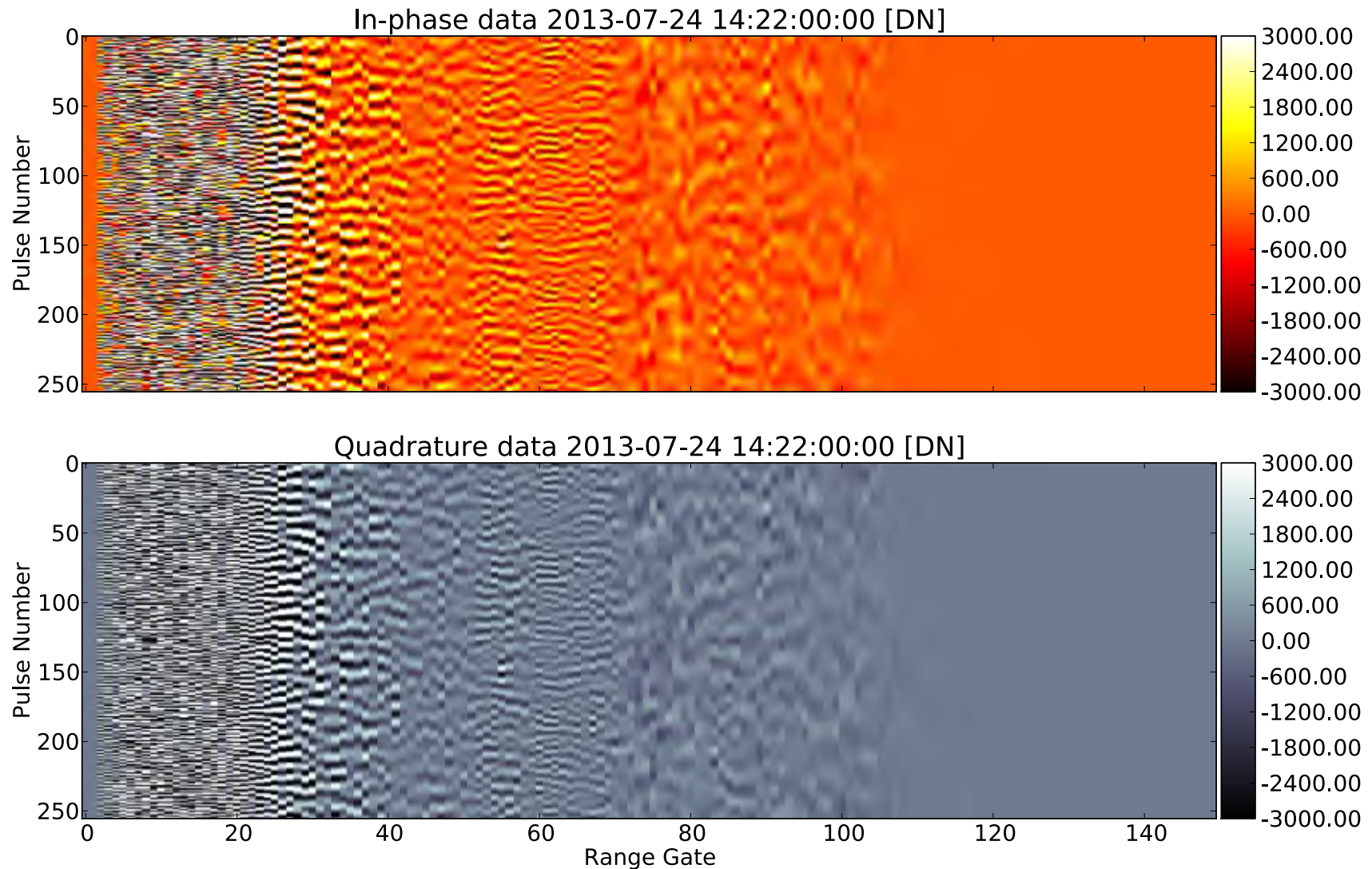
$$I = A \cos(\Phi) \quad Q = A \sin(\Phi)$$

$$A^2 = I^2 + Q^2$$

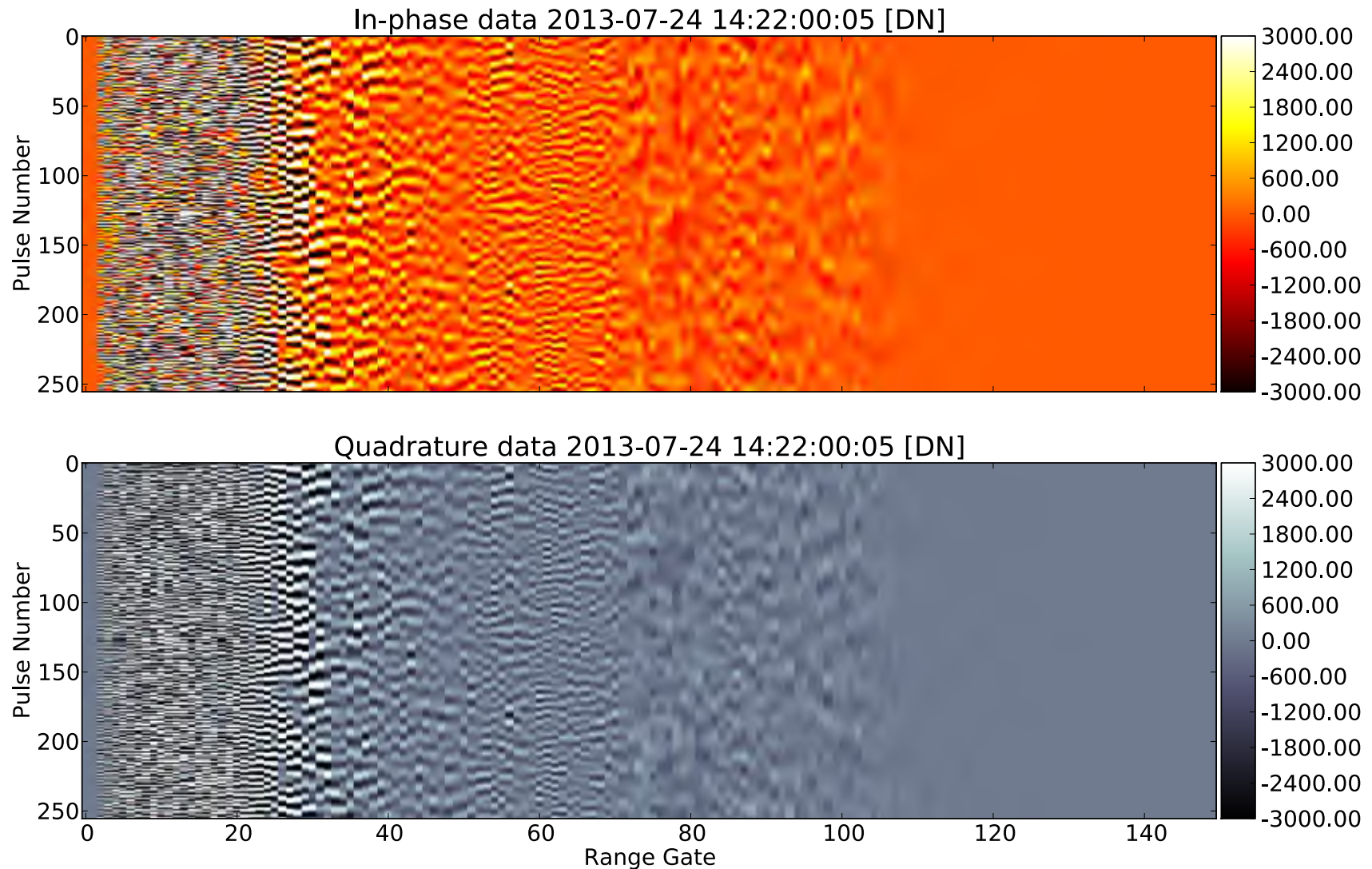
$$\Phi = \arctan(Q/I)$$



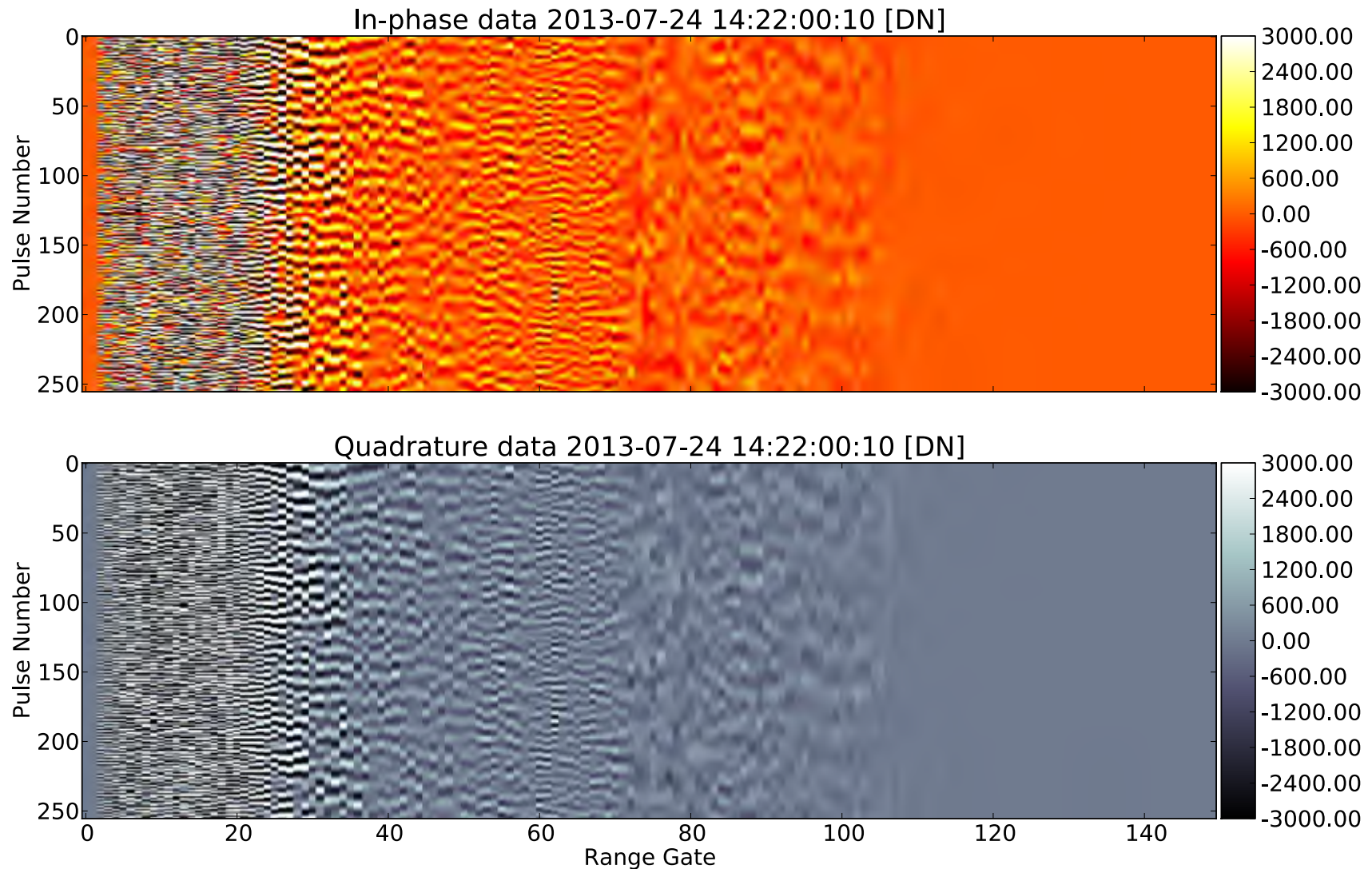
IQ data – timeseries (t=0ms)



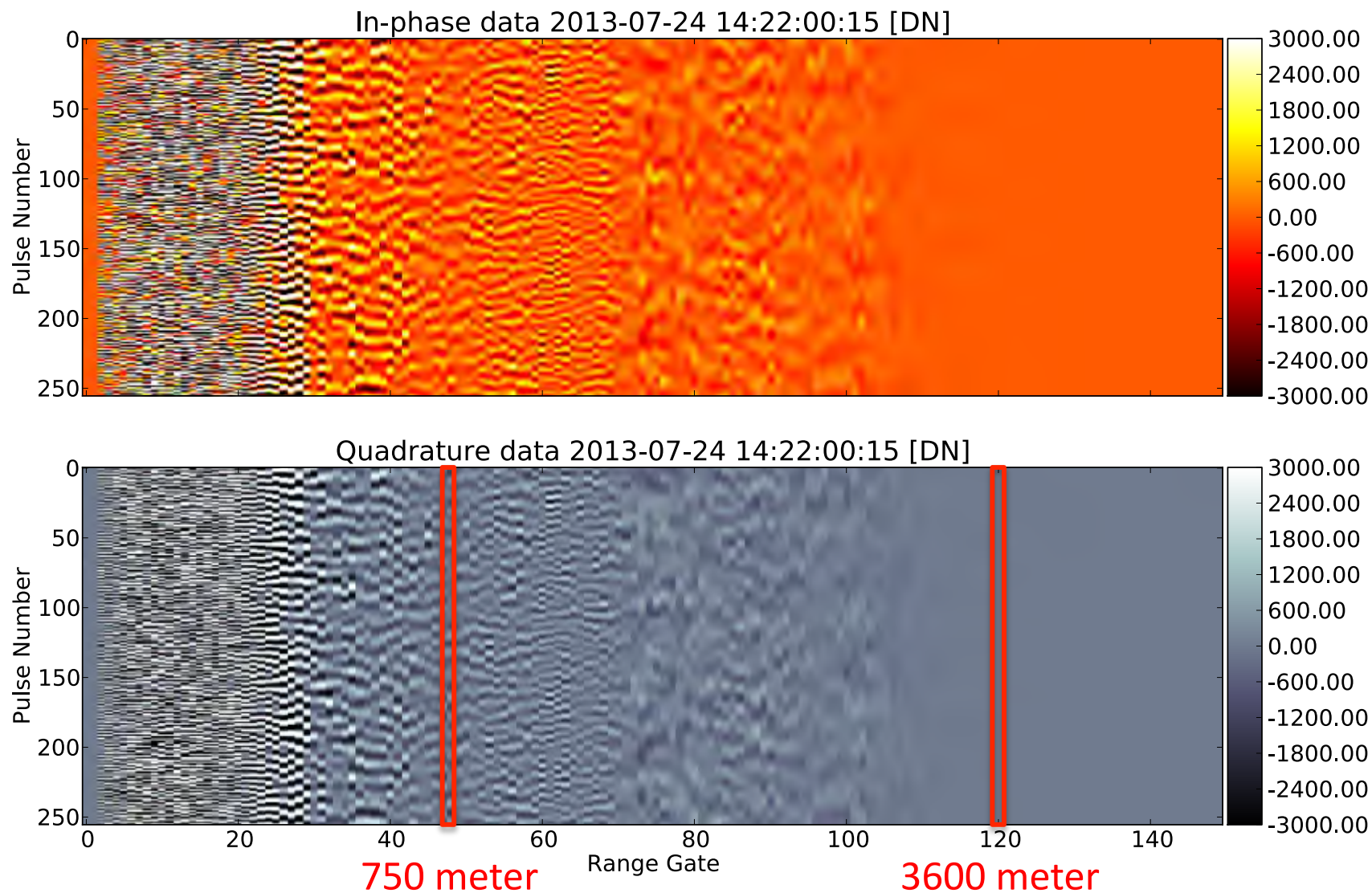
IQ data – timeseries (t=50ms)



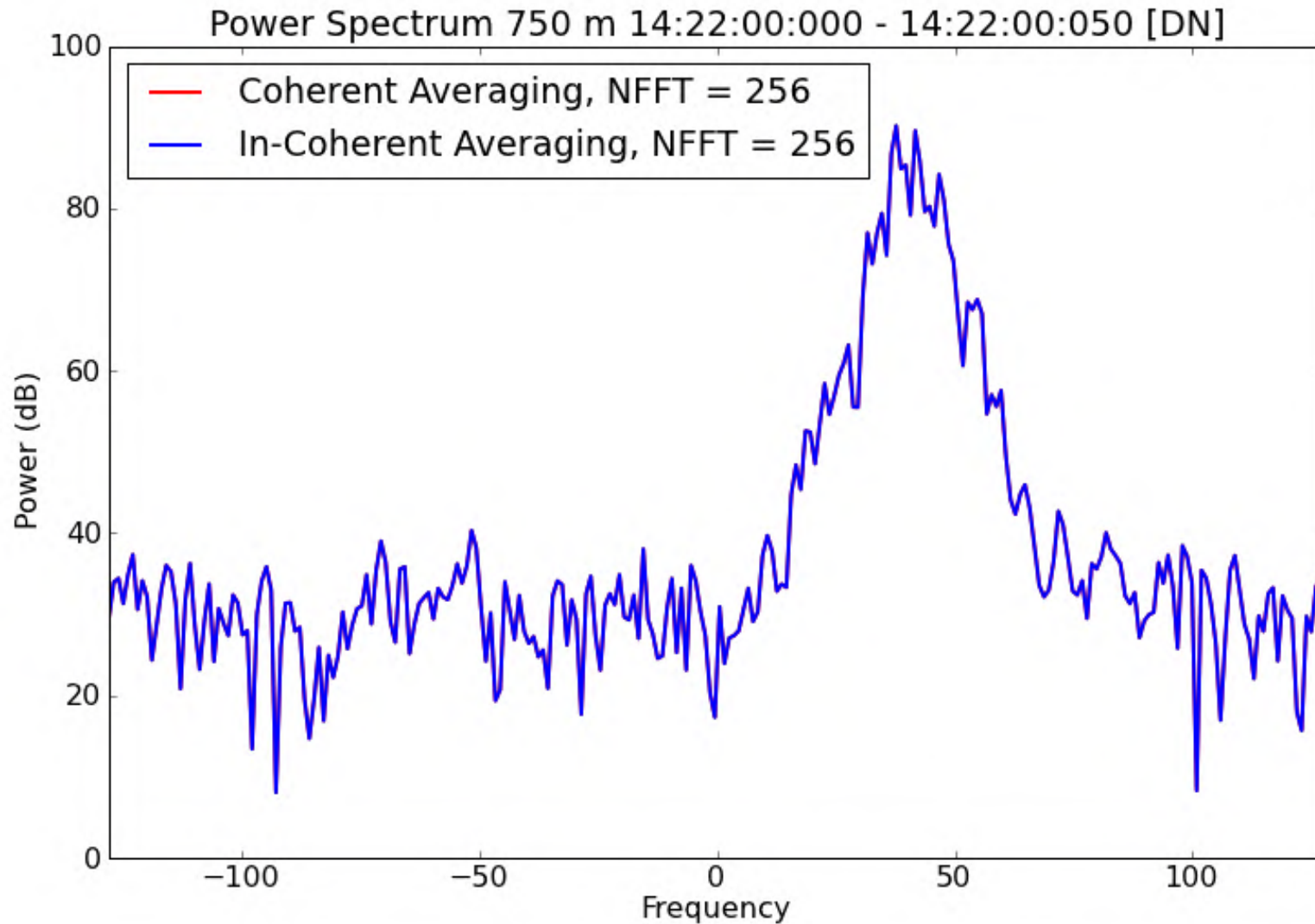
IQ data – timeseries (t=100ms)



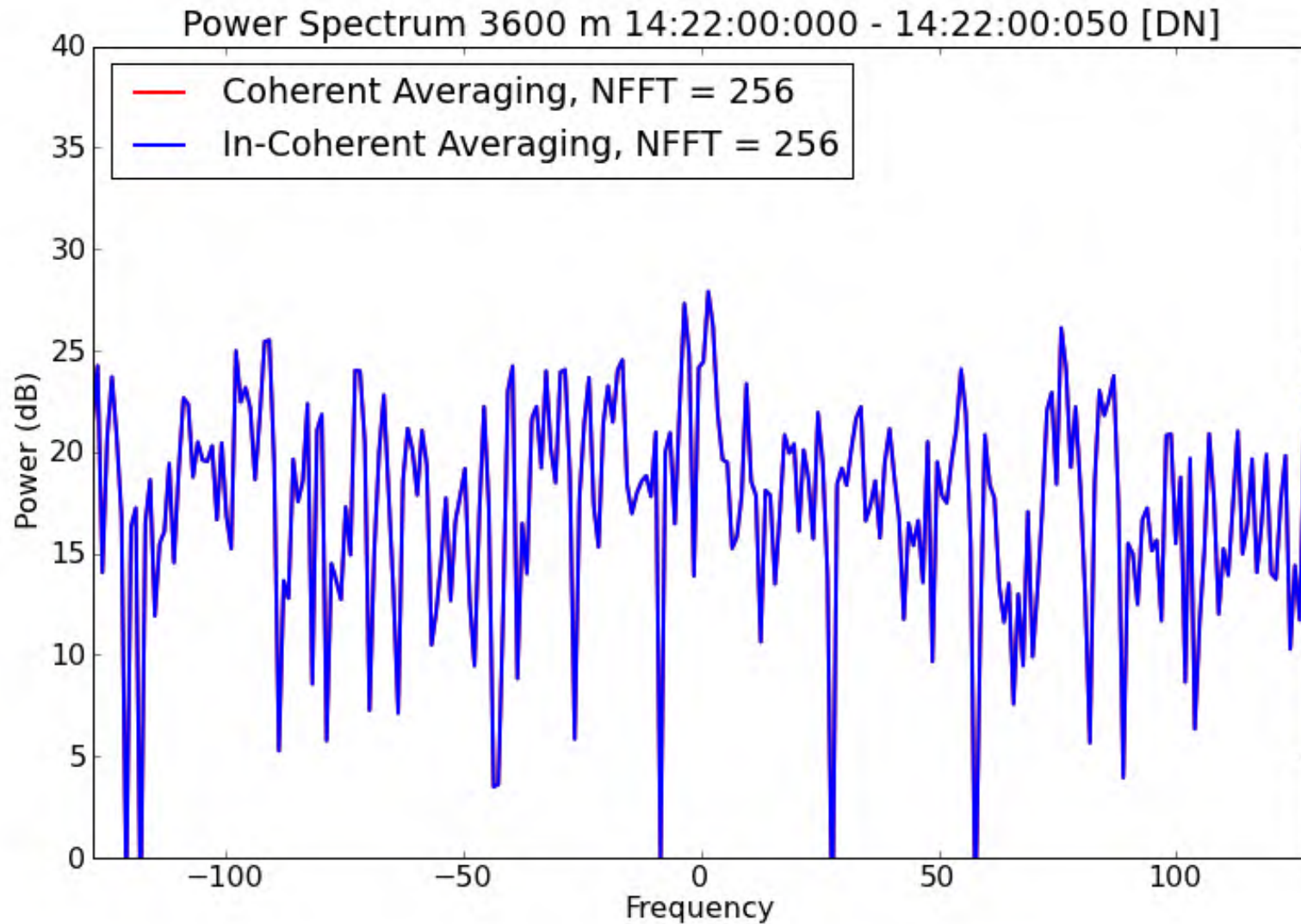
IQ data – timeseries (t=150ms)



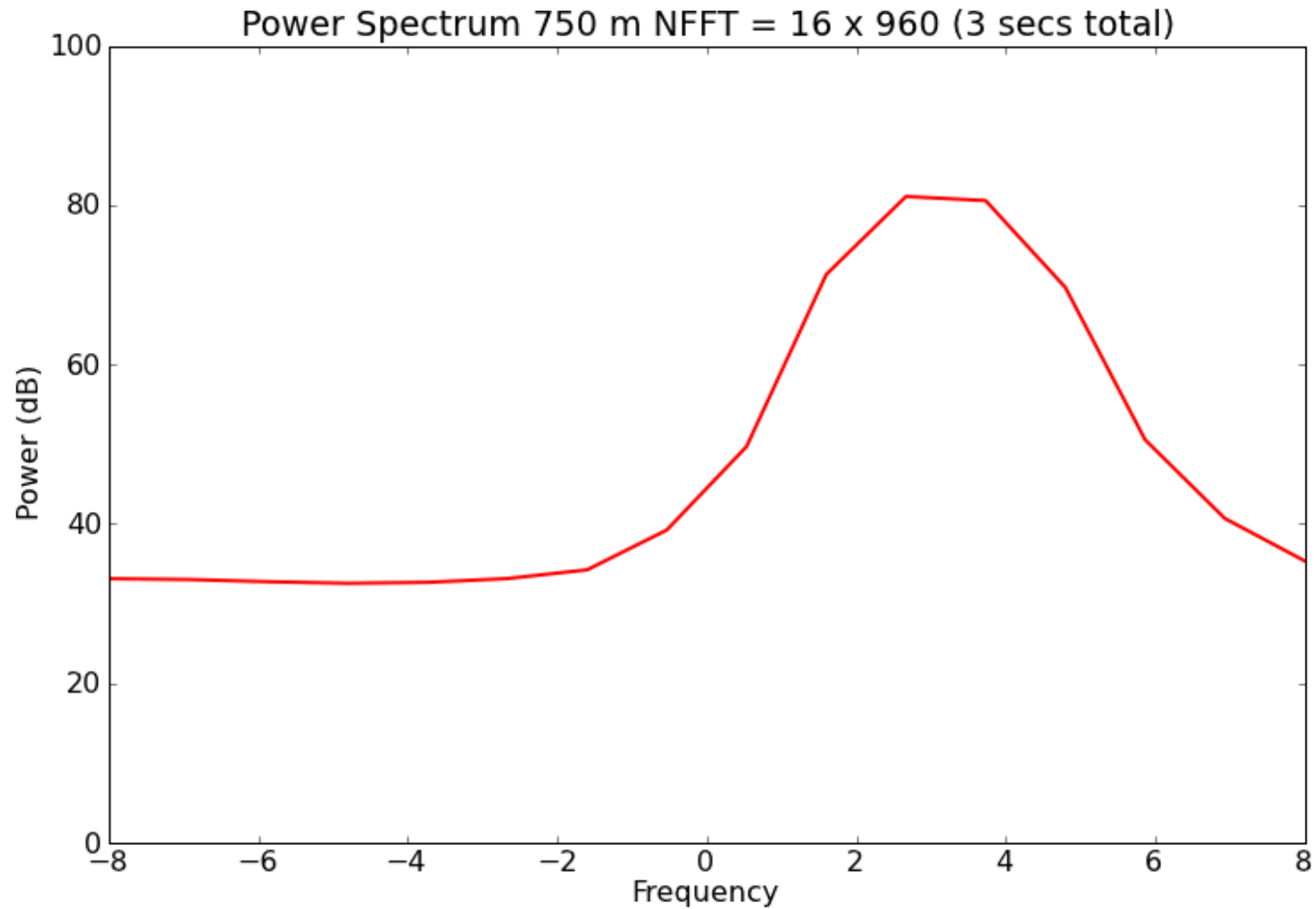
IQdata – In/Coherent averaging



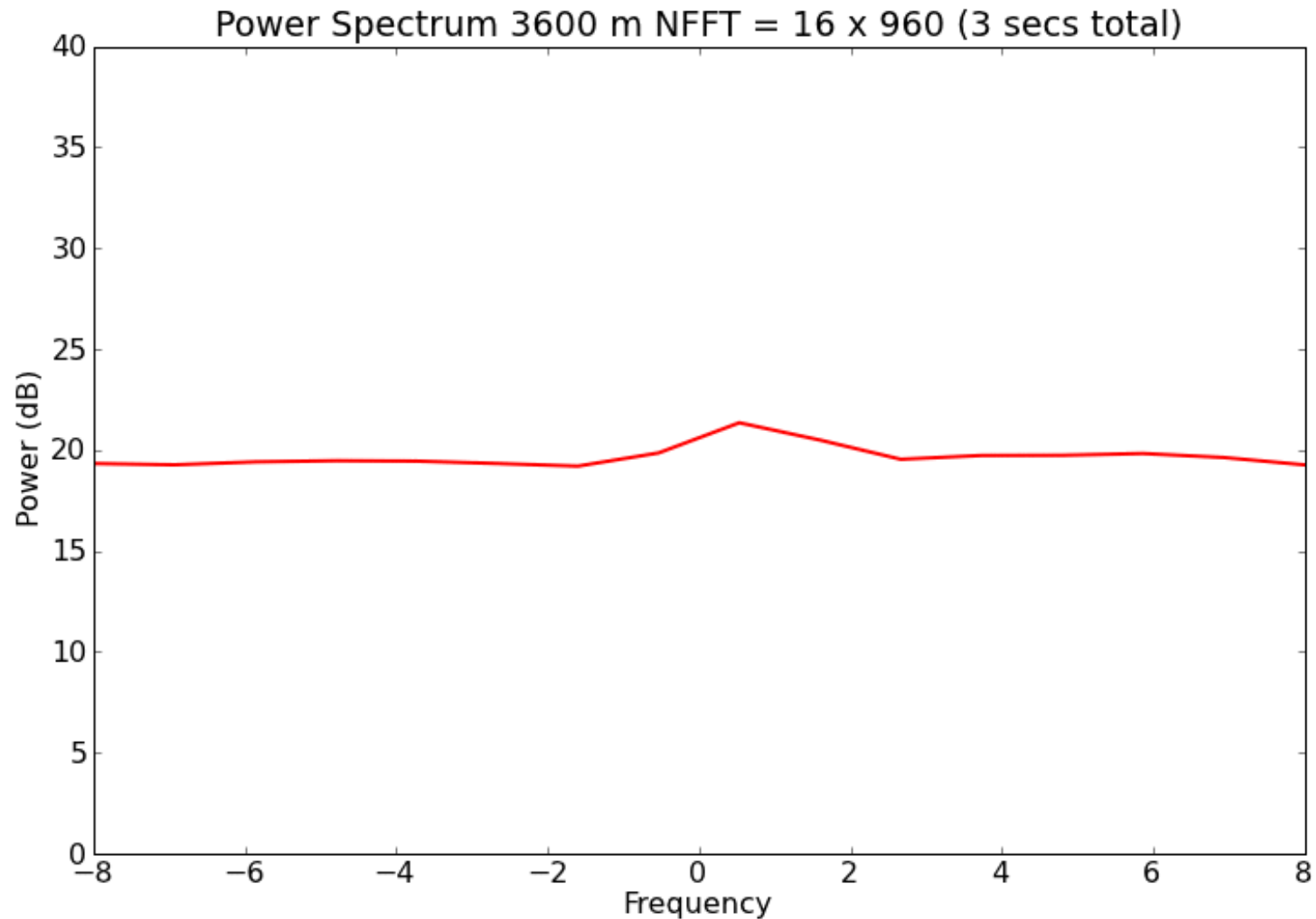
IQdata – In/Coherent averaging



IQdata – Decoherence Noise?



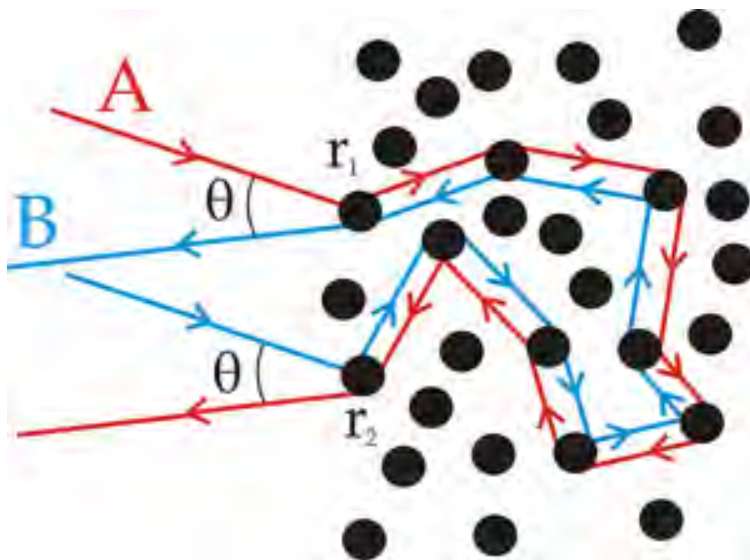
IQdata – Decoherence Noise?



Coherent (Back-)Scattering?

Kobayashi et al (2004):

For 95 GHz (3.1 mm) radar and water droplets of 1 mm diameter and a density of 5000 m^{-3} backscattering should increase by 1 - 2 dB.



→ Christian Pause (PhD Topic)

Argyrouli et al. (2012):

The clustering of particles inside the cloud volume results in a radar response deviating from the one predicted by the standard radar theory. [...] Therefore, the radar reflectivity sensitivity of a ground-based cloud radar may **not be sufficient** for detecting backscattered signals from water clouds.

Erkelens et al. (2001):

Coherent particle scattering can considerably **enhance** the reflections [...]. In parts of cumulus clouds coherent scattering from droplets may be a dominating scattering mechanism [due to droplet concentration fluctuations]



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