



# Clouds in Data Assimilation (DA)

Olaf Stiller, DWD

- Clouds in the atmosphere and NWP models
- Assimilation in cloudy air
  - Ensemble Kalman Filter vs. Variational DA
  - Cloud screening
  - Assimilation of cloudy radiances

# This is not covered in this talk:



- Cloud radars/lidars
  - ground based
    - cloud radar/lidar networks (research facilities)
    - ceilometers (nadir pointing, height of lower cloud edge)
  - space based (research satellites/missions)
    - A Train (Cloudsat/Calipso)
    - Earthcare mission (start 2013 ???)
  
- Assimilation of precipitation
  - latent heat nudging
  - in 4D Var (directly)
  
- Retrieval vs Radiances (raw-data)



# What is covered?

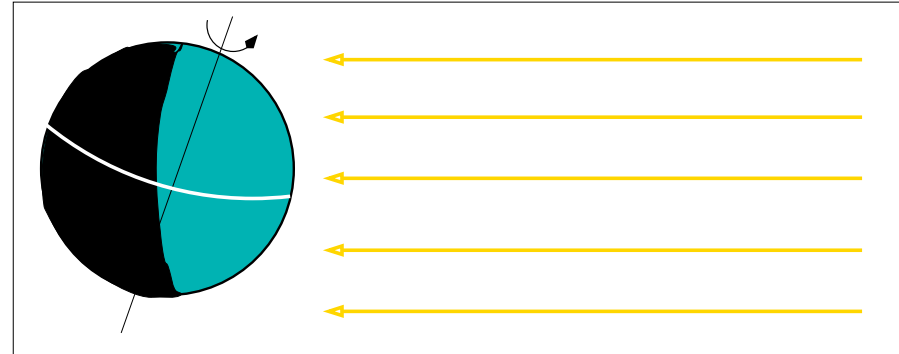


- Clouds
  - stability and clouds (why are clouds in the atmosphere?)
  - where do clouds occur?
  - clouds in NWP models
    - parametrisations
    - interactions and impact
- Assimilation in cloudy air
  - Ensemble Kalman Filter vs. Variational DA
  - Cloud screening
  - Assimilation of cloudy radiances
    - Infrared vs microwave
    - What have others done
    - A simplified model problem



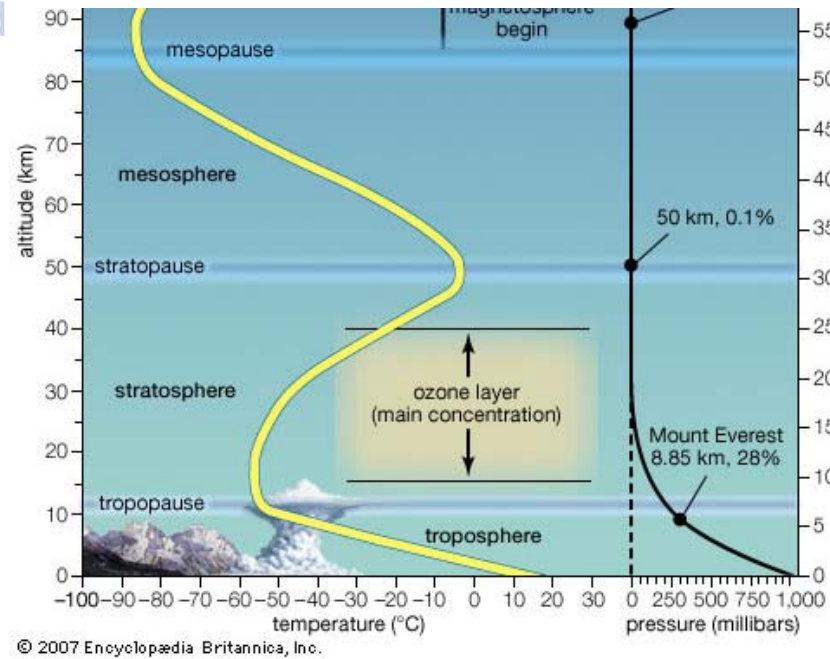
# Stability and Clouds

- The earth is in radiative equilibrium but
  - heating is strongest
    - at the ground
    - in the Tropics and the Summer hemisphere
  - air in the troposphere is constantly cooled (both day and night)



- This leads to instability
- Instability leads to convection
- Convection restores stability
- → almost neutral Temperature profile

❖ How can the troposphere get colder with height?  
Is this not unstable?



# Stability and Clouds

❖ How can the troposphere get colder with height?  
Is this not unstable?

Air that rises becomes colder

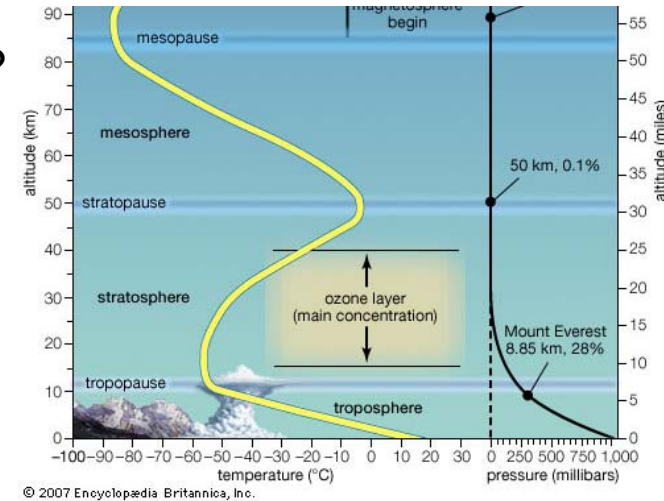
- pressure reduces → adiabatic expansion

$$T = \left(\frac{p}{p_0}\right)^\kappa T_0$$

- Potential Temperature is conserved

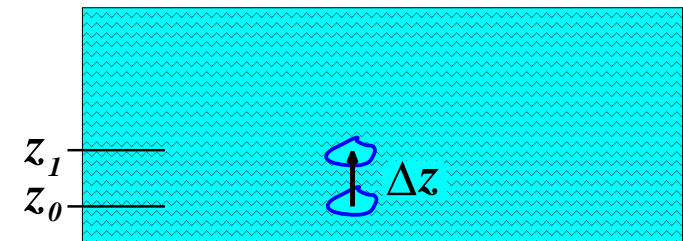
$$\theta \equiv \left(\frac{p}{p_0}\right)^{-\kappa} T = \text{const.}$$

dry adiab  
(neutral stability profile in dry air)



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*parcel lifted by a distance  $\Delta z$*



# Moisture variables



$q, q$	$\frac{\text{mass of H}_2\text{O vapour}}{\text{total mass of air}}$	specific humidity
$q_v, q_v$	$\frac{\text{mass of H}_2\text{O vapour}}{\text{mass of dry air}}$	water vapour mixing ratio
$q_l, q_l$	$\frac{\text{mass of liquid H}_2\text{O}}{\text{mass of dry air}}$	liquid cloud water mixing ratio
$q_i, q_i$	$\frac{\text{mass of frozen H}_2\text{O}}{\text{mass of dry air}}$	frozen cloud water mixing ratio
$q_c, q_c$	$q_l + q_i$	total cloud water mixing ratio
$q_T$	$q_v + q_l + q_i$	total water mixing ratio
$q_r, q_s$		mixing ratio of rain/snow

$q_{sat}$	$(T, p)$	saturation value of $q_v$ w.r.t. liquid
$q_{sat,i}$	$(T, p)$	saturation value of $q_v$ w.r.t. ice

$RH$	$= \frac{q_v}{q_{sat}}$	relative humidity
$RH_T$	$= \frac{q_T}{q_{sat}}$	total relative humidity



# Stability and Clouds

- Air that rises becomes colder  
(adiabatic expansion)

➤ dry adiabat

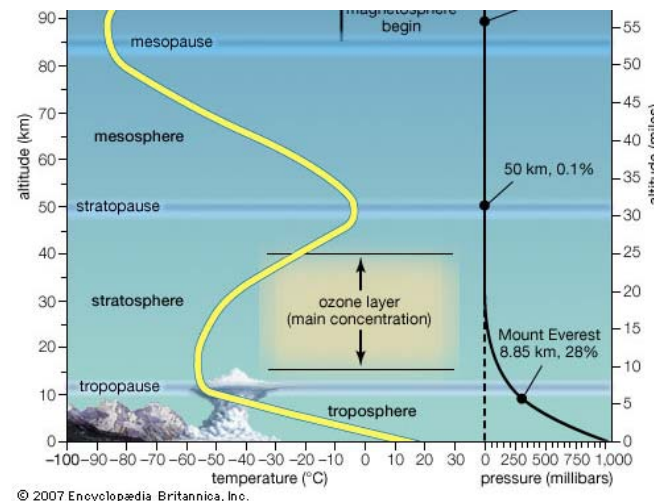
$$\theta \equiv \left( \frac{p}{p_0} \right)^{-\kappa} T = \text{const.}$$

- The impact of moisture:  
In cloudy air:  $q_{\text{sat}}$  decreases with height

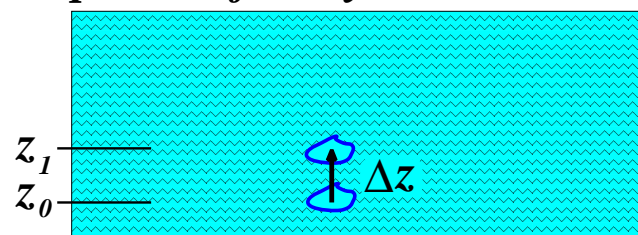
- condensation -> latent heat release
- potential Temperature increases with height

➤ moist adiabat

$$\frac{d}{dz} \theta = \Gamma > 0$$



*parcel lifted by a distance  $\Delta z$*

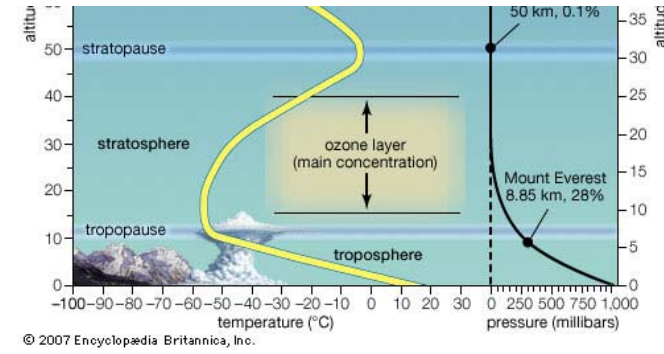


# Stability and Clouds

Air that rises becomes colder  
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➤ dry adiabat

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The impact of moisture:

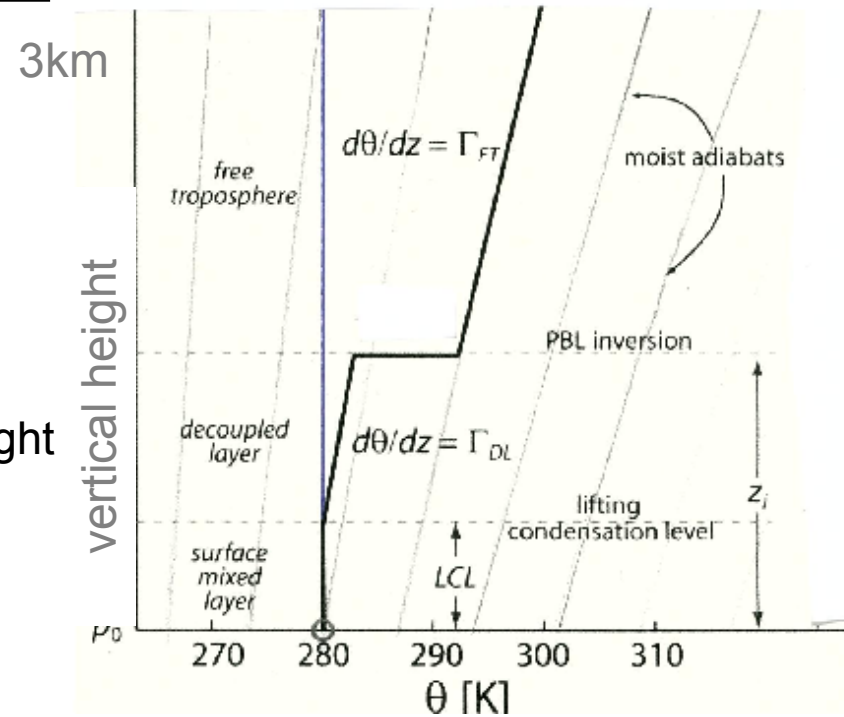
In cloudy air:  $q_{\text{sat}}$  decreases with height

- condensation -> latent heat release

➤ potential Temperature increases with height

➤ moist adiabat

$$\frac{d}{dz}\theta = \Gamma > 0$$





Convection typically stops near inversions or stable layers such as:

- tropopause (deep convection)
- Low level inversion (shallow convection)
- boundary layer (BL) top (dry convection or cloud topped BLs)
- freezing level (intermediate)

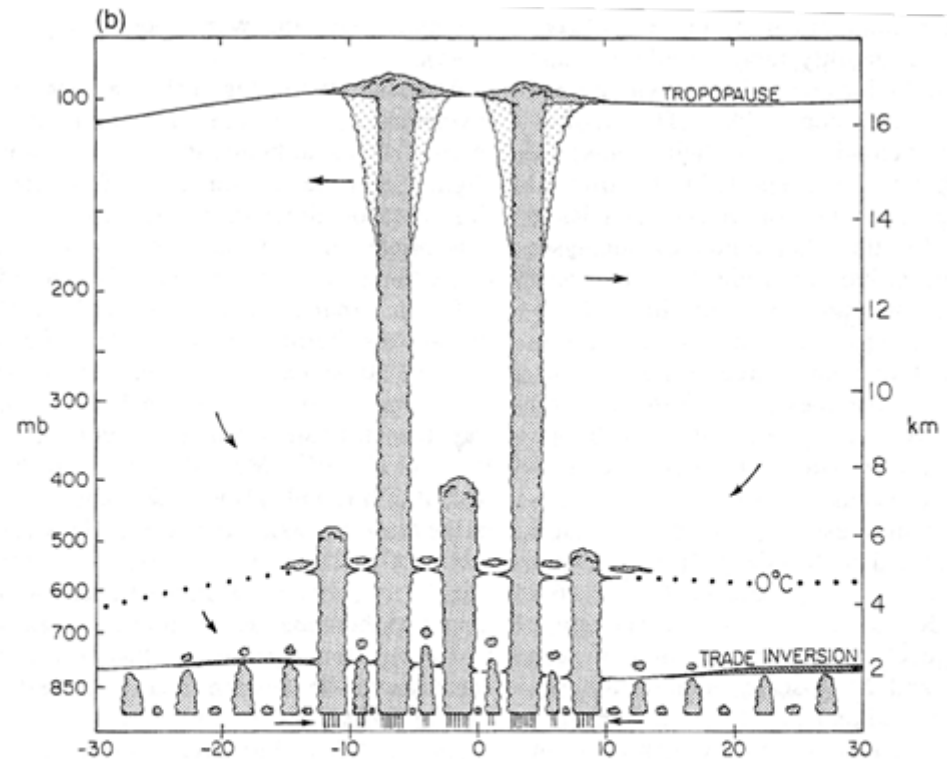
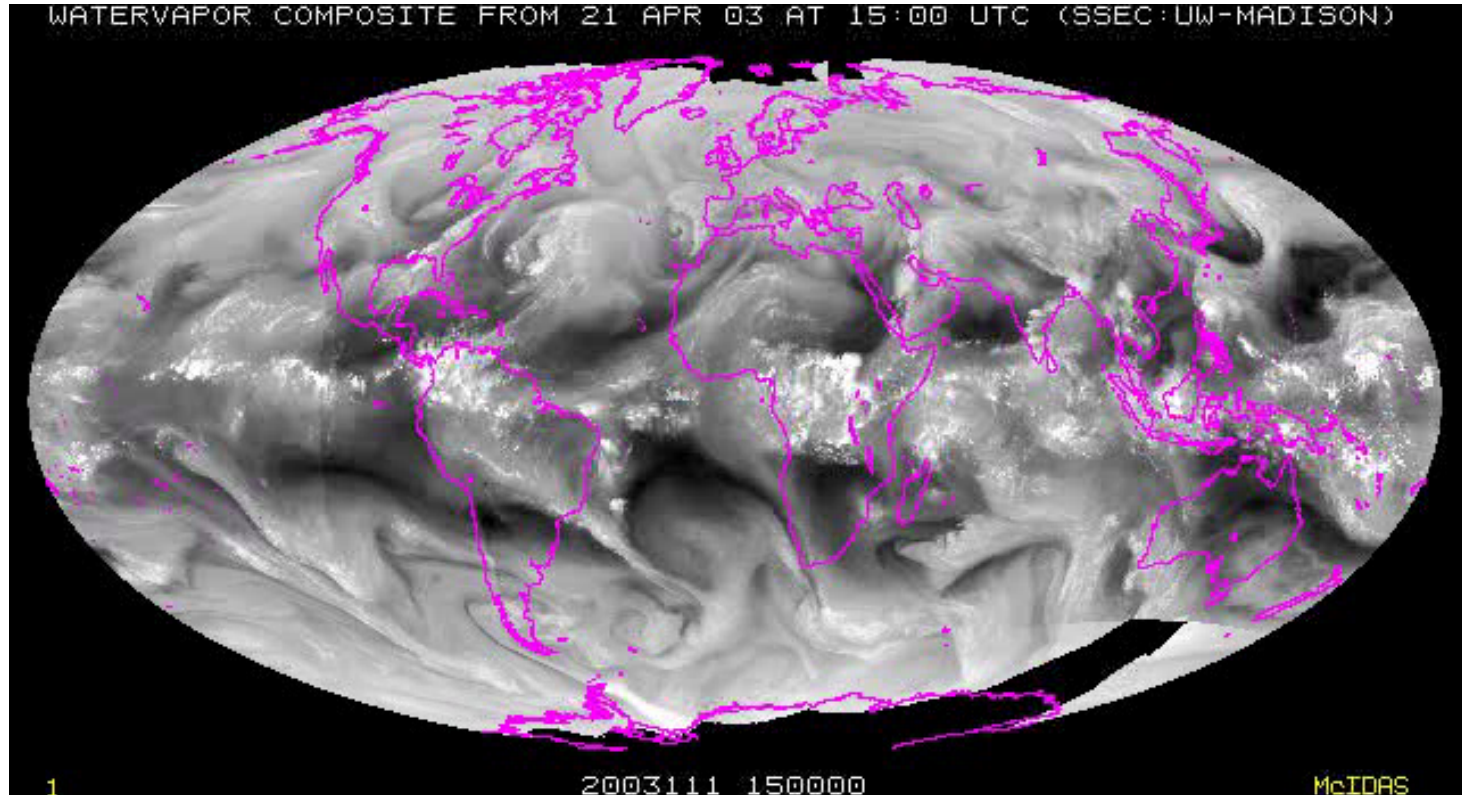


FIG. 13. (Continued) cloud types are indicated: shallow cumulus, cumulus congestus, and cumulonimbus. Within the shallow cumulus classification, there are two subdivisions: forced and active cumulus. Three stable layers are indicated: the trade inversion, the 0°C layer, and the tropopause. Shelf clouds and cloud debris near the trade and 0°C stable layers represent detrainment there. Cirrus anvils occur near the tropopause. Considerable overshooting of the trade and 0°C stable layers occurs in the equatorial trough zone. Arrows indicate meridional circulation. Although double ITCZ is indicated, representing IOP-mean, this structure is transient over the warm pool and a single ITCZ often exists.

Johnson et al., 1999, JCL

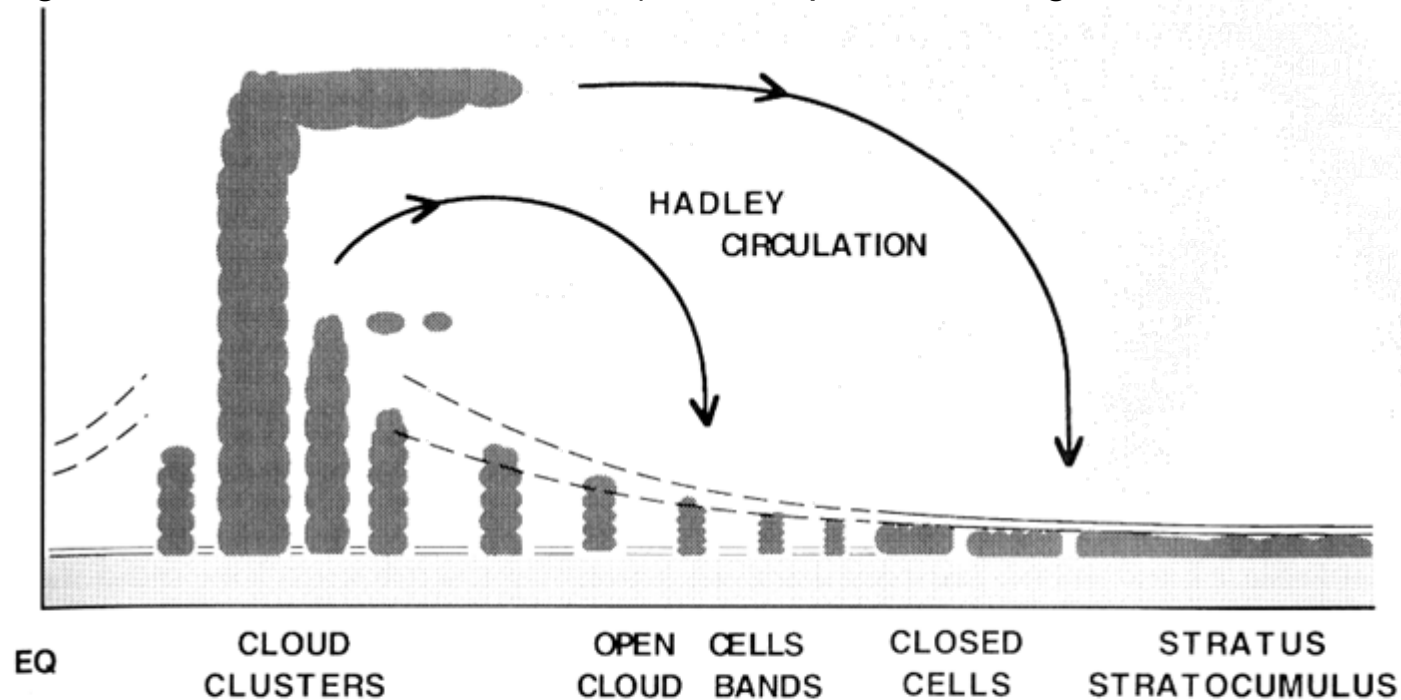
# Horizontal distribution of clouds

- The occurrence of convection and clouds is linked to both:
  - the temperature field (horizontally smoothed through buoyancy – gravity waves)
  - the moisture field (strong horizontal variations/gradients)



# Clouds are an important part of the general circulation

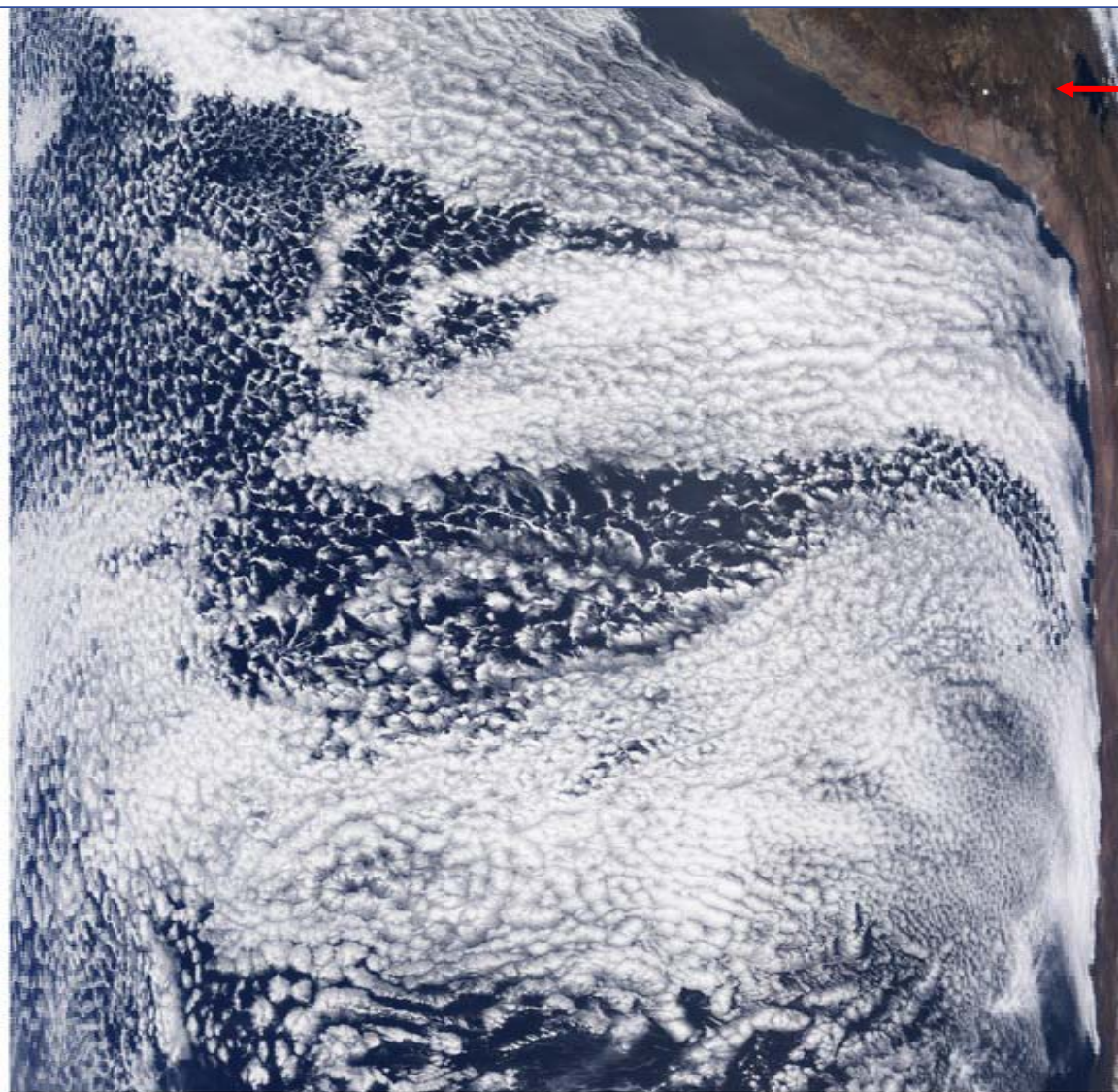
- Convection occurs where the atmosphere is most unstable
  - e.g. over warm waters, hot land (Inter-Tropical Convergence Zone – ITCZ)



**Figure 13** Schematic NE-SW cross section over the northeastern Pacific, summarizing typical observed cloud regimes. From right to left, the sea surface temperature increases and subsidence decreases. The stippled area is the PBL, the top of which is shown by the continuous and discontinuous double-stroked lines. The dashed lines above the cumulus clouds show an inversion layer, which is principally the trade wind inversion. (Redrawn from Arakawa, 1975.)



# Stratocumulus ... from Satellite

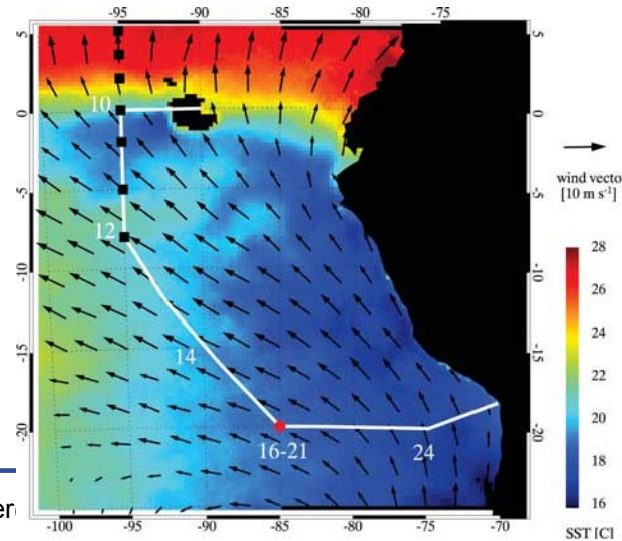


← Peru

MODIS true color  
(1540UTC, 20 Oct. 2001)

← Chile

SST & surface wind

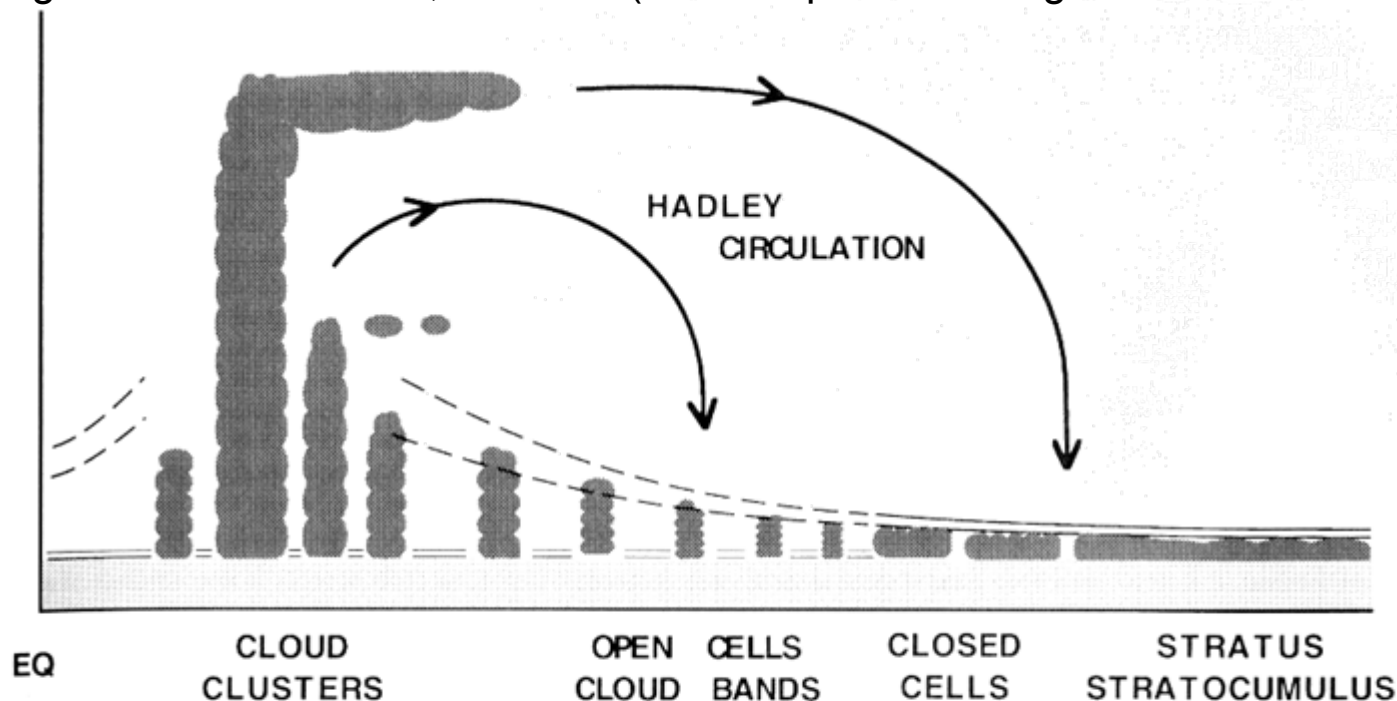


(Courtesy Martin Köhler)

Olaf.Stiller

# Clouds are an important part of the general circulation

- Convection occurs where the atmosphere is most unstable
  - e.g. over warm waters, hot land (Inter-Tropical Convergence Zone – ITCZ)

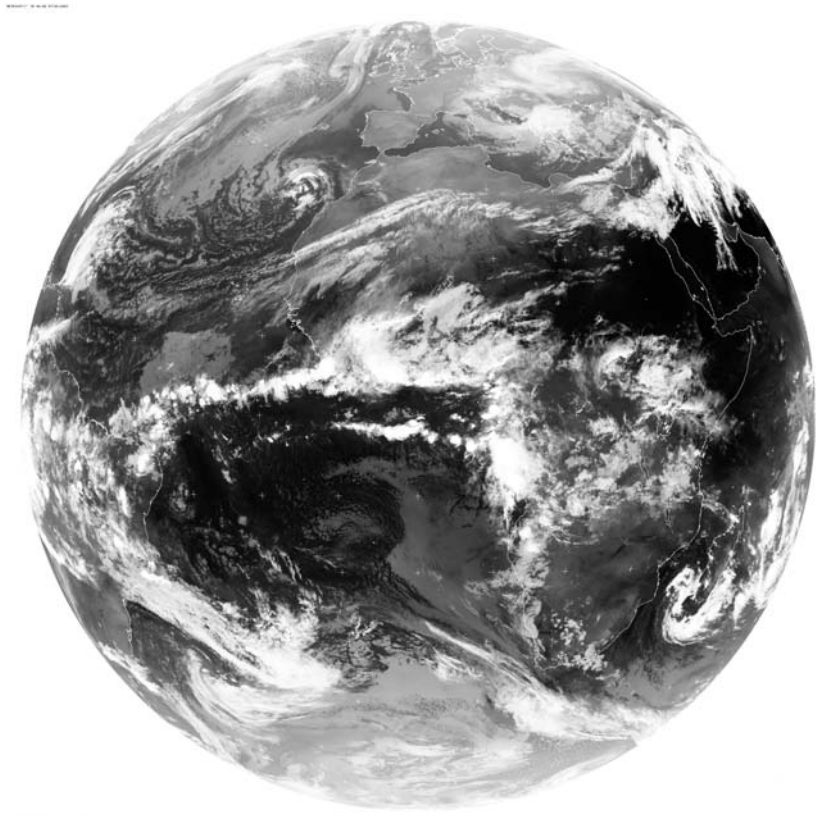


**Figure 13** Schematic NE-SW cross section over the northeastern Pacific, summarizing typical observed cloud regimes. From right to left, the sea surface temperature increases and subsidence decreases. The stippled area is the PBL, the top of which is shown by the continuous and discontinuous double-stroked lines. The dashed lines above the cumulus clouds show an inversion layer, which is principally the trade wind inversion. (Redrawn from Arakawa, 1975.)



# Geographical distribution of deep convection

- Convection occurs where the atmosphere is most unstable
  - e.g. over warm waters, hot land (Inter-Tropical Convergence Zone – ITCZ)
  - sea-land interaction (e.g. monsoon)
  - large scale lifting (embedded convection)
    - equatorial waves
    - orographic flows
    - extra-tropical storms (baroclinic instability)
  
- Non convective clouds are formed through
  - large scale lifting
  - radiative cooling (e.g. fog)



IR GOES METEOSAT 7/04/2003

# Clouds formed in the extra tropics at warm/cold fronts

- Non convective clouds are typically formed as air from warm fronts is lifted over colder air
- Air lifted at cold fronts typically leads to convection

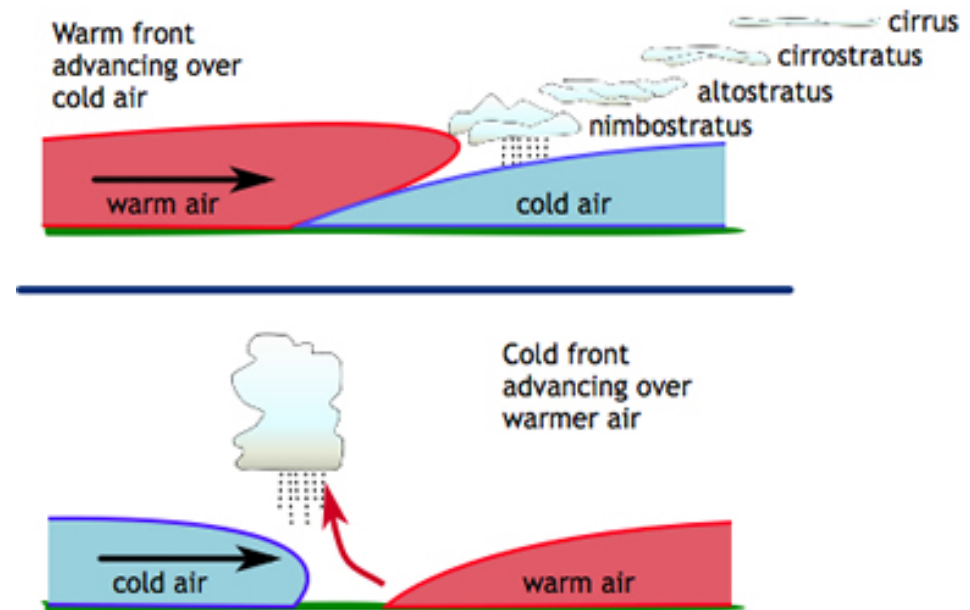


Image courtesy of Windows to the Universe



- clouds occur in different parametrizations:
  - Convection scheme (convective clouds)
    - deep convection
    - shallow convection
  - Boundary layer scheme (boundary layer clouds)
    - well mixed clouds at BL top
  - Cloud scheme (large scale clouds – non convective)
    - complex micro physics
      - liquid clouds (rain)
      - ice clouds (snow)
      - mixed phase







- Dynamical interaction of clouds
  - latent heat release
    - net latent heat release  $\cong$  surface precipitation
  - radiative cooling
    - cloud top cooling can be up to 7 degrees per hour
      - turbulent overturning and mixing within clouds (needs to be parametrized!)
    - cooling in clear air only about 2 degrees per day





- Cloud and convection parametrizations have a strong impact on the model climate and balance relationships in the model
  - stability (temperature profile)
  - moisture content
  - height of inversions
  - etc.
- Many of these relationships are fast (i.e., the model will tend towards such balances on short time scales)

## Problem for data assimilation

- The model may respond wrongly to the correct initial conditions
  - tends towards its own climate
  - “How can we initialize the model to respond correctly?”
- Bias correction
  - which part of the model bias should we try to correct? (If we knew it.)



# Some important things to keep in mind



- The temperature field is smoothed by buoyancy constraint
  - can be interpolated (e.g., to the location of an observation)
- The moisture field
  - is small scale / can have strong subgrid variations
    - interpolation very problematic
  - interaction with dynamics is strongly nonlinear (latent heat, radiative cooling)
- Clouds are an active part of the flow
  - it makes little sense to assimilate a cloud if it does not fit to the temperature and wind field
- Cloud and convection parametrizations contribute to the model climatology (which generally differs from that of the real world)
  - Model bias
  - It makes little sense to correct for model bias if it is related to a fast equilibrium



# Data assimilation in cloudy air

## The challenges



- How to .....
  - make sure observations are not contaminated by clouds?
    - cloud screening
    - “subtracting” cloud impact from the measurements
  - get cloud information from the observations?
  - profit from cloud information for improving the weather forecast?
  
- Problems and answers generally differ for different DA systems
  - variational DA (1D Var, 3D Var, 4D Var, ..)
  - Ensemble methods (Kalman Filter, ..)



- Both Ensemble KF and Var need **observation operators**

$$J(x) = \frac{1}{2} (x - x_b)^T \mathbf{B}^{-1} (x - x_b) + \frac{1}{2} (y - y_{mod})^T \mathbf{R}^{-1} (y - y_{mod})$$

$y$  : observation

$$y_{mod} = H(x)$$

$H$  : *generalized* observation operator

$$H_{obs}(\mathbf{x}) \rightarrow y_{mod}$$

$$H_1(\mathbf{x}) \rightarrow \tilde{\mathbf{x}} \quad \text{physics operator}$$

$$RTTOV(\tilde{\mathbf{x}}) \rightarrow y_{mod} \quad \text{radiative transfer model}$$

Example 4D Var:

$$H(x) = H_{obs} \cdot S [M(x)]$$

$M$  : time evolution operator (NWP model)

$S$  : interpolation to observation location

$H_{obs}$  : classical observation operator

$y_{mod}$  : model observations

$\mathbf{x}$  : standard model variables  
(changed by assimilation)

$\tilde{\mathbf{x}}$  : standard model variables  
+ **cloud variables**: e.g.,  $C_{fr}, P_{cldtop}$

# Ensemble KF vs Var



- Both need **observation operators**

- Var also needs linear and adjoint **obs operator**
- **obs operator** needs to be very robust and smooth

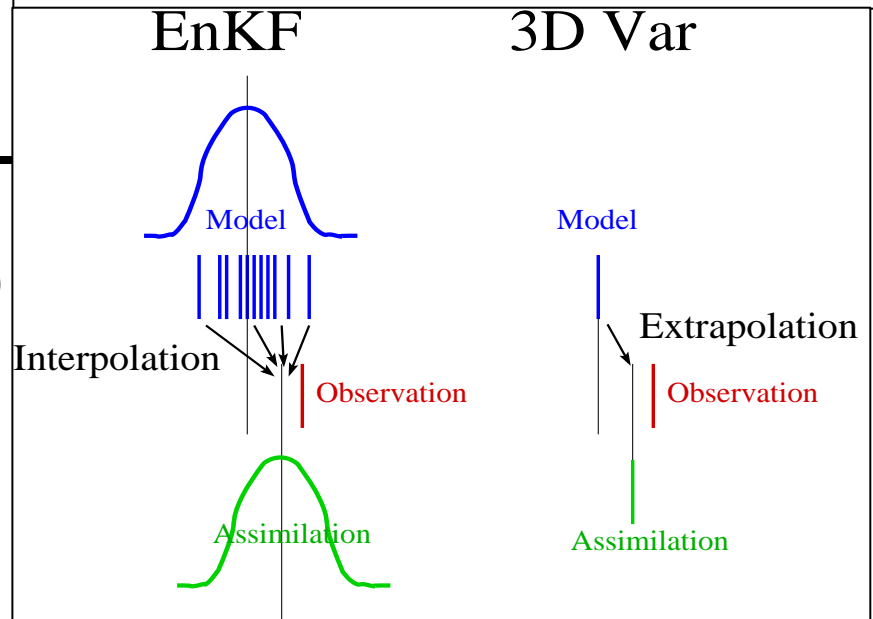
- EnKF uses a secant (not a tangent)
- Var can make several outer loops

$$H_{obs}(\mathbf{x}) \rightarrow y_{mod}$$

$$H_1(\mathbf{x}) \rightarrow \tilde{\mathbf{x}} \quad \text{physics operator}$$

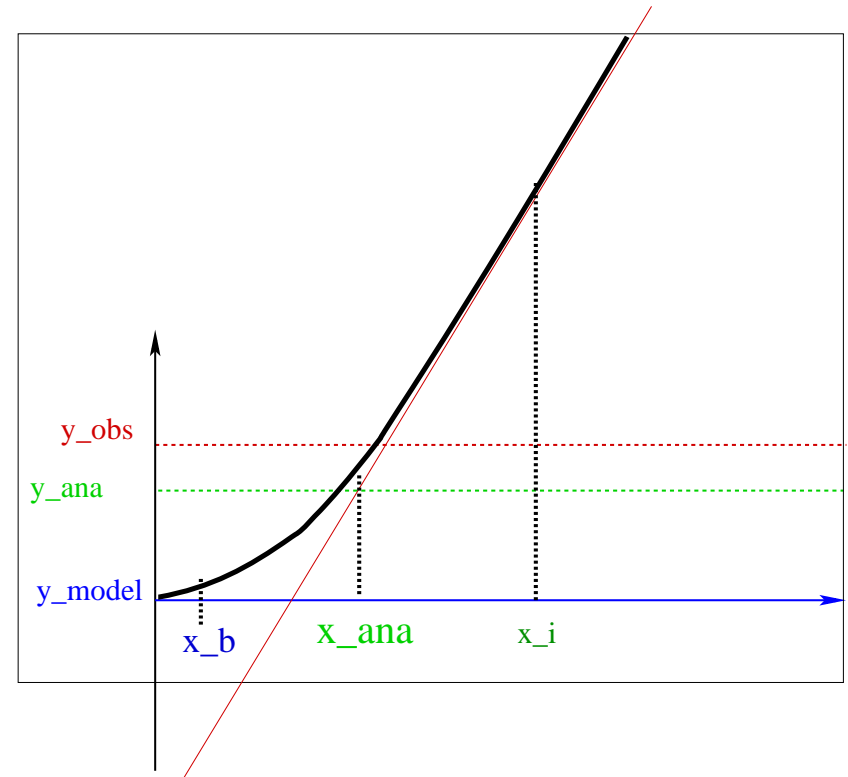
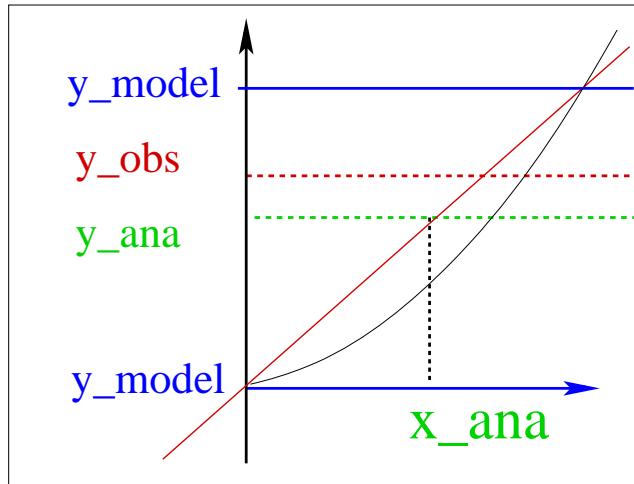
$$RTTOV(\tilde{\mathbf{x}}) \rightarrow y_{mod} \quad \text{radiative transfer model}$$

- 3D Var extrapolates (uses tangent)
- EnKF also interpolates (uses secant)



# Ensemble KF vs Var

- EnKF uses a secant (not a tangent)
- Var can make several outer loops



# Ensemble KF vs Var for convective scales



- Var extrapolates
  - Can a strongly nonlinear object be found by extrapolation?
  
- EnKF has limited ensemble size
  - localized features (like thunderstorms or cloud top height, etc.) will probably not be matched precisely by any ensemble member
  - What do you do when thunderstorm is only approximately in the right position? Or cloud top height is only approximate?
  - Does a linear combination of ensemble members with different thunderstorms (at different positions, etc.) give a dynamically consistent thunderstorm?
  
- Strategie: Do not ask for too much:
  - e.g. assimilate **only one moisture variable** (on top of the other variables) to make regions moister or drier depending on observations
    - total water:  $q_t = q_v + q_c$  (Met Office, UK)

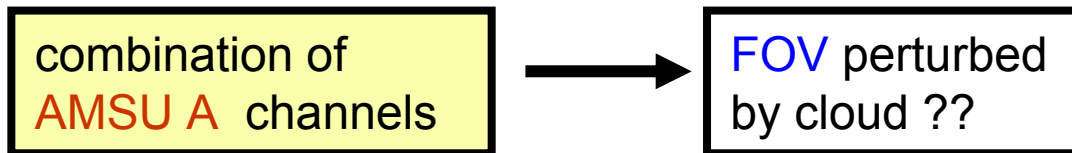




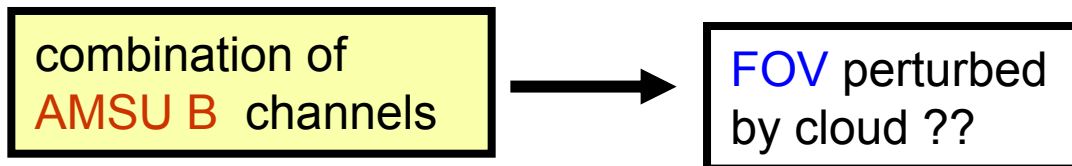
- DWD currently only assimilates radiances which are “cloud free”
- Screening methods use channels of the respective satellite instruments

## ■ MW

- is field of view (FOV) perturbed by **too much cloud water?**
- **AMSU A** (temperature sensitive channels)

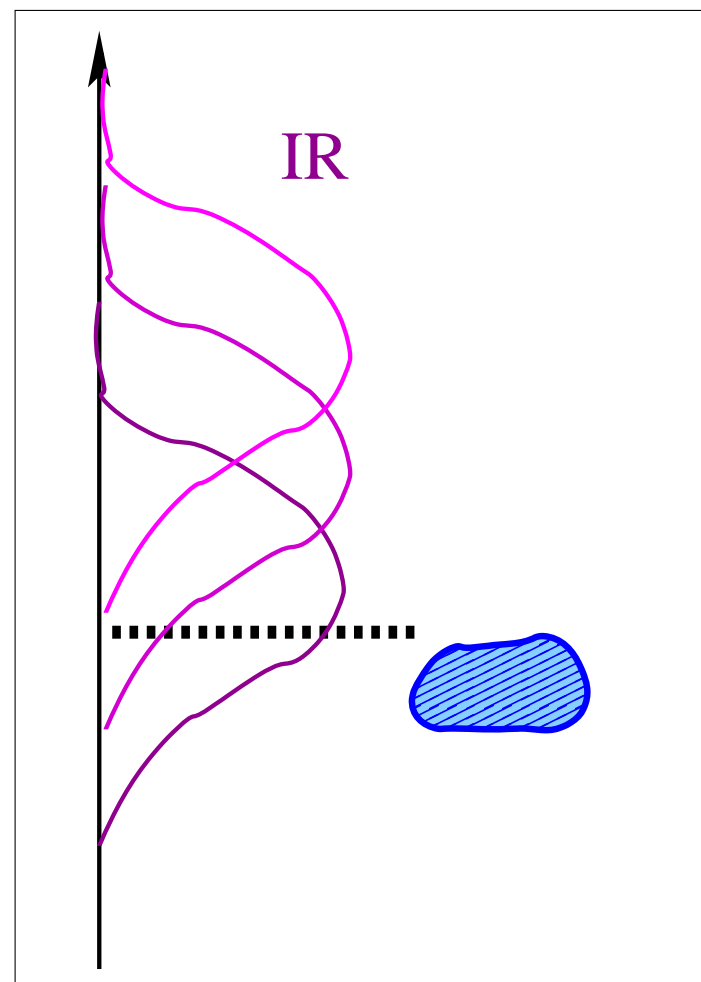


- **AMSU B** (humidity sensitive channels)



- IR
  - HIRS, IASI and AIRS
    - get as close to the cloud as you can
    - use First Guess Departures  
 $FGD = obs - fg$   
(i.e. include model info)  
to identify cloudy fingerprint
  - HIRS (20 Channels, 8 CO<sub>2</sub> channels)
    - screening criterion:

$$FGD_n - FGD_{n-1} < \text{Thresh.}$$



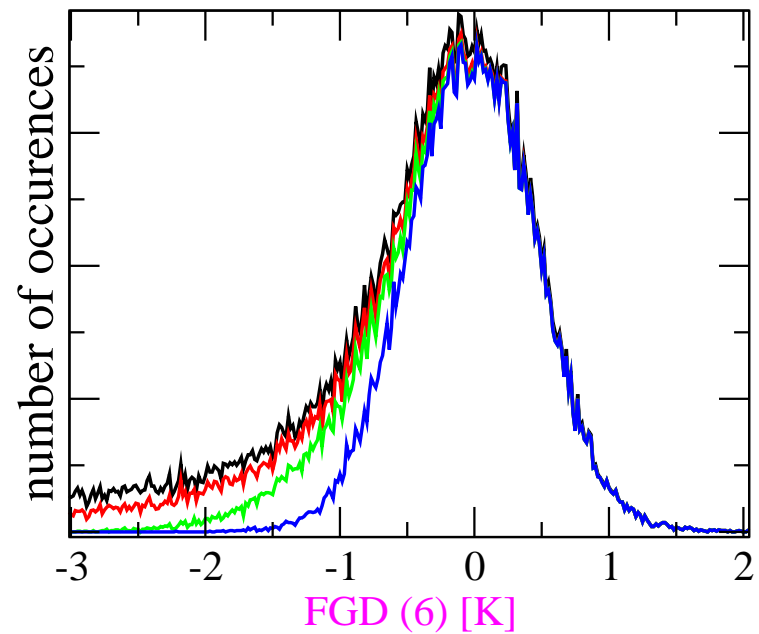
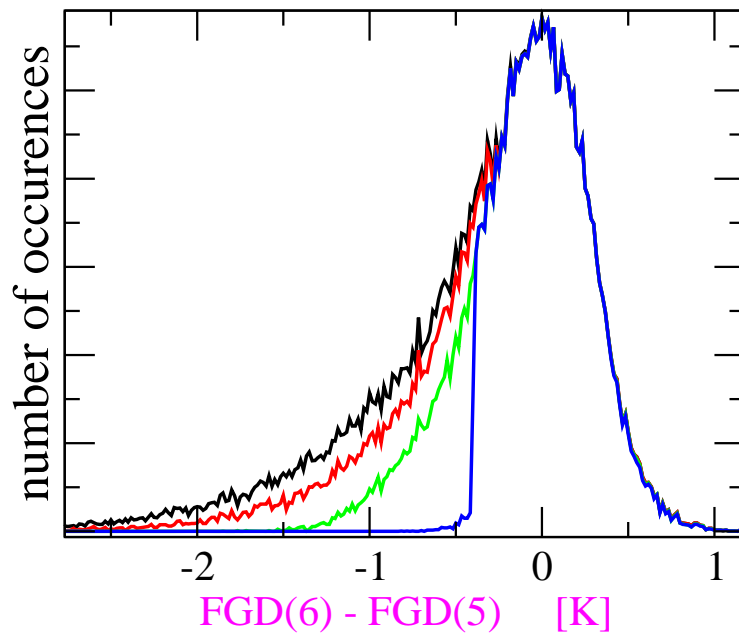
# Example: Cloud screening

**HIRS** (chan. 6, middle/lower troposphere)

Deutscher Wetterdienst  
Wetter und Klima aus einer Hand

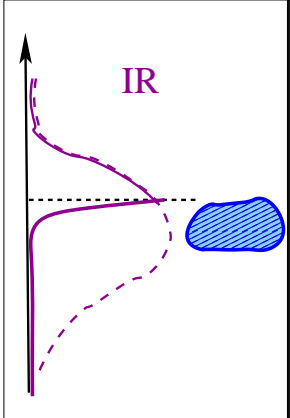
$$FGD_n - FGD_{n-1} < \text{Thresh.}$$

- Cloud screening
  - makes PDF more Gaussian
  - induces bias

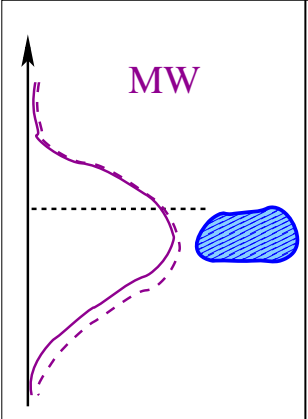


- Satellite radiances are assimilated mainly in the infrared (IR) and microwave (MW) band

- IR
  - strongly nonlinear (opaque)
  - good identification of cloud location
  - more than 80% of channels are affected by cloud
  - cloud impact on IR sounders is subtracted from RT computations.



- MW
  - multiple scattering important
  - sees only thick clouds and rain
  - less than 20% of channels are affected by cloud
  - cloud information from MW imagers is assimilated



- Some work in the “near IR” and visible regime is carried out by the Ertel Center for DA in Munich

# Assimilation of cloud affected satellite radiances

## What has been done?



What has been done?

- MW imagers,
  - ECMWF
  - all sky approach
  - long development route.
    - 2005-2009 only:
      - 1D+4D Var
      - TCWV as pseudo-observation
  - bias correction with “symmetric” cloud variable as predictor
  - screening out *low-skill situations*
    - cold air outbreaks
    - intense tropical convection

$$H(\mathbf{x}) \rightarrow y_{mod}$$

$$H_1(\mathbf{x}) \rightarrow \tilde{\mathbf{x}} \quad \text{physics operator}$$

$$RTTOV(\tilde{\mathbf{x}}) \rightarrow y_{mod} \quad \text{radiative transfer model}$$

$y_{mod}$  : model observations

$\mathbf{x}$  : standard model variables  
(changed by assimilation)

$\tilde{\mathbf{x}}$  : standard model variables

+ cloud variables :  $C_{fr}, P_{cldtop}$



# Assimilation of cloud affected satellite radiances

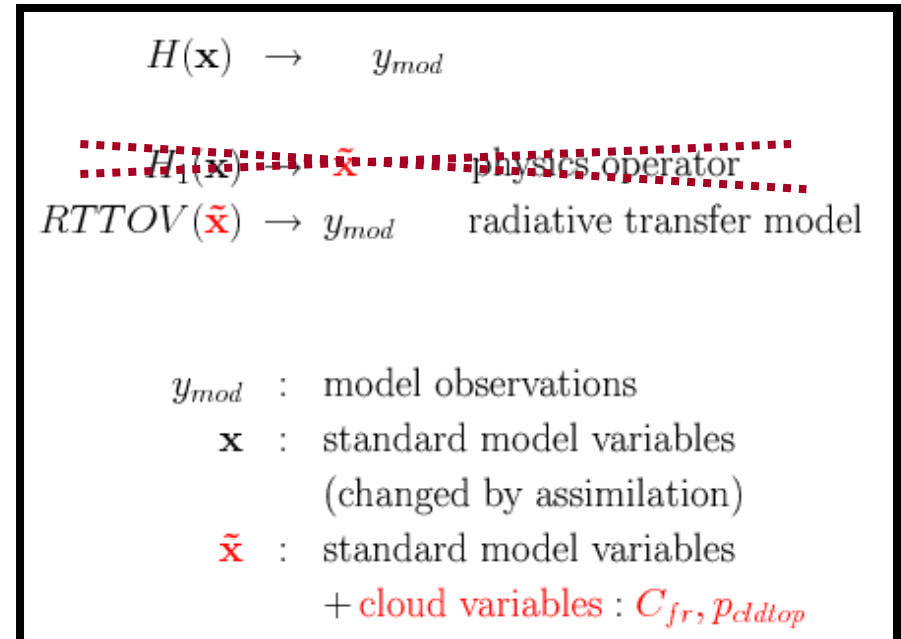
## What has been done?



What has been done?

- IR sounders, HIRS, AIRS, IASI
  - ECMWF
  - only fully overcast situations
  - only RT operator
    - cloud variables:

- first guess estimated from independent observations (model first guess not good enough)
- optimized through additional term to the cost function
- not used for updating model state



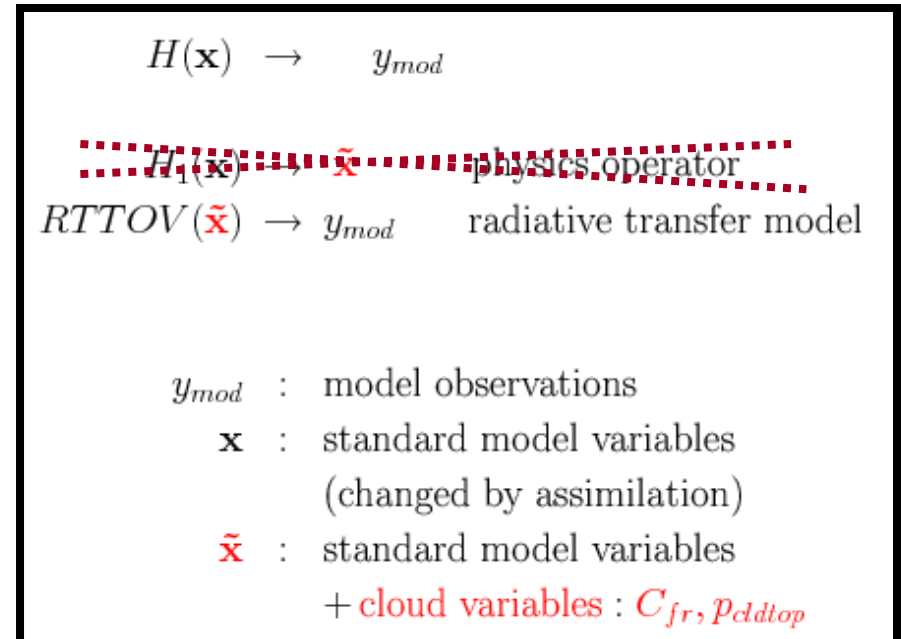
# Assimilation of cloud affected satellite radiances

## What has been done?



What has been done?

- IR sounders, HIRS, AIRS, IASI
  - Met Office, UK
  - only radiances affected less than 10%
  - only RT operator
    - cloud variables:
      - first guess estimated from independent observations (model first guess not good enough)
      - optimized through 1D Var step
      - not used for updating model state



# Assimilation of cloud affected satellite radiances

## What has been done?



What has been done?

- IR sounders, AIRS

- Meteo France

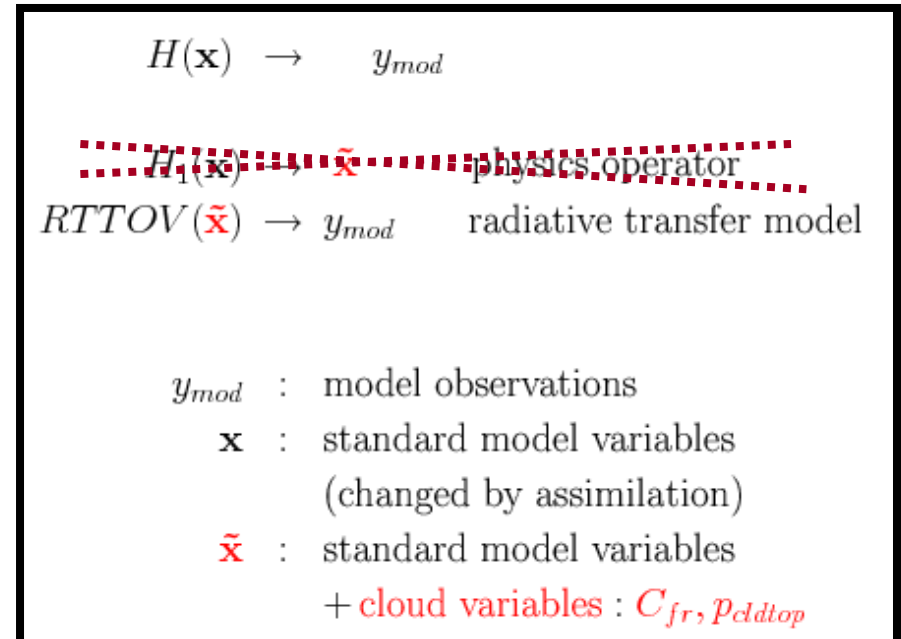
- only

- Stratospheric and upper-tropospheric radiances
    - lower-tropospheric clouds

- only RT operator

- cloud variables:

- first guess estimated from independent observations (model first guess not good enough)
      - “CO2 slicing method” (popular retrieval method – not explained in this lecture)
      - not used for updating model state





# Assimilation of cloud retrievals

## What has been done?

- Met Office, limited area model
  - convert cloud fraction (0%-100%) into total relative humidity
  - use filter to switch off assimilation if
    - $C.\text{fract.}(\text{obs})=C.\text{fract.}(\text{model})=0$
    - or  $C.\text{fract.}(\text{obs})=C.\text{fract.}(\text{model})=1$

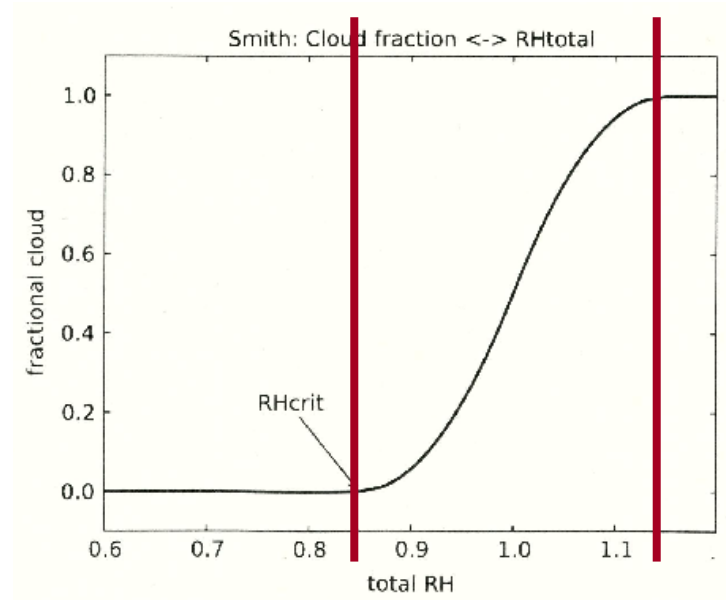


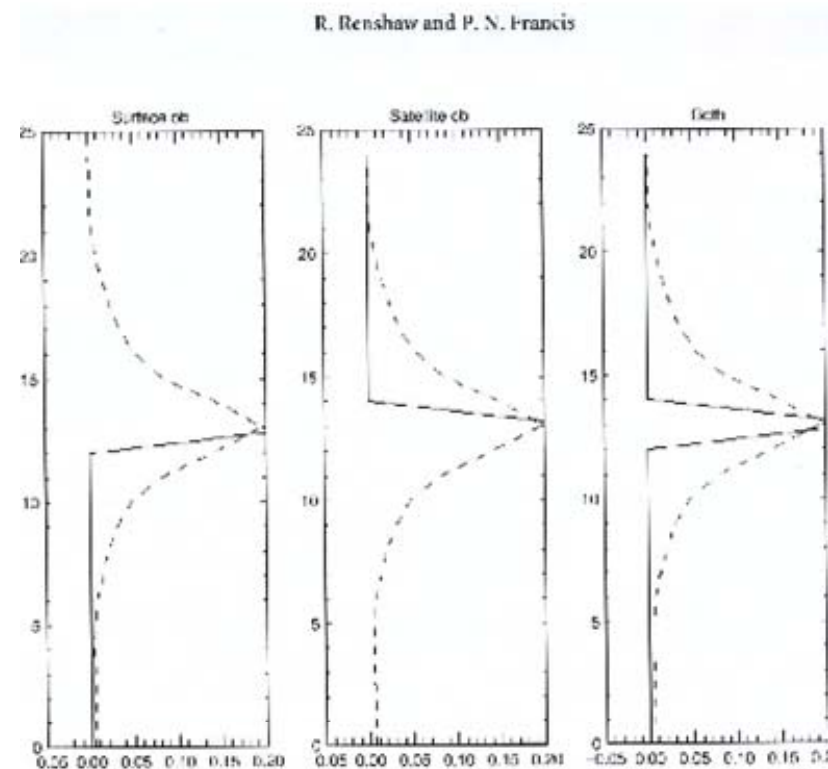
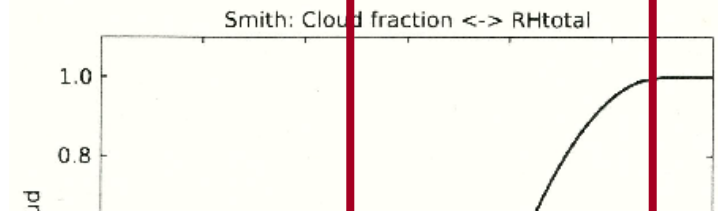
Figure 1. Relationship between total relative humidity and cloud fraction defined by Smith (1990), with  $RH_{crit} = 0.85$ .

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  - but:
    - use **cloud-free information** above and below clouds (if available)



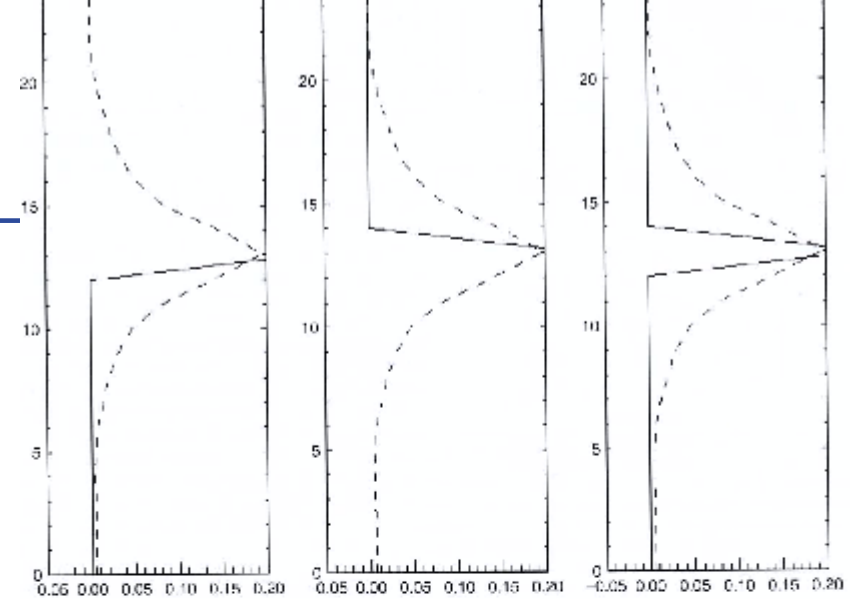
For the case of a stratiform layer, in response to your ask, a diagram of observed humidity (solid line) for three columns represents cloud base (no data above the cloud), a satellite-derived cloud top (no data below), and both together.



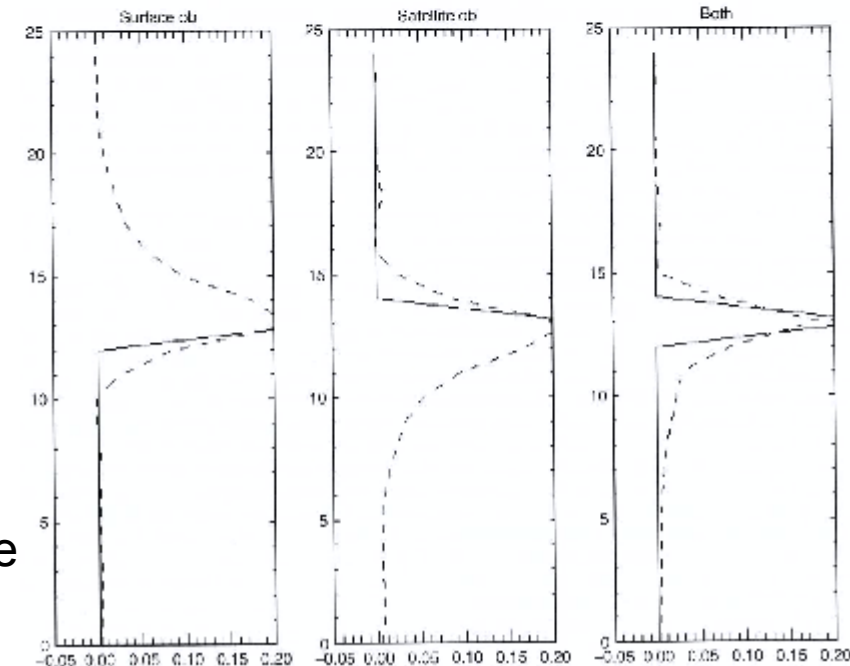
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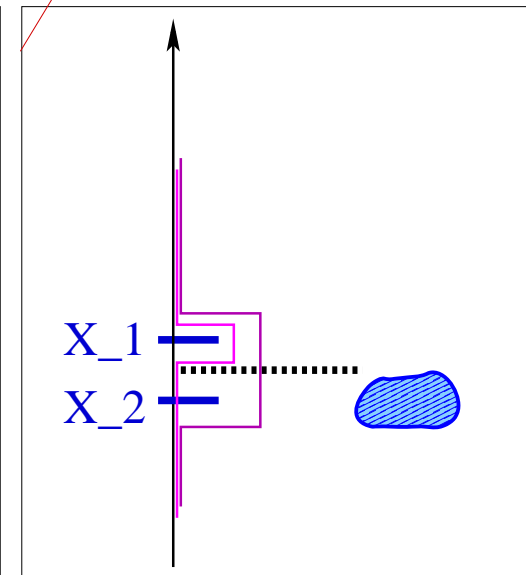
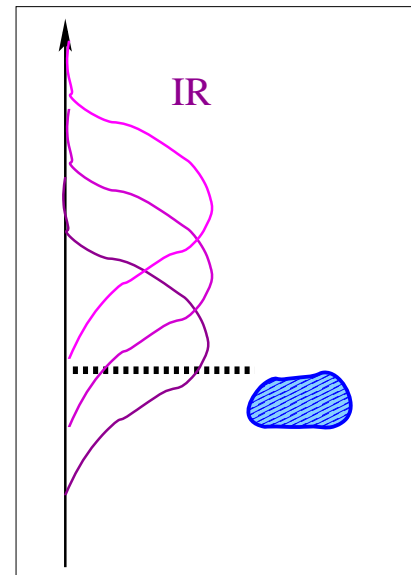
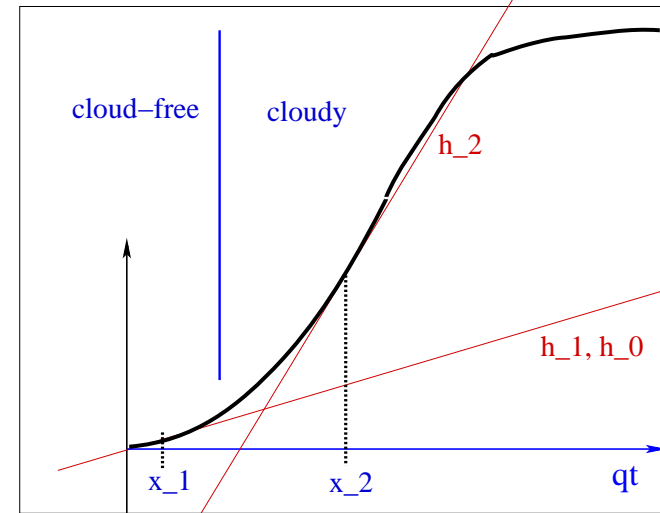
Vertical profiles (dashed line) in response to synthetic columns of observed humidities (solid line) for three columns representing a cloud base (no data above the cloud), a satellite-derived cloud top (no data below), and both together.



# A simplified model problem

$$\mathcal{H}(x) = \mathcal{H}(\hat{x}) + \mathbf{H} (x - \hat{x}) ; \quad \mathbf{H} = \begin{pmatrix} h_1 & 0 \\ h_0 & h_2 \end{pmatrix}$$

$$\mathbf{R} = \begin{pmatrix} r_1 & 0 \\ 0 & r_2 \end{pmatrix}, \quad \mathbf{B} = \begin{pmatrix} b_1 & b_0 \\ b_0 & b_2 \end{pmatrix}$$



# A simplified model problem

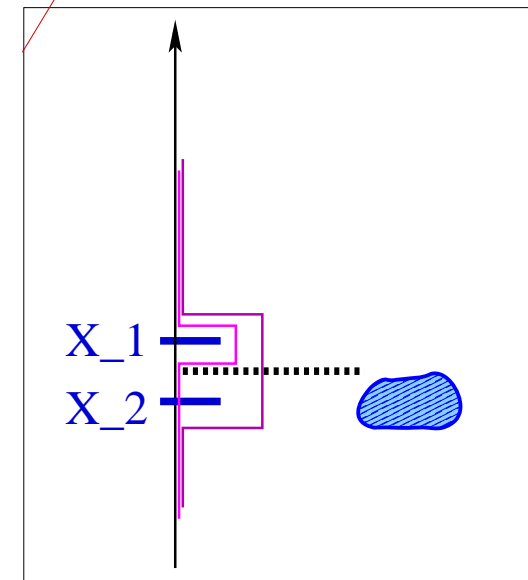
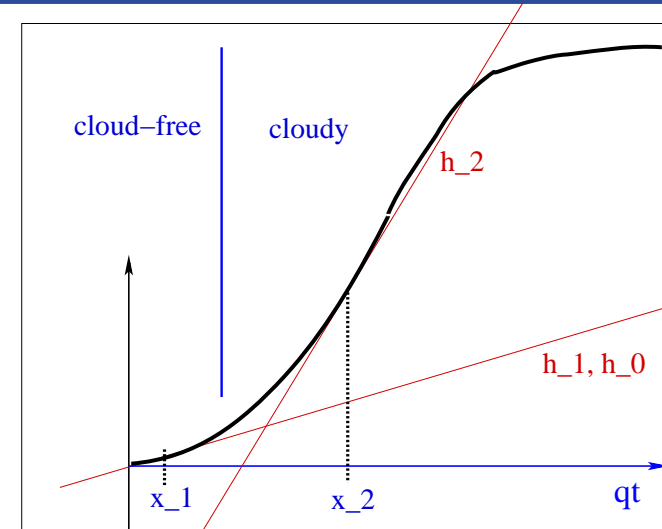
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$$\begin{pmatrix} \Delta_a y_1 \\ \Delta_a y_2 \end{pmatrix} \equiv \mathbf{H} (x - x_b) = \begin{pmatrix} \Lambda_1^{-1} & 0 \\ 0 & \Lambda_2^{-1} \end{pmatrix} \begin{pmatrix} 1 & \gamma_{2 \rightarrow 1} \\ \gamma_{1 \rightarrow 2} & 1 \end{pmatrix} \begin{pmatrix} \Delta y_1 \\ \Delta y_2 \end{pmatrix}$$

$$(x - x_b) = \mathbf{K} \{y - \mathcal{H}(x_i) - H(x_i - x_b)\}$$

$$\begin{pmatrix} \Delta y_1 \\ \Delta y_2 \end{pmatrix} = y - \mathcal{H}(x_i) - H(x_i - x_b)$$



# A simplified model problem

$$\mathcal{H}(x) = \mathcal{H}(\hat{x}) + \mathbf{H}(x - \hat{x}) ; \quad \mathbf{H} = \begin{pmatrix} h_1 & 0 \\ h_0 & h_2 \end{pmatrix}$$

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$$R_1 = \frac{r_1}{b_1 h_1^2} \quad R_2 = \frac{r_2}{b_2 h_2^2}$$

$$\tilde{h}_0 = \frac{h_0}{h_2} \sqrt{\frac{b_1}{b_2}}$$

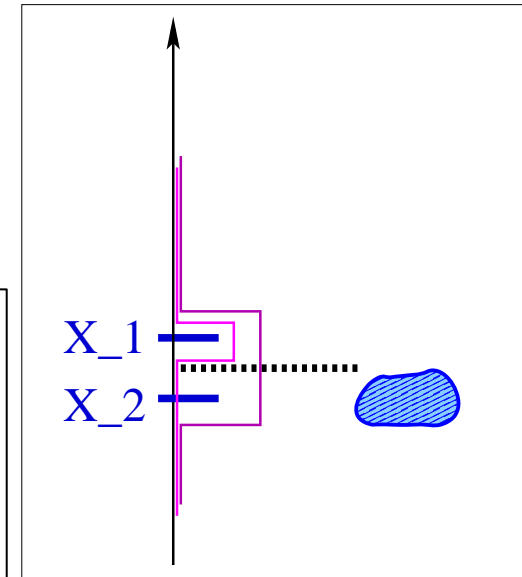
$$\tilde{b}_0 = \frac{b_0}{\sqrt{b_1 b_2}}$$

$$\Lambda_1 = 1 + R_1 \left\{ 1 + \frac{(\tilde{h}_0 + \tilde{b}_0)^2}{[1 - \tilde{b}_0^2] + R_2} \right\}$$

$$\Lambda_2 = 1 + R_2 \frac{\left\{ 1 + \frac{(\tilde{h}_0 + \tilde{b}_0)^2}{[1 - \tilde{b}_0^2] + (1 + \tilde{h}_0^2 + 2\tilde{b}_0\tilde{h}_0) R_1} \right\}}{(1 + \tilde{h}_0^2 + 2\tilde{b}_0\tilde{h}_0)}$$

$$\gamma_{2 \rightarrow 1} = \frac{(\tilde{h}_0 + \tilde{b}_0)}{[1 - \tilde{b}_0^2] + R_2} R_1 \frac{h_1 \sqrt{b_1}}{h_2 \sqrt{b_2}}$$

$$\gamma_{1 \rightarrow 2} = \frac{(\tilde{h}_0 + \tilde{b}_0)}{[1 - \tilde{b}_0^2] + (\tilde{h}_0^2 + 2\tilde{b}_0\tilde{h}_0 + 1) R_1} R_2 \frac{h_2 \sqrt{b_2}}{h_1 \sqrt{b_1}}$$



# A simplified model problem

$$\mathcal{H}(x) = \mathcal{H}(\hat{x}) + \mathbf{H}(x - \hat{x}); \quad \mathbf{H} = \begin{pmatrix} h_1 & 0 \\ h_0 & h_2 \end{pmatrix}$$

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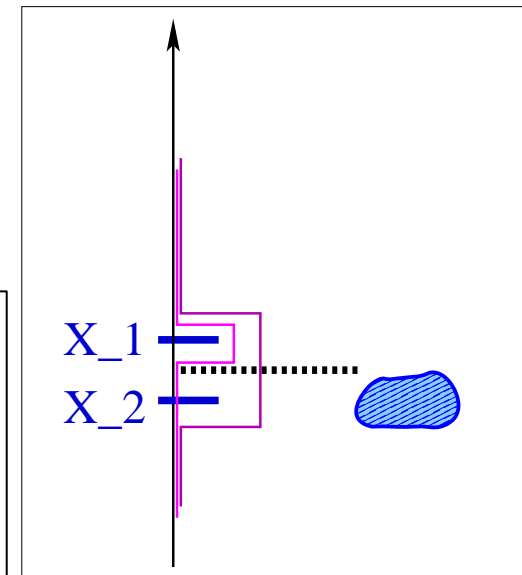
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$$\gamma_{2 \rightarrow 1} = \frac{(\tilde{h}_0 + \tilde{b}_0)}{[1 - \tilde{b}_0^2] + R_2} R_1 \frac{h_1 \sqrt{b_1}}{h_2 \sqrt{b_2}}$$

$$\gamma_{1 \rightarrow 2} = \frac{(\tilde{h}_0 + \tilde{b}_0)}{[1 - \tilde{b}_0^2] + (\tilde{h}_0^2 + 2\tilde{b}_0\tilde{h}_0 + 1) R_1} R_2 \frac{h_2 \sqrt{b_2}}{h_1 \sqrt{b_1}}$$



# Assimilation in cloudy air

## Topics (check list)



- Impact on the model state
  - Which variables are we trying to alter?
    - (only T? Also  $q_v$ ? Even  $q_c$ ?)
- Scene selection
  - Which type of cloud affected radiance do we want to process (assimilate)?
- First guess
  - Is the model first guess good enough for cloud parameters?
- How are errors affected by the presence of clouds?:
  - Observation errors?
  - Bias correction?
    - How to deal with error characteristics / biases in cloudy areas?
- Forward operators
  - physics operators / RT model
  - nonlinear / linear / adjoint
- Additional quality control
  - screening (excluding) situations where method has problems (e.g. first guess too bad)







Questions? Remarks?

